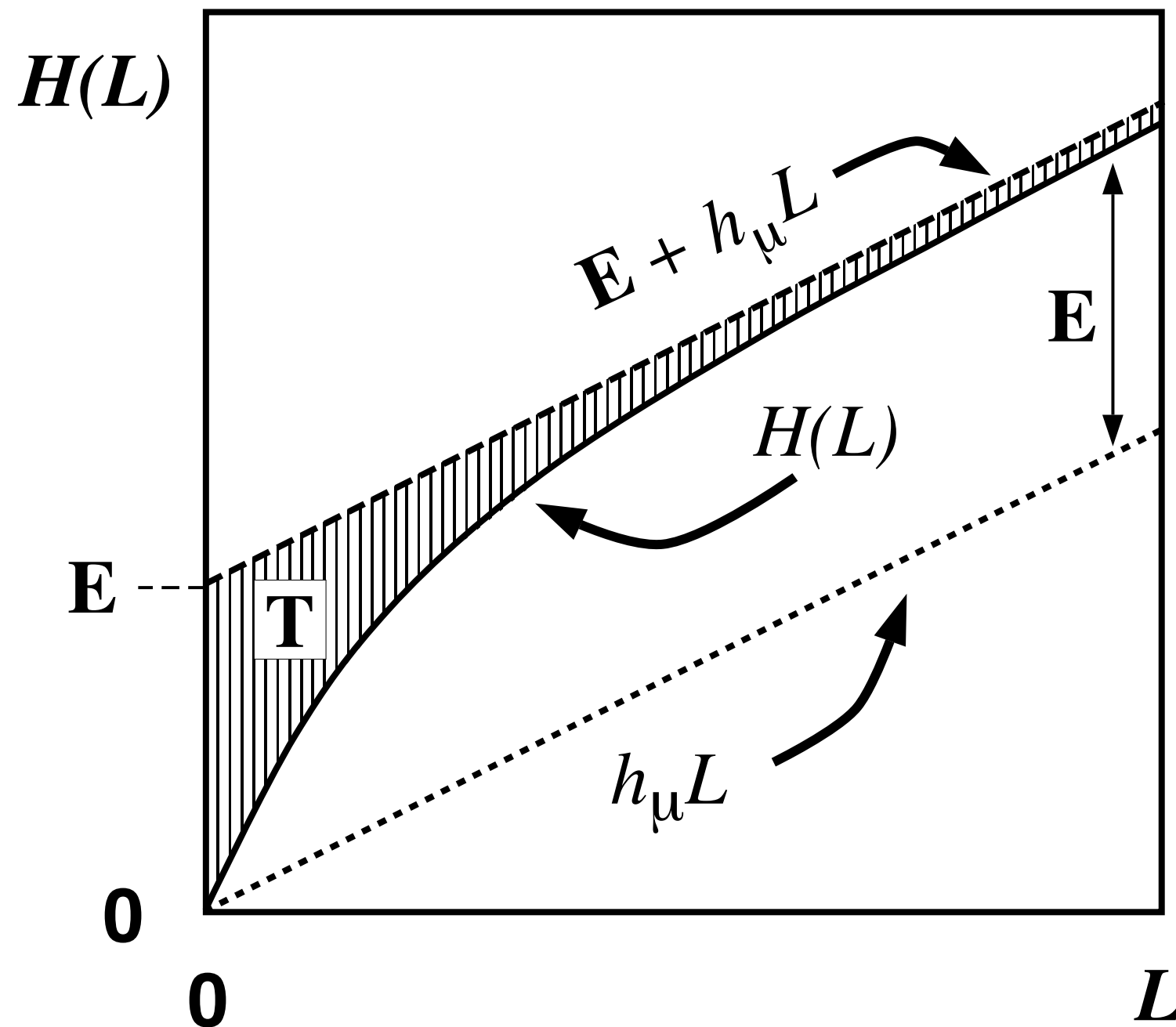


# Intrinsic Computation

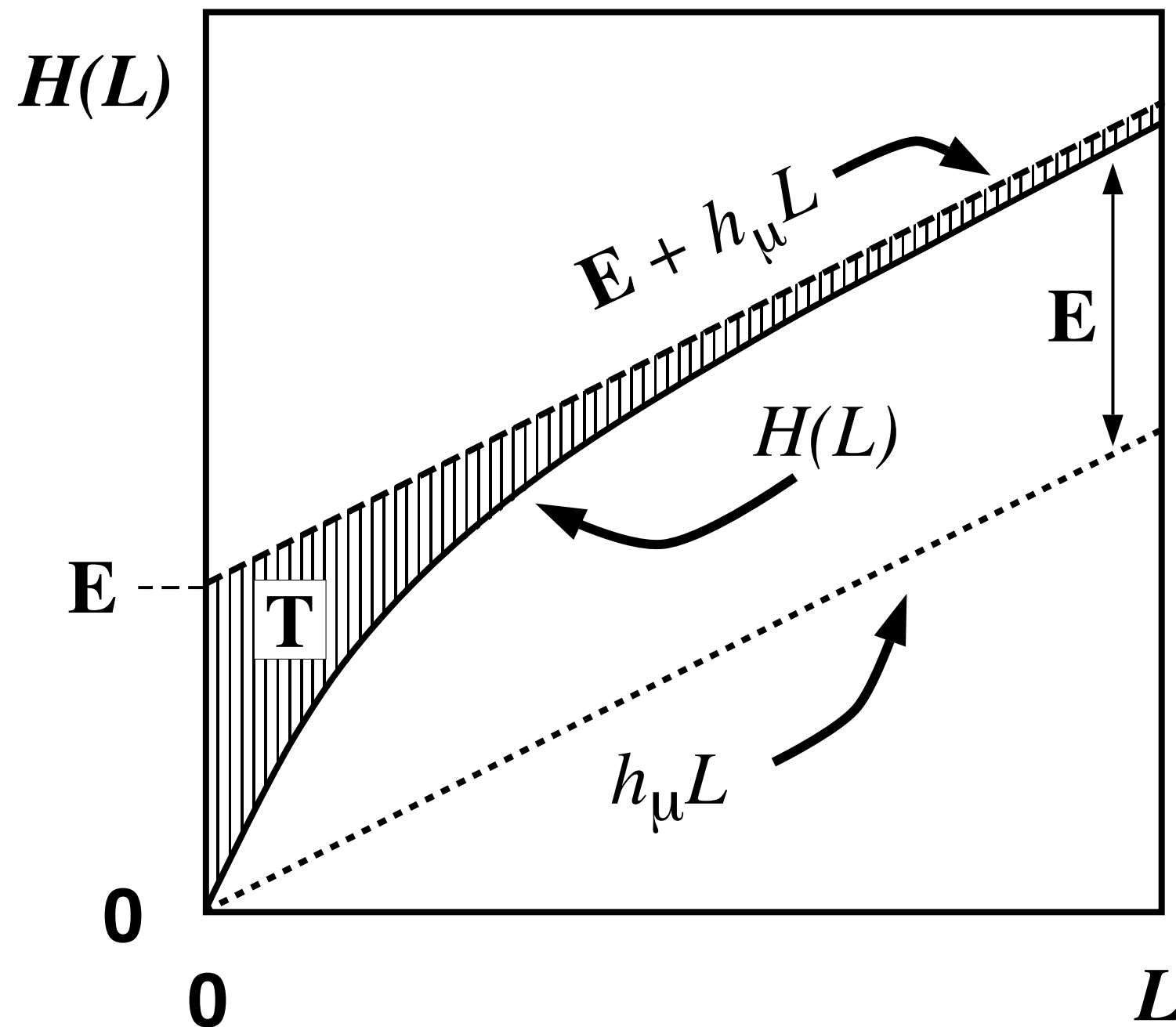
Jim Crutchfield & Nix Barnett  
Complexity Sciences Center  
Physics Department  
University of California at Davis

Complex Systems Summer School  
Santa Fe Institute  
Santa Fe, NM  
14 June 2013

# Information Roadmap for a Complex Process

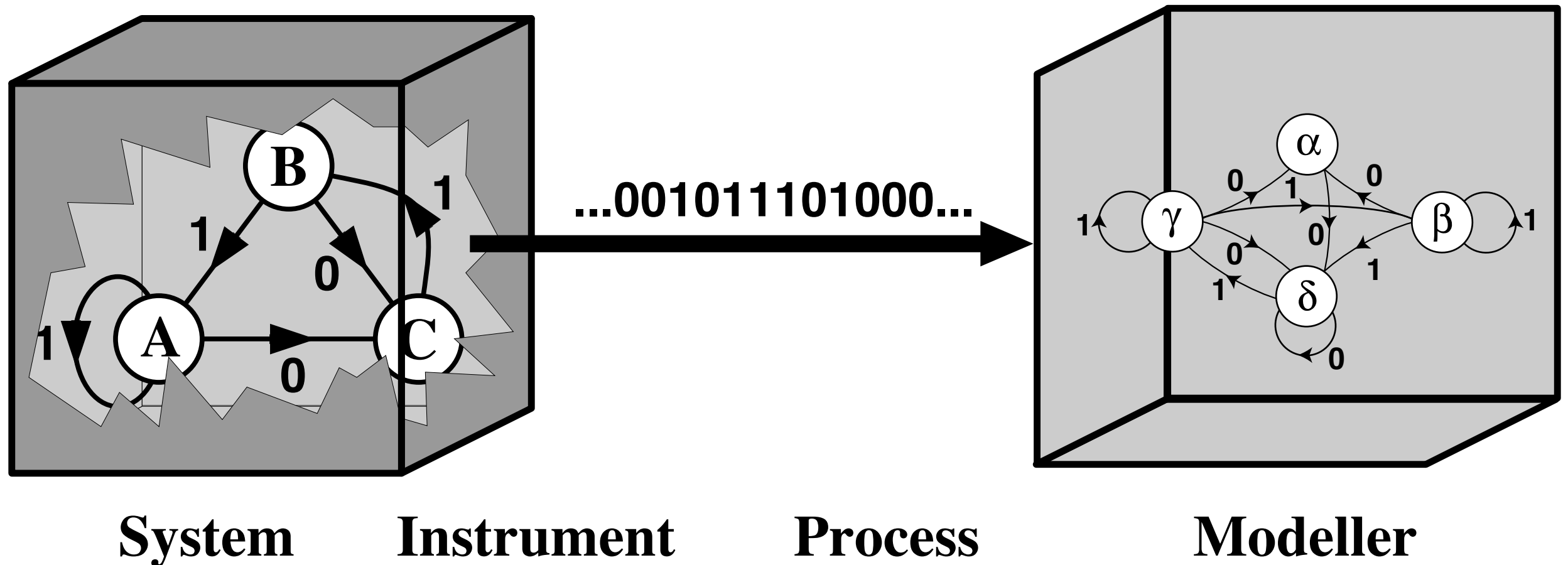


# Information Roadmap for a Complex Process



What's wrong with information theory?

# The Learning Channel:



Central questions:  
What are the states?  
What is the dynamic?

# The Learning Channel ...

## The Prediction Game

### Rules:

1. I give you a data stream (an observed past sequence).
2. You predict its future.
3. You give a model (states & transitions) describing the process.

# The Learning Channel ...

## The Prediction Game ...

Process I:

# The Learning Channel ...

## The Prediction Game ...

### Process I:

Past:      ... 111111111111

# The Learning Channel ...

## The Prediction Game ...

Process I:

Past:     ... 111111111111

Your prediction is?

# The Learning Channel ...

## The Prediction Game ...

Process I:

Past:      ... 111111111111

Your prediction is?

Future:      111111111111 ...

# The Learning Channel ...

## The Prediction Game ...

Process I:

Past:      ... 111111111111

Your prediction is?

Future:      111111111111 ...

Your model (states & dynamic) is?

# The Learning Channel ...

## The Prediction Game ...

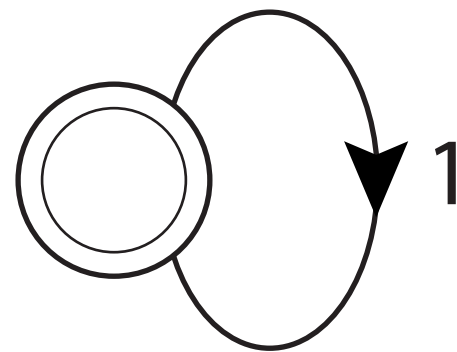
Process I:

Past: ... 111111111111

Your prediction is?

Future: 111111111111...

Your model (states & dynamic) is?



# The Learning Channel ...

## The Prediction Game ...

### Process II:

# The Learning Channel ...

## The Prediction Game ...

### Process II:

**Past:** ... 10110010001101110

# The Learning Channel ...

## The Prediction Game ...

### Process II:

Past: ... 10110010001101110

Your prediction is?

# The Learning Channel ...

## The Prediction Game ...

Process II:

Past: ... 10110010001101110

Your prediction is?

Analysis: All words of length  $L$  occur & equally often

# The Learning Channel ...

## The Prediction Game ...

### Process II:

Past: ... 10110010001101110

Your prediction is?

Analysis: All words of length  $L$  occur & equally often

Future: Well, anything can happen, how about?

# The Learning Channel ...

## The Prediction Game ...

### Process II:

Past: ... 10110010001101110

Your prediction is?

Analysis: All words of length  $L$  occur & equally often

Future: Well, anything can happen, how about?

01010111010001101 ...

# The Learning Channel ...

## The Prediction Game ...

### Process II:

Past: ... 10110010001101110

Your prediction is?

Analysis: All words of length  $L$  occur & equally often

Future: Well, anything can happen, how about?

01010111010001101 ...

Your model is?

# The Learning Channel ...

## The Prediction Game ...

### Process II:

Past: ... 10110010001101110

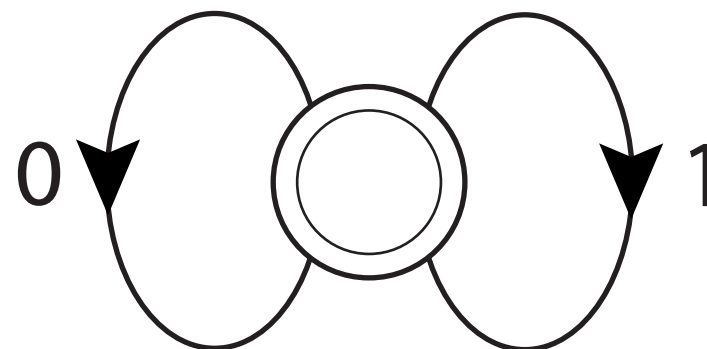
Your prediction is?

Analysis: All words of length  $L$  occur & equally often

Future: Well, anything can happen, how about?

01010111010001101 ...

Your model is?



The Learning Channel ...

The Prediction Game ...

Process III:

# The Learning Channel ...

## The Prediction Game ...

### Process III:

Past: ... 1010101010101010

# The Learning Channel ...

## The Prediction Game ...

### Process III:

Past: ... 1010101010101010

Your prediction is?

# The Learning Channel ...

## The Prediction Game ...

### Process III:

Past: ... 1010101010101010

Your prediction is?

Future: 101010101010101...

# The Learning Channel ...

## The Prediction Game ...

### Process III:

Past: ... 1010101010101010

Your prediction is?

Future: 101010101010101 ...

Your model is?

# The Learning Channel ...

## The Prediction Game ...

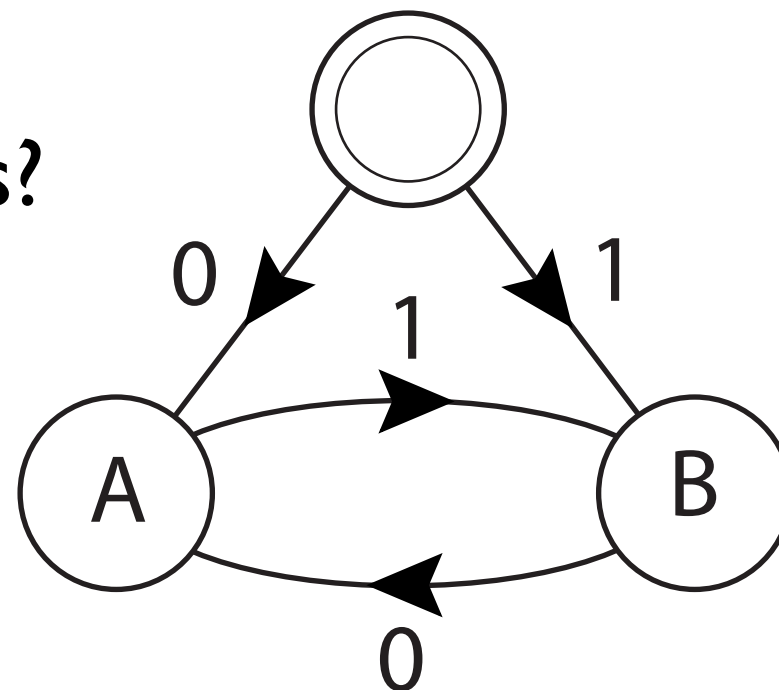
### Process III:

Past: ... 10101010101010

Your prediction is?

Future: 1010101010101...

Your model is?



# The Learning Channel ...

Theory? Algorithms?

Computational Mechanics

# The Learning Channel ...

Goal:

Predict the future  $\vec{S}$   
using information from the past  $\overleftarrow{S}$

But what “information” to use?

We want to find the effective “states”  
and the dynamic (state-to-state mapping)

How to define “states”, if they are hidden?

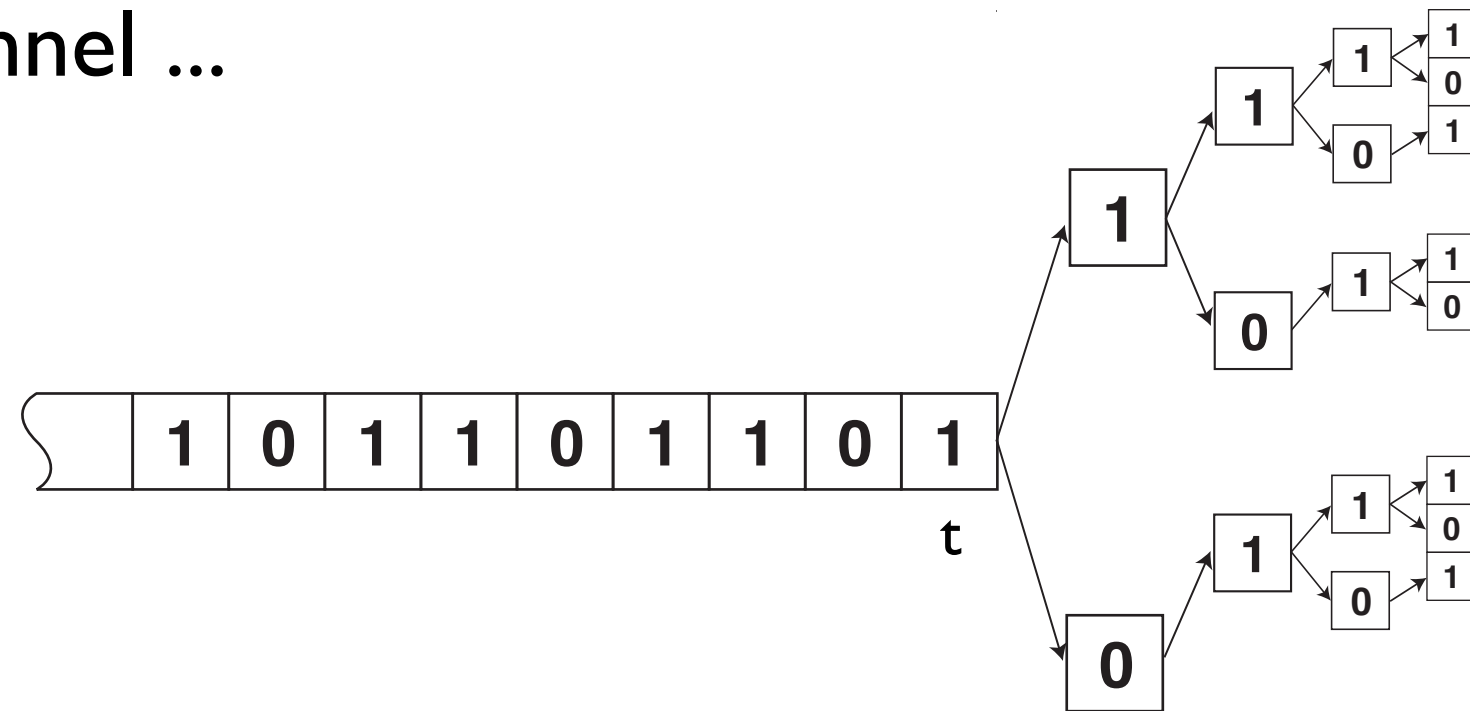
All we have are sequences of observations  
Over some measurement alphabet  $\mathcal{A}$   
These symbols only indirectly reflect the hidden states

# The Learning Channel ...

## Effective States:

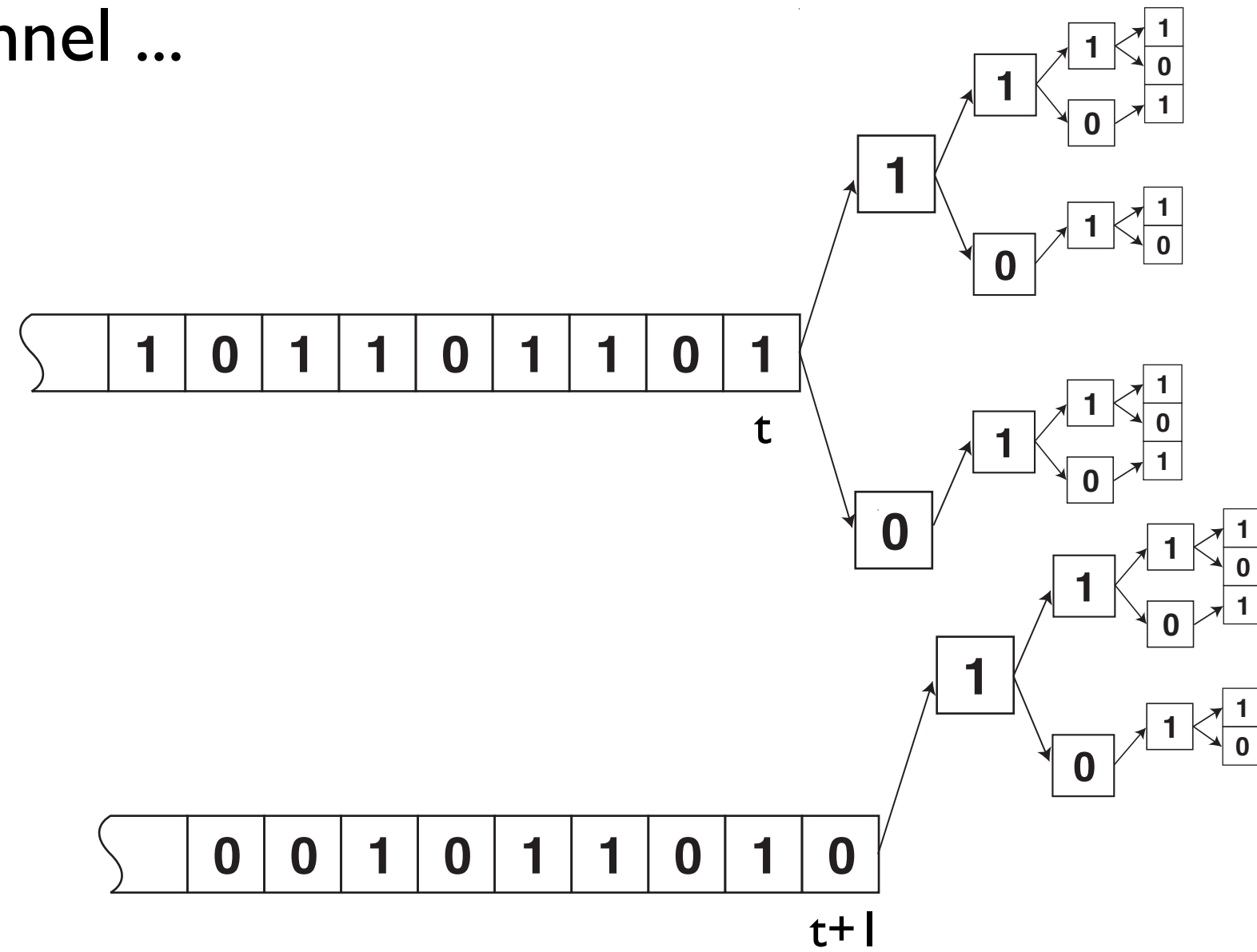
# The Learning Channel ...

Effective States:



# The Learning Channel ...

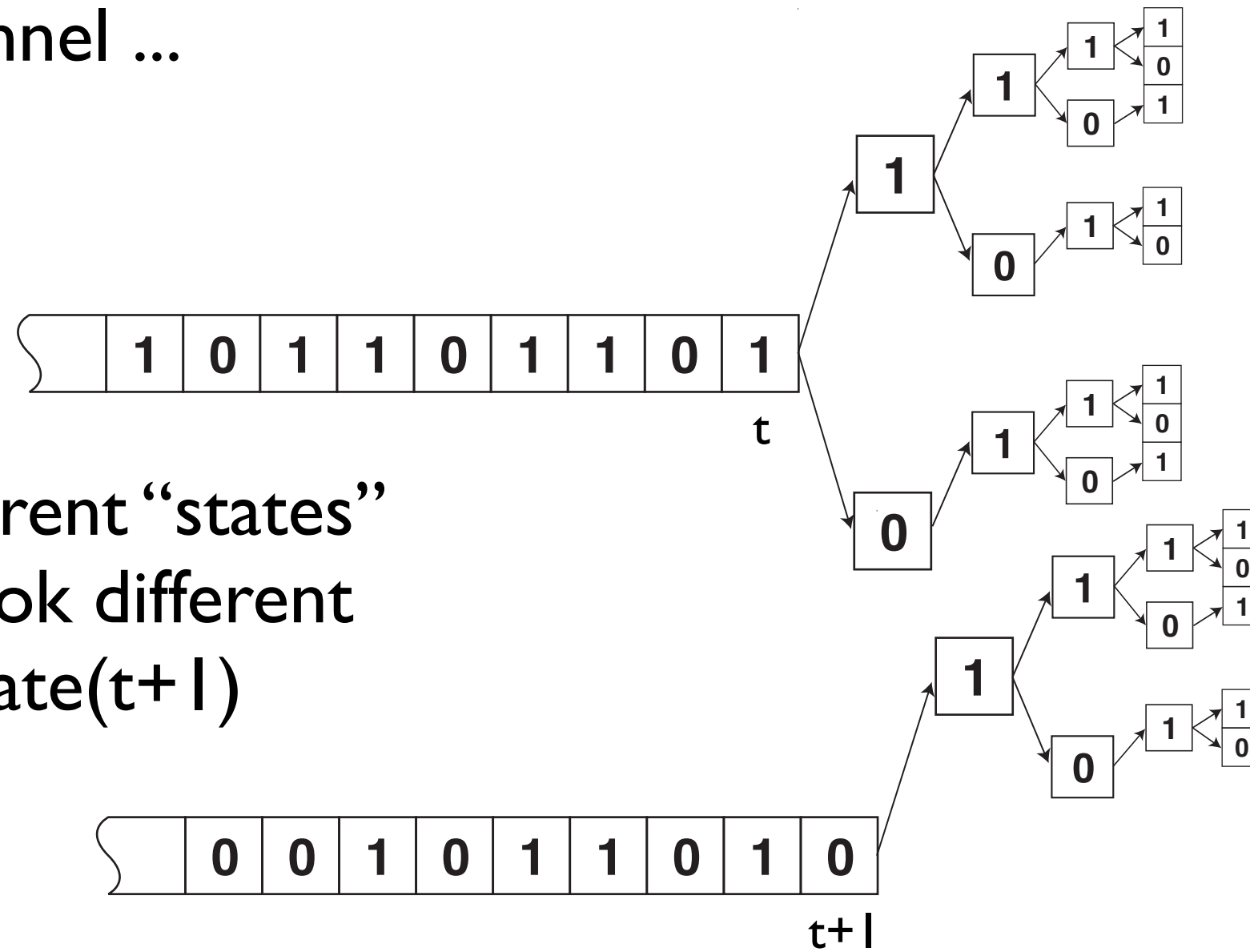
## Effective States:



# The Learning Channel ...

Effective States:

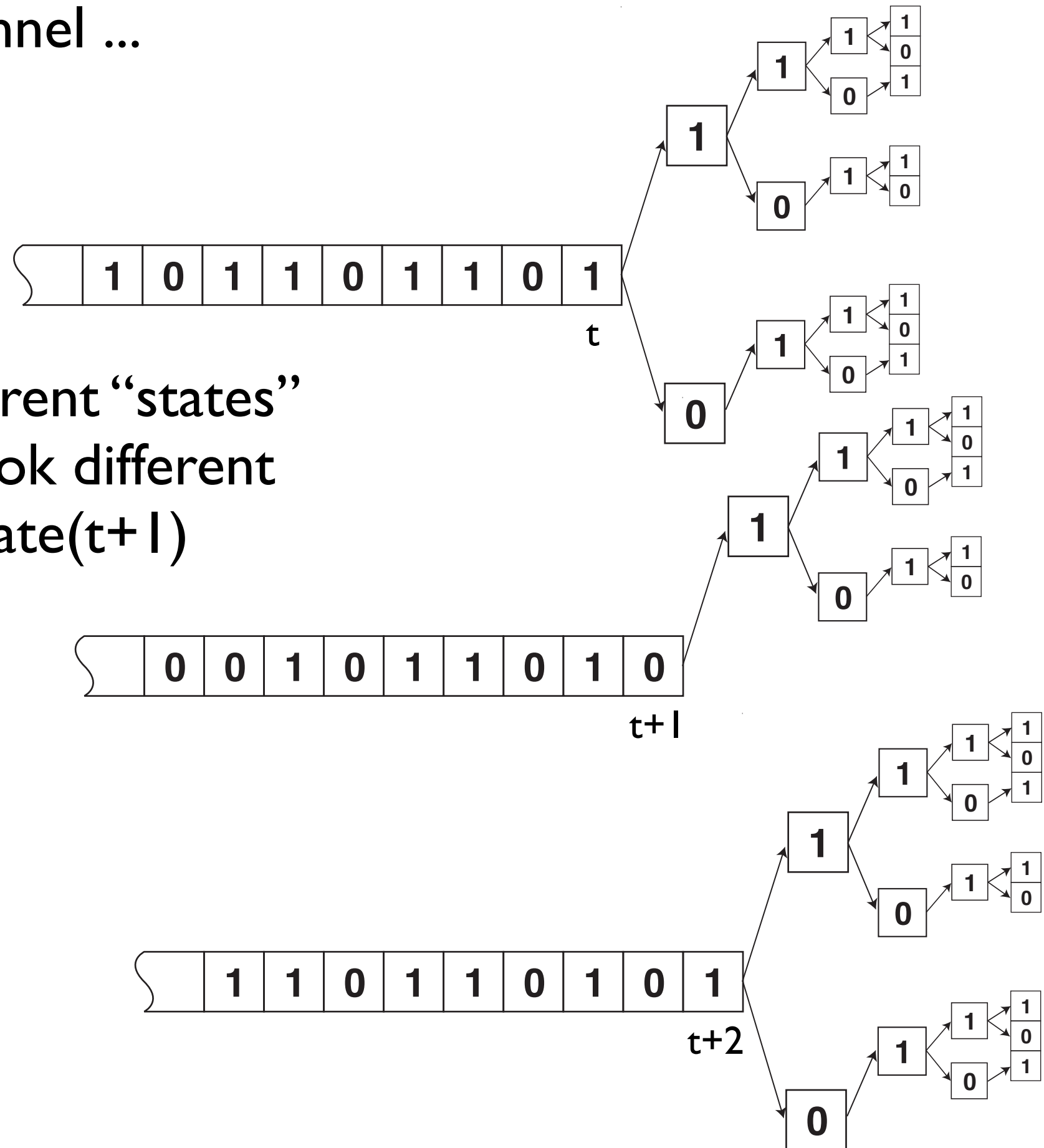
Process is in different “states”  
when futures look different  
 $\text{State}(t) \approx \text{State}(t+1)$



# The Learning Channel ...

Effective States:

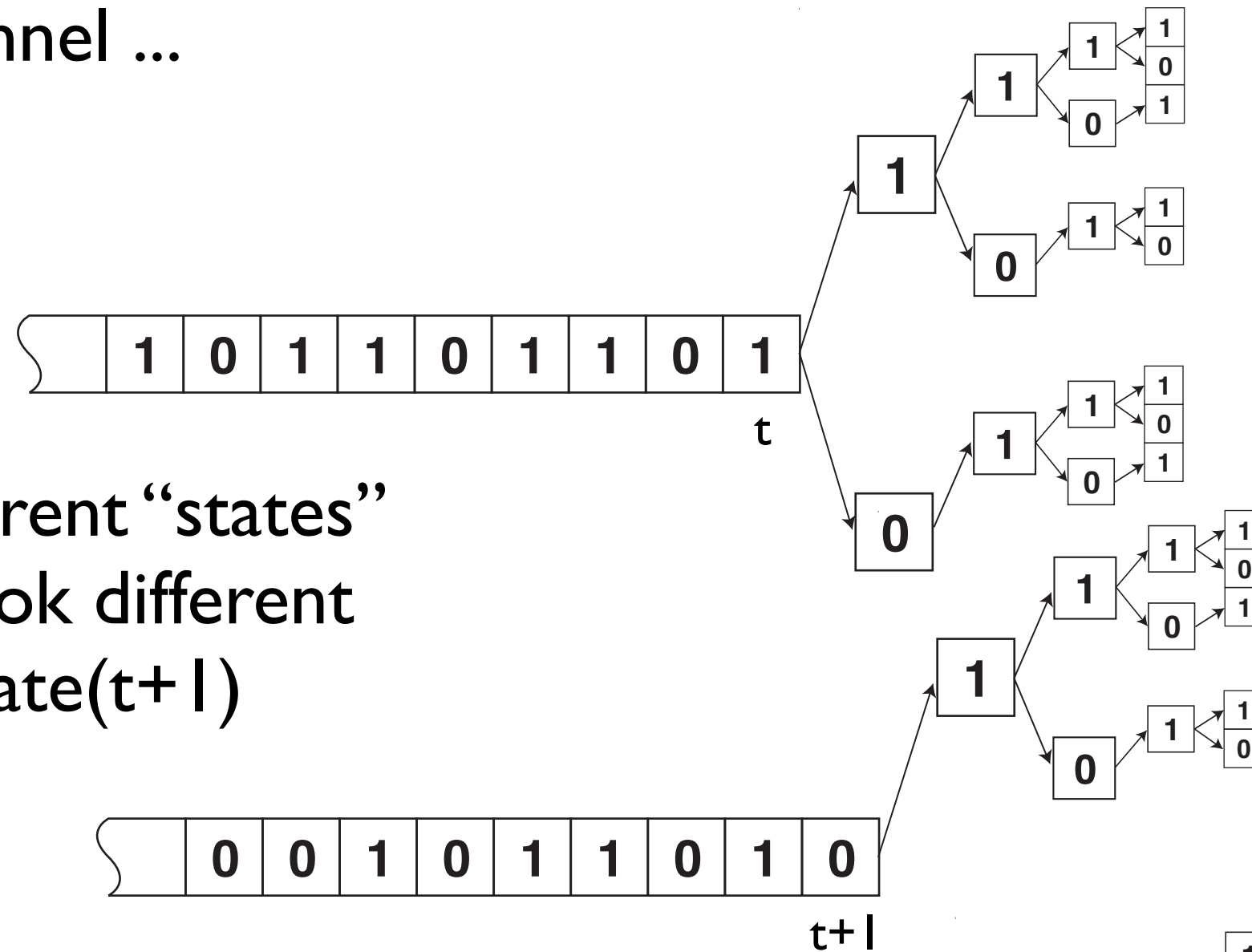
Process is in different “states”  
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 $\text{State}(t) \approx \text{State}(t+1)$



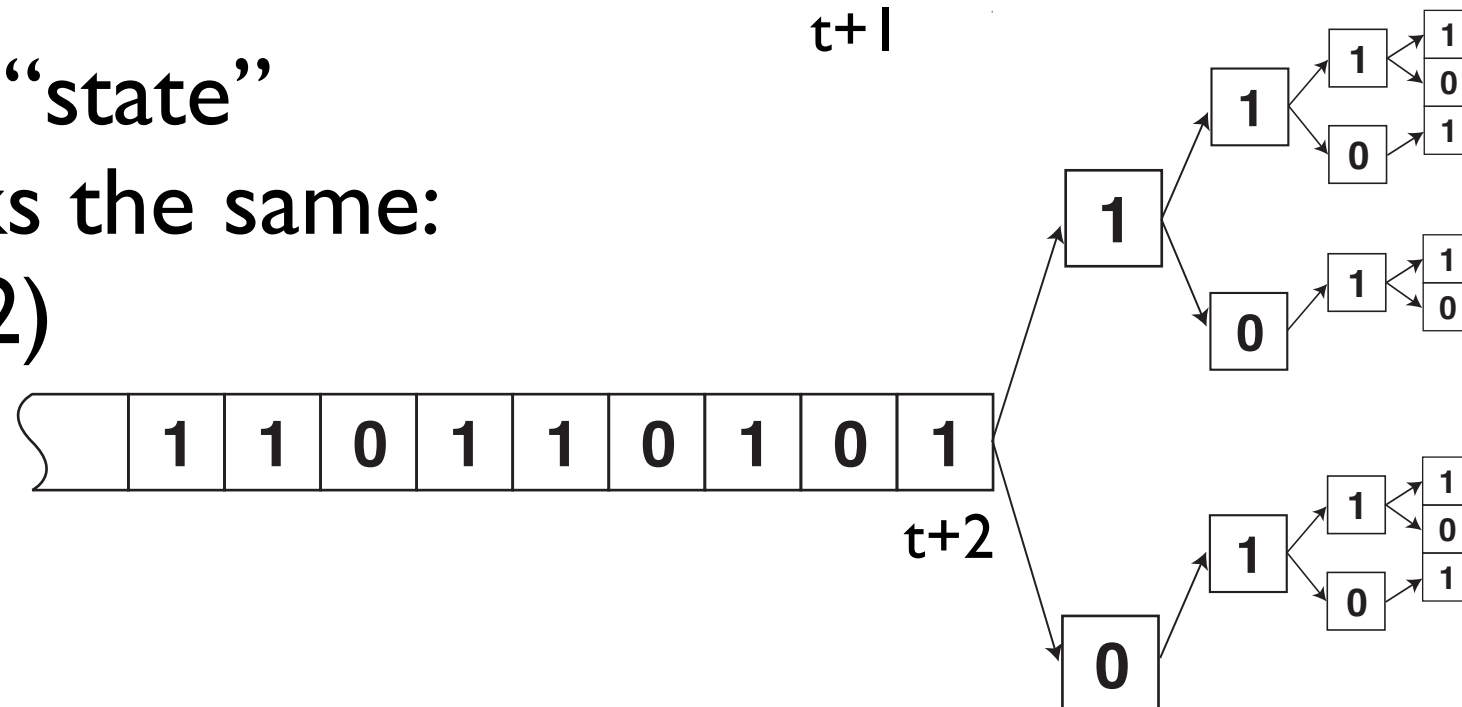
# The Learning Channel ...

Effective States:

Process is in different “states”  
when futures look different  
 $\text{State}(t) \not\sim \text{State}(t+1)$



Process is in the same “state”  
when the future looks the same:  
 $\text{State}(t) \sim \text{State}(t+2)$



# The Learning Channel ...

Effective for what?

What's a prediction?

A mapping from the past to the future.

Process  $\Pr(\overleftrightarrow{S}) : \overleftrightarrow{S} = \overleftarrow{S} \overrightarrow{S}$

Future:  $\overrightarrow{S}^L$

Particular past:  $\overleftarrow{s}$

**Future Morph:**  $\Pr(\overrightarrow{S}^L \mid \overleftarrow{s})$  (the most general mapping)

Refined goal:

Predict as much about the future  $\overrightarrow{S}$ ,  
using as little of the past  $\overleftarrow{S}$  as possible.

# The Learning Channel ...

How Effective are the Effective States?

Candidate “rival” model  $R$

(Think some HMM)

A given mapping from pasts to future morphs

How to measure goodness?

Effective Prediction Error:

$$H[\vec{S}^L | R]$$

Uncertainty about future given effective states

Effective Prediction Error Rate:

$$h_{\mu}(R) = \lim_{L \rightarrow \infty} \frac{H[\vec{S}^L | R]}{L}$$

Entropy rate given effective states

# The Learning Channel ...

## How Effective are the Effective States?

### Statistical Complexity of the Effective States:

$$C_{\mu}(R) = H[R] = H(\text{Pr}(R))$$

#### Interpretations:

Uncertainty in state.

Shannon information one gains when told effective state.

Model “size”  $\propto \log_2(\text{number of states})$

Historical memory used by  $R$ .

# The Learning Channel ...

## Goals Restated:

### Question 1:

Can we find effective states that give good predictions?

$$H[\vec{S}^{\rightarrow L} | R] = H[\vec{S}^{\rightarrow L} | \vec{S}^{\leftarrow}]$$

or

$$h_{\mu}(R) = h_{\mu}$$

### Question 2:

Can we find the smallest such set?

$$\min C_{\mu}(R)$$

# The Learning Channel ...

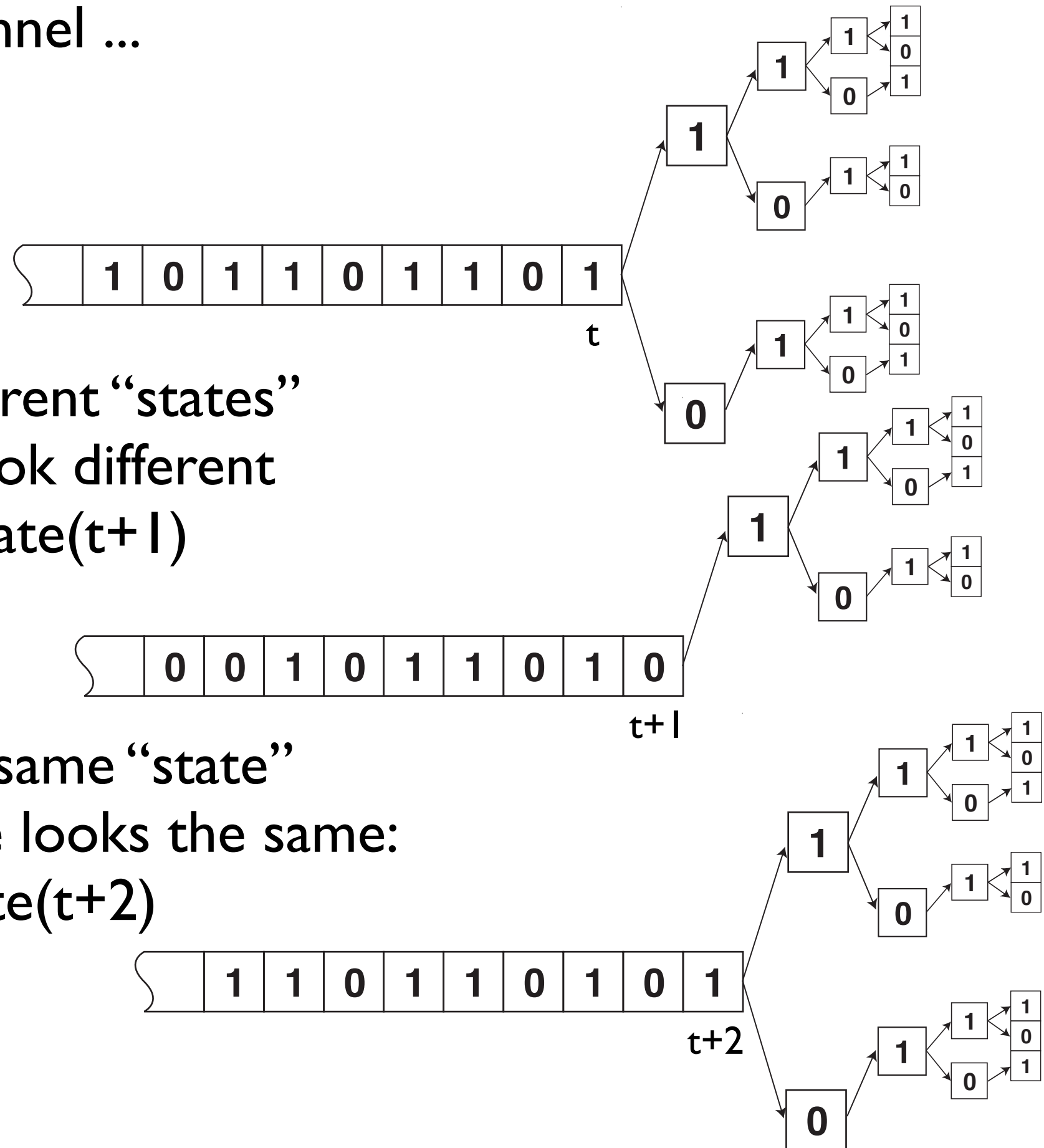
## Effective States:

# Process is in different “states” when futures look different

$$\text{State}(t) \approx \text{State}(t+1)$$

Process is in the same “state”  
when the future looks the same:

# State(t) ~ State(t+2)



# The Learning Channel ...

## Causal States:

### Causal State:

Set of pasts with same morph  $\Pr(\vec{S} \mid \overleftarrow{s})$ .

Set of histories that lead to same predictions.

### Predictive equivalence relation:

$$\overleftarrow{s}' \sim \overleftarrow{s}'' \iff \Pr(\vec{S} \mid \overleftarrow{S} = \overleftarrow{s}') = \Pr(\vec{S} \mid \overleftarrow{S} = \overleftarrow{s}'')$$

$$\overleftarrow{s}', \overleftarrow{s}'' \in \overleftarrow{\mathbf{S}}$$

# The Learning Channel ...

## Causal State Components

Causal State = Pasts with same morph:  $\Pr(\vec{S} \mid \overleftarrow{s})$

$$\mathcal{S} = \{ \overleftarrow{s}' : \overleftarrow{s}' \sim \overleftarrow{s} \}$$

Set of causal states:

$$\mathcal{S} = \overleftarrow{\mathbf{S}} / \sim = \{ \mathcal{S}_0, \mathcal{S}_1, \mathcal{S}_2, \dots \}$$

Causal state map:

$$\epsilon : \overleftarrow{\mathbf{S}} \rightarrow \mathcal{S}$$

$$\epsilon(\overleftarrow{s}) = \{ \overleftarrow{s}' : \overleftarrow{s}' \sim \overleftarrow{s} \}$$

# The Learning Channel ...

## Causal States ...

We've answered the first part of the modeling goal:

We have the effective states!

Now,

What is the dynamic?

# The Learning Channel ...

## Causal State Dynamic ...

### Causal-state Filtering:

$$\begin{aligned}\overleftrightarrow{s} &= \dots s_{-3} \quad s_{-2} \quad s_{-1} \quad s_0 \quad s_1 \quad s_2 \quad s_3 \quad \dots \\ \epsilon(\overleftrightarrow{s}) &= \dots \epsilon(\overleftarrow{s}_{-3}) \epsilon(\overleftarrow{s}_{-2}) \epsilon(\overleftarrow{s}_{-1}) \epsilon(\overleftarrow{s}_0) \epsilon(\overleftarrow{s}_1) \epsilon(\overleftarrow{s}_2) \epsilon(\overleftarrow{s}_3) \dots \\ \overleftrightarrow{\mathcal{S}} &= \dots \mathcal{S}_{t=-3} \mathcal{S}_{t=-2} \mathcal{S}_{t=-1} \mathcal{S}_{t=0} \mathcal{S}_{t=1} \mathcal{S}_{t=2} \mathcal{S}_{t=3} \dots\end{aligned}$$

### Causal-state process:

$$\Pr(\overleftrightarrow{\mathcal{S}})$$

# The Learning Channel ...

## Causal State Dynamic ...

Conditional transition probability:

$$\begin{aligned} T_{ij}^{(s)} &= \Pr(\mathcal{S}_j, s | \mathcal{S}_i) \\ &= \Pr\left(\mathcal{S} = \epsilon(\overleftarrow{s} s) | \mathcal{S} = \epsilon(\overleftarrow{s})\right) \end{aligned}$$

State-to-State Transitions:

$$\{T_{ij}^{(s)} : s \in \mathcal{A}, i, j = 0, 1, \dots, |\mathcal{S}|\}$$

# The $\epsilon$ -Machine ...

Process  $\Rightarrow$  Predictive equivalence  $\Rightarrow \epsilon$  - Machine

$$\text{Pr}(\vec{S}) \Rightarrow \vec{\mathbf{S}} / \sim \Rightarrow \epsilon - \text{Machine}$$

$$\mathcal{M} = \left\{ \mathbf{s}, \{T^{(s)}, s \in \mathcal{A}\} \right\}$$

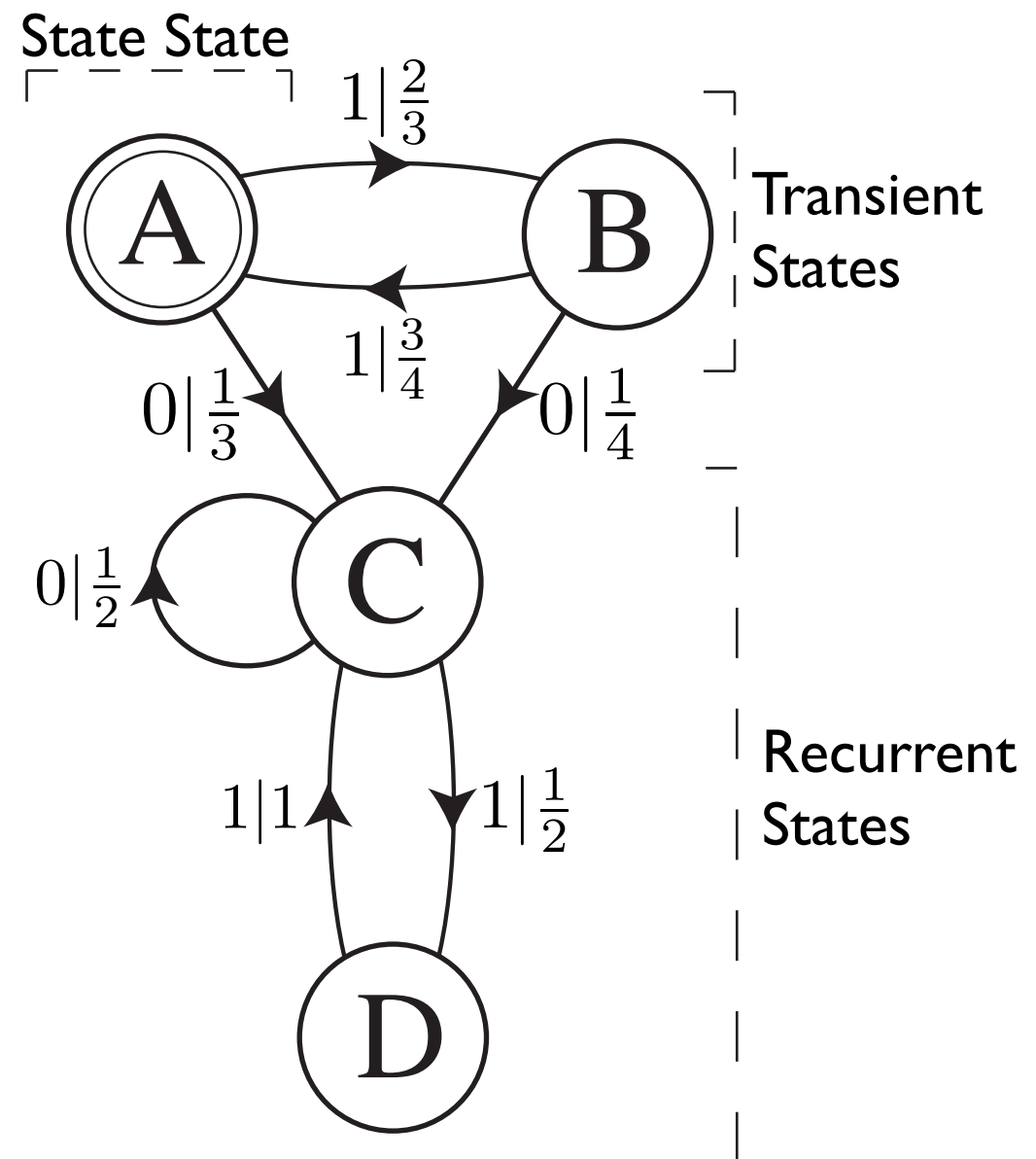
Unique Start State:

$$\mathcal{S}_0 = [\lambda]$$

$$\text{Pr}(\mathcal{S}_0, \mathcal{S}_1, \mathcal{S}_2, \dots) = (1, 0, 0, \dots)$$

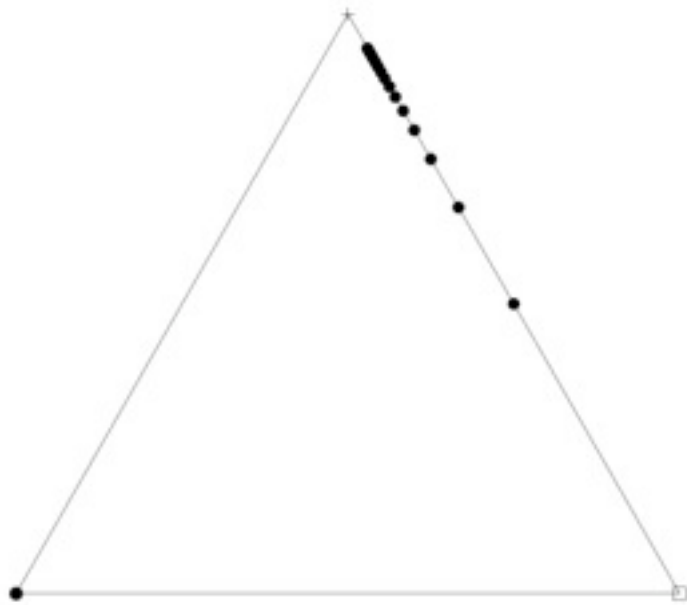
Transient States

Recurrent States

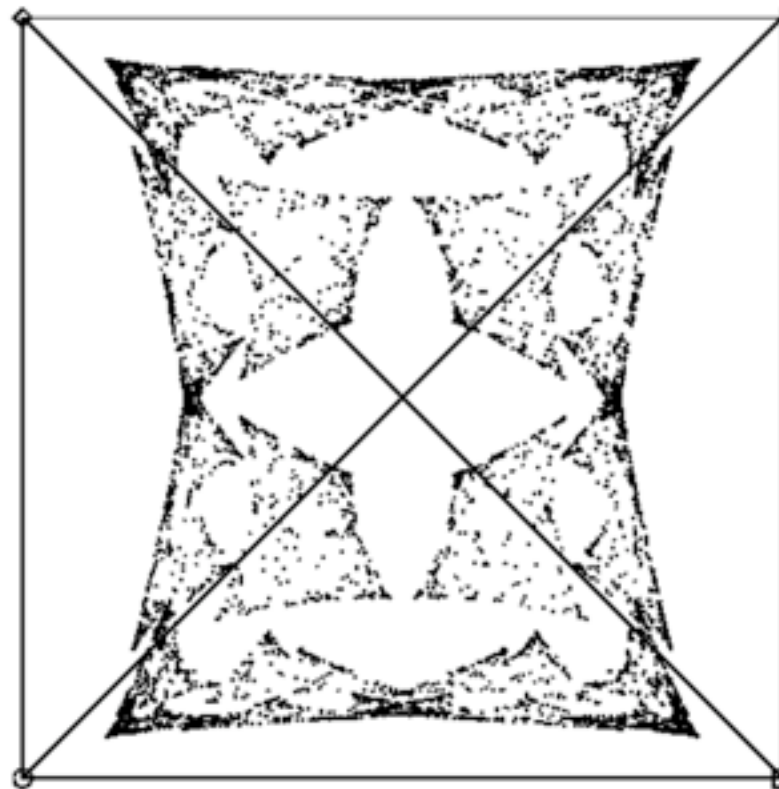


# The Learning Channel ...

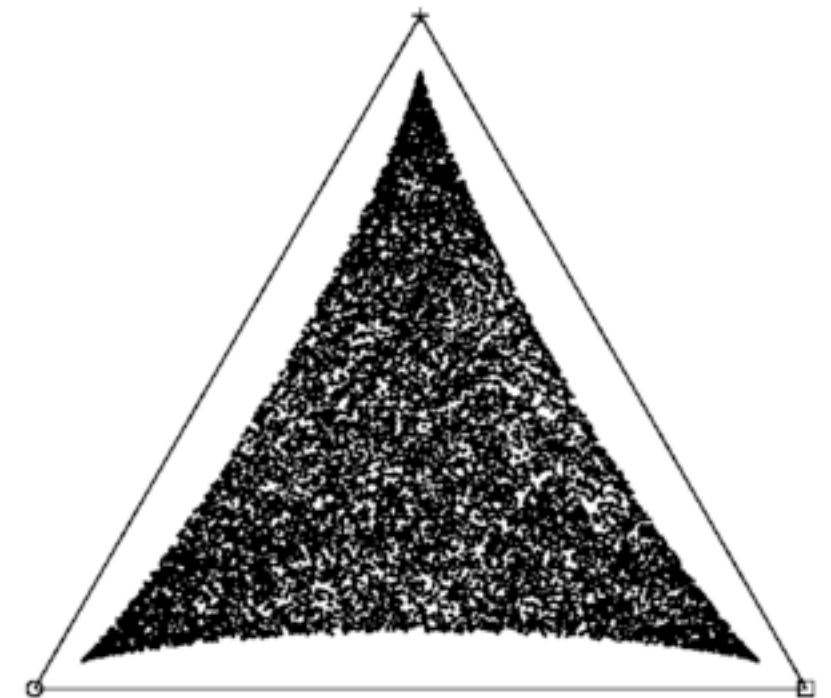
## The $\epsilon$ -Machine of a Process ...



**Denumerable  
Causal States**

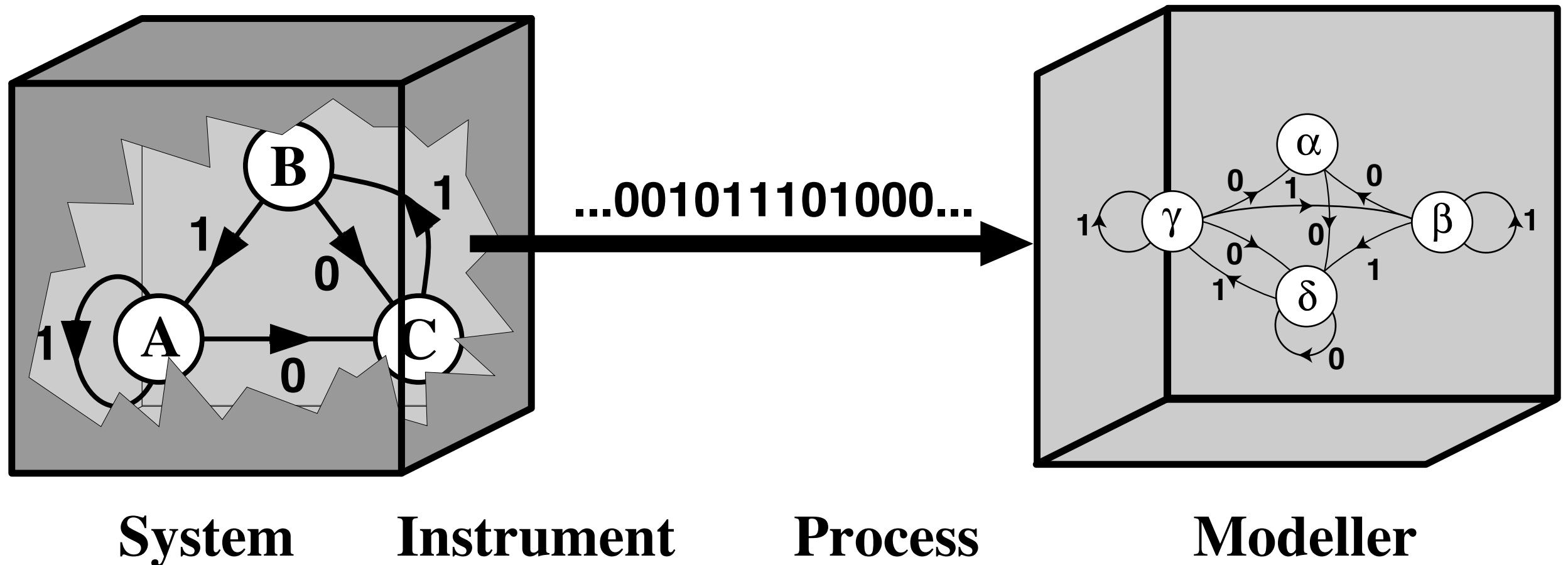


**Fractal**



**Continuous**

# The Learning Channel:



Central questions:

What are the states? Causal States

What is the dynamic? The  $\epsilon$ -Machine

# The $\epsilon$ -Machine

# The $\epsilon$ -Machine ...

A **Model** of a Process  $\Pr(\vec{S})$ :

$\epsilon$ -Machine reproduces the process's word distribution:

$$\Pr(s^1), \Pr(s^2), \Pr(s^3), \dots$$

$$s^L = s_1 s_2 \dots s_L \quad \mathcal{S}(t=0) = \mathcal{S}_0$$

$$\begin{aligned} \Pr(s^L) = & \Pr(\mathcal{S}_0) \Pr(\mathcal{S}_0 \rightarrow_{s=s_1} \mathcal{S}(1)) \Pr(\mathcal{S}(1) \rightarrow_{s=s_2} \mathcal{S}(2)) \\ & \dots \Pr(\mathcal{S}(L-1) \rightarrow_{s=s_L} \mathcal{S}(L)) \end{aligned}$$

Initially,  $\Pr(\mathcal{S}_0) = 1$ .

$$\Pr(s^L) = \prod_{l=1}^L T_{i=\epsilon(s^{l-1}), j=\epsilon(s^l)}^{(s^l)}$$

# The $\epsilon$ -Machine ...

## Causal shielding:

Past and future are independent given causal state

$$\text{Process: } \Pr(\vec{S}) = \Pr(\overleftarrow{S} \overrightarrow{S})$$

$$\Pr(\overleftarrow{S} \overrightarrow{S} | \mathcal{S}) = \Pr(\overleftarrow{S} | \mathcal{S}) \Pr(\overrightarrow{S} | \mathcal{S})$$

Causal states shield past & future from each other.

Similar to states of a Markov chain, but for hidden processes.

# The $\epsilon$ -Machine ...

$\epsilon$ Ms are **Unifilar**:  $(\mathcal{S}_t, s) \rightarrow \text{unique } \mathcal{S}_{t+1}$   
(in automata theory, “deterministic”)

## Consequence:

Unifilarity: 1-1 map between state-sequences & symbol-sequences.

Entropy rate expression requires this 1-1 mapping.

Can use  $\epsilon$ M to calculate entropy rate  $h_\mu$ .  
(Any unifilar presentation will do.)

# The $\epsilon$ -Machine ...

$\epsilon$ Ms are **Optimal Predictors**:

Compared to any rival effective states  $R$ :

$$H \left[ \begin{array}{c|c} \vec{S}^L & R \end{array} \right] \geq H \left[ \begin{array}{c|c} \vec{S}^L & S \end{array} \right]$$

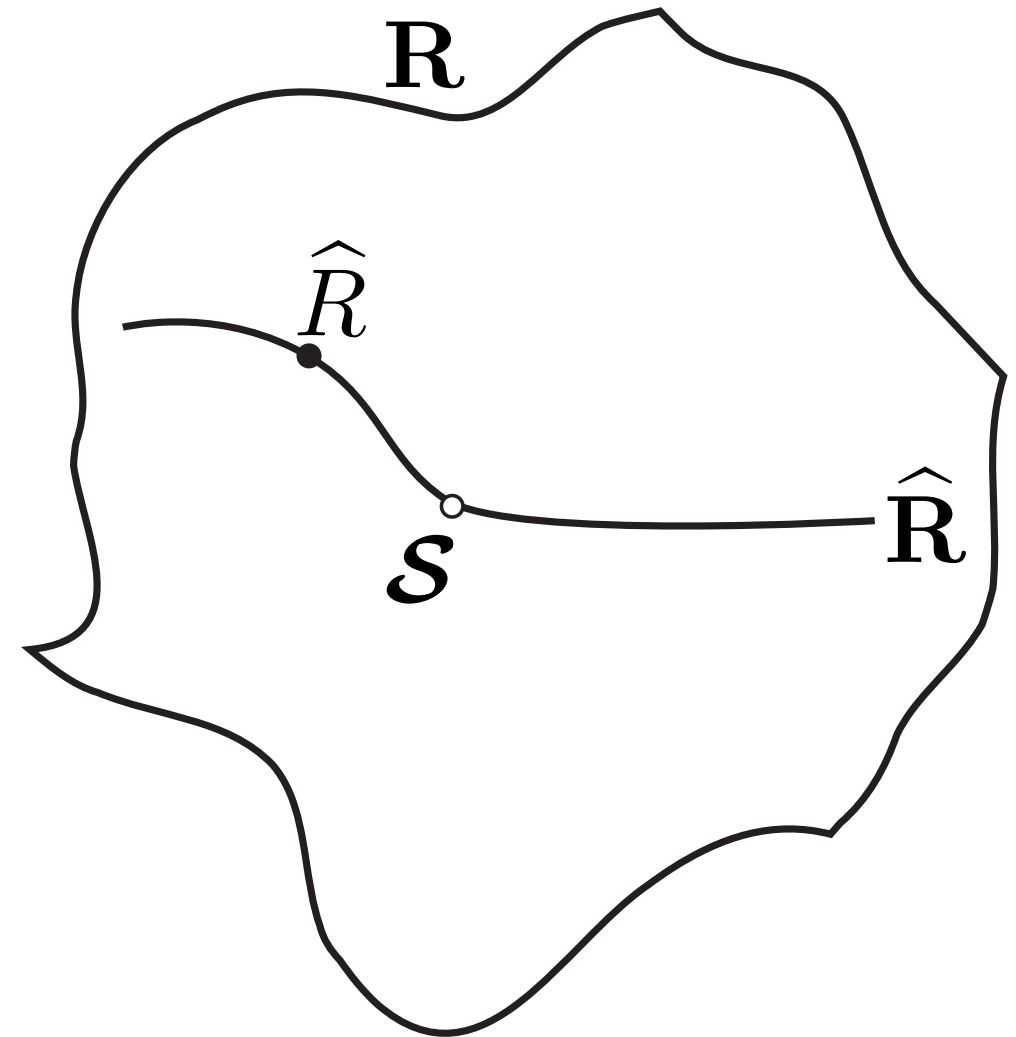
# The $\epsilon$ -Machine ...

## Prescient Rivals $\hat{\mathbf{R}}$ :

Alternative models that are optimal predictors

$$\hat{R} \in \hat{\mathbf{R}}$$

$$H[\vec{S}^L | \hat{R}] = H[\vec{S}^L | \mathcal{S}]$$



(Prescient rivals are sufficient statistics for process's future.)

# The $\epsilon$ -Machine ...

## Minimal Statistical Complexity:

For all prescient rivals,  $\epsilon M$  is the smallest:

$$C_{\mu}(\hat{R}) \geq C_{\mu}(\mathcal{S})$$

Consequence:

- (1)  $C_{\mu}$  measures historical information process stores.
- (2) This would not be true, if not minimal representation.

Remarks:

- (1) Causal states contain every difference (in past)  
that makes a difference (to future) (Bateson “information”)
- (2) Causal states are sufficient statistics for the future.

# The $\epsilon$ -Machine ...

## Summary:

$\epsilon M$ :

- (1) Optimal predictor: Lower prediction error than any rival.
- (2) Minimal size: Smallest of the prescient rivals.
- (3) Unique: Smallest, optimal, unifilar predictor is equivalent.
- (4) Model of the process: Reproduces all of process's statistics.
- (5) Causal shielding: Renders process's future independent of past.

# Measures of Intrinsic Computation

# Measures of Intrinsic Computation ...

A complex process's **intrinsic computation**:

(1) How much of past does process store?

(2) In what architecture is that information stored?

(3) How is stored information used to produce future behavior?

# Measures of Intrinsic Computation ...

A complex process's **intrinsic computation**:

(1) How much of past does process store?

$$C_{\mu}$$

(2) In what architecture is that information stored?

(3) How is stored information used to produce future behavior?

# Measures of Intrinsic Computation ...

A complex process's **intrinsic computation**:

(1) How much of past does process store?

$$C_{\mu}$$

(2) In what architecture is that information stored?

$$\left\{ \mathcal{S}, \{T^{(s)}, s \in \mathcal{A}\} \right\}$$

(3) How is stored information used to produce future behavior?

# Measures of Intrinsic Computation ...

A complex process's **intrinsic computation**:

(1) How much of past does process store?

$$C_{\mu}$$

(2) In what architecture is that information stored?

$$\left\{ \mathcal{S}, \{T^{(s)}, s \in \mathcal{A}\} \right\}$$

(3) How is stored information used to produce future behavior?

$$h_{\mu}$$

# Measures of Intrinsic Computation ...

## Measures of Structural Complexity:

| Information Measures  |          | Interpretation       |
|-----------------------|----------|----------------------|
| Entropy Rate          | $h_\mu$  | Intrinsic Randomness |
| Excess Entropy        | <b>E</b> | Info: Past to Future |
| Total Predictability  | <b>G</b> | Redundancy           |
| Transient Information | <b>T</b> | Synchronization      |

How related to statistical complexity  $C_\mu$ ?

How to get from  $\epsilon M$ ?

# Measures of Intrinsic Computation ...

Measures from the  $\epsilon M$ :

Entropy Rate of a Process:

$$h_{\mu}(\text{Pr}(\vec{S})) = \lim_{L \rightarrow \infty} \frac{H(L)}{L}$$

Entropy Rate given  $\epsilon M$ :

$$h_{\mu}(\mathcal{S}) = - \sum_{\mathcal{S} \in \mathcal{S}} \text{Pr}(\mathcal{S}) \sum_{s \in \mathcal{A}, \mathcal{S}' \in \mathcal{S}} T_{\mathcal{S}\mathcal{S}'}^{(s)} \log_2 T_{\mathcal{S}\mathcal{S}'}^{(s)}$$

where  $\text{Pr}(\mathcal{S})$  is casual-state asymptotic probability.

Possible only due to  $\epsilon M$  unifilarity!

I-I mapping between measurement sequences & internal paths.

# Measures of Intrinsic Computation ...

Measures from the  $\epsilon M$ ...

## Statistical Complexity of a Process:

$$C_{\mu}(\mathcal{S}) = - \sum_{\mathcal{S} \in \mathcal{S}} \text{Pr}(\mathcal{S}) \log_2 \text{Pr}(\mathcal{S})$$

where  $\text{Pr}(\mathcal{S})$  is causal-state asymptotic probability.

### Meaning:

Shannon information in the causal states.

The amount of historical information a process stores.

The amount of structure in a process.

# Measures of Intrinsic Computation ...

Measures from the  $\epsilon M$ ...

**Excess Entropy:** Three versions, all equivalent for IID processes

$$\mathbf{E} = \lim_{L \rightarrow \infty} [H(L) - h_\mu L]$$

$$\mathbf{E} = \sum_{L=1}^{\infty} [h_\mu(L) - h_\mu]$$

$$\mathbf{E} = I[\overleftarrow{S}; \overrightarrow{S}]$$

How to get, given  $\epsilon M$ ?

Special cases: When  $\epsilon M$  is IID, periodic, or spin chain.

General case: Need a new framework.

# Measures of Intrinsic Computation ...

Measures from the  $\epsilon\mathcal{M}$  ...

Bound on Excess Entropy:

$$\mathbf{E} \leq C_\mu$$

Proof sketch:

$$(1) \mathbf{E} = I[\vec{S}; \overleftarrow{S}] = H[\vec{S}] - H[\vec{S} | \overleftarrow{S}]$$

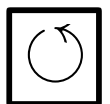
$$(2) \text{ Causal States: } H[\vec{S} | \overleftarrow{S}] = H[\vec{S} | \mathcal{S}]$$

$$(3) \mathbf{E} = H[\vec{S}] - H[\vec{S} | \mathcal{S}]$$

$$= I[\vec{S}; \mathcal{S}]$$

$$= H[\mathcal{S}] - H[\mathcal{S} | \vec{S}]$$

$$\leq H[\mathcal{S}] = C_\mu$$



# Measures of Intrinsic Computation ...

Measures from the  $\epsilon\mathcal{M}$  ...

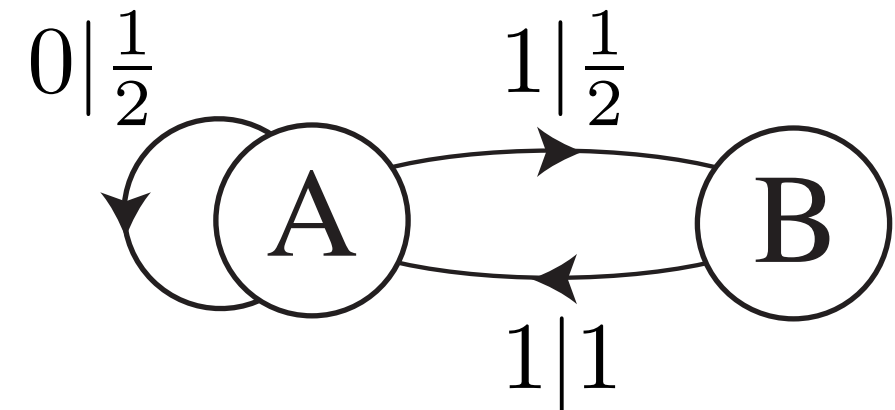
Bound on Excess Entropy ...

But, the bound is saturated!

Even Process:

$$C_\mu = H(2/3) \approx 0.9182$$

$$\mathbf{E} \approx 0.9182$$



$$T^{(0)} = \begin{pmatrix} \frac{1}{2} & 0 \\ 0 & 0 \end{pmatrix}$$

$$T^{(1)} = \begin{pmatrix} 0 & \frac{1}{2} \\ 1 & 0 \end{pmatrix}$$

$$\pi_V = (2/3, 1/3)$$

When does this occur?

In general, need a new framework for answering this question:  
**Directional Computational Mechanics.**

Measures of Intrinsic Computation ...

Measures from the  $\epsilon M$  ...

Bound on Excess Entropy ...

Consequence: The Cryptographic Limit

Can have  $E \rightarrow 0$  when  $C_\mu \gg 1$ .

Excess entropy is *not* the process's stored information.

$E$  is the *apparent* information,  
as revealed in *measurement sequences*.

Statistical complexity *is* stored information.

Measures of Intrinsic Computation ...

Measures from the  $\epsilon M$  ...

Bound on Excess Entropy ...

Executive Summary:

$C_\mu$  is the amount of information the process uses  
to *communicate*

**E** bits of information from the past to the future.

# Measures of Intrinsic Computation ...

Measures from the  $\epsilon M$  ...

Bound on Excess Entropy:  $\mathbf{E} \leq C_\mu$

Consequence:

The inequality is Why We Must Model.

Cannot simply use sequences as states.

There is internal structure not expressed by this.

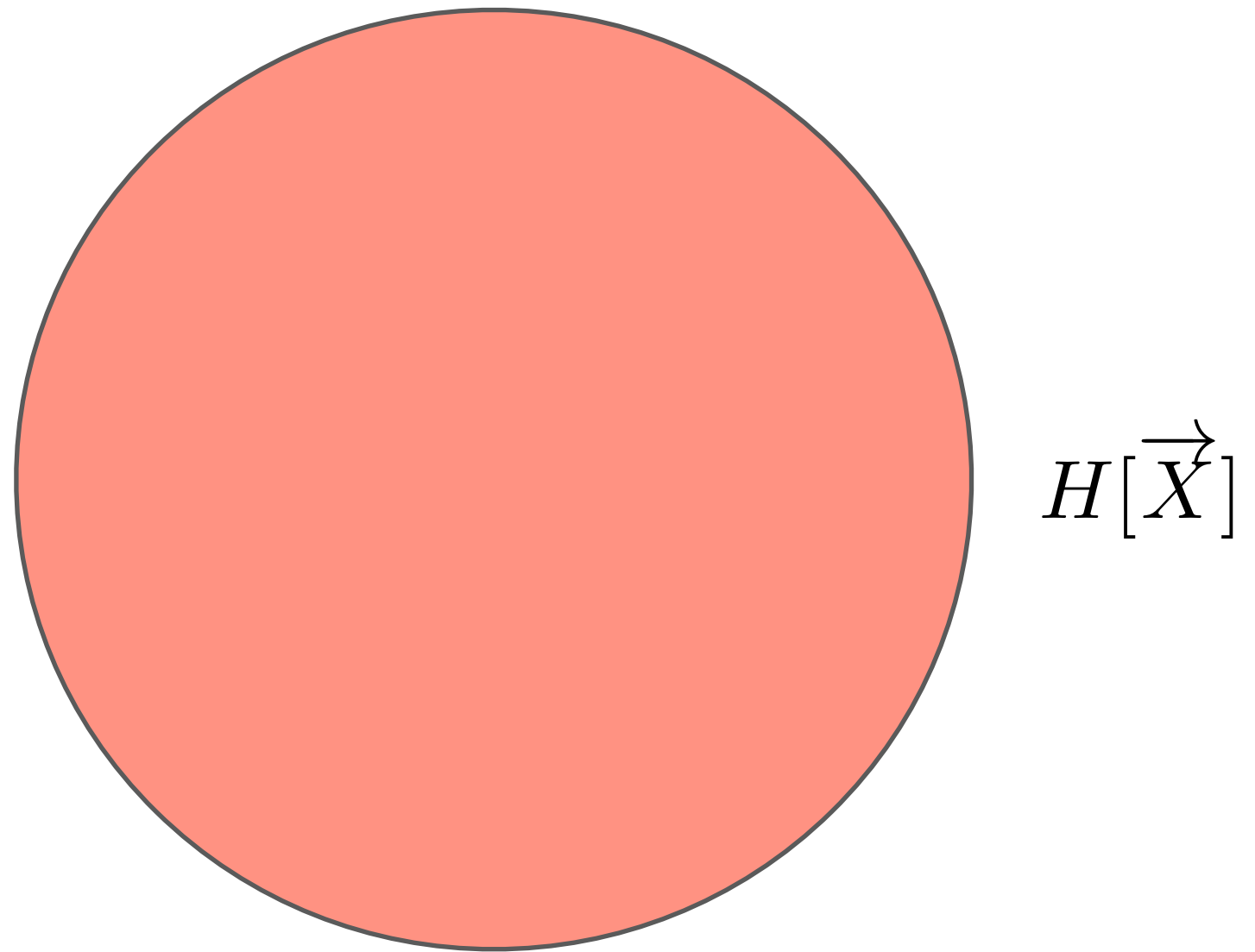
# Information Diagrams for Processes

# Information Diagrams for Processes

## Process I-diagram:

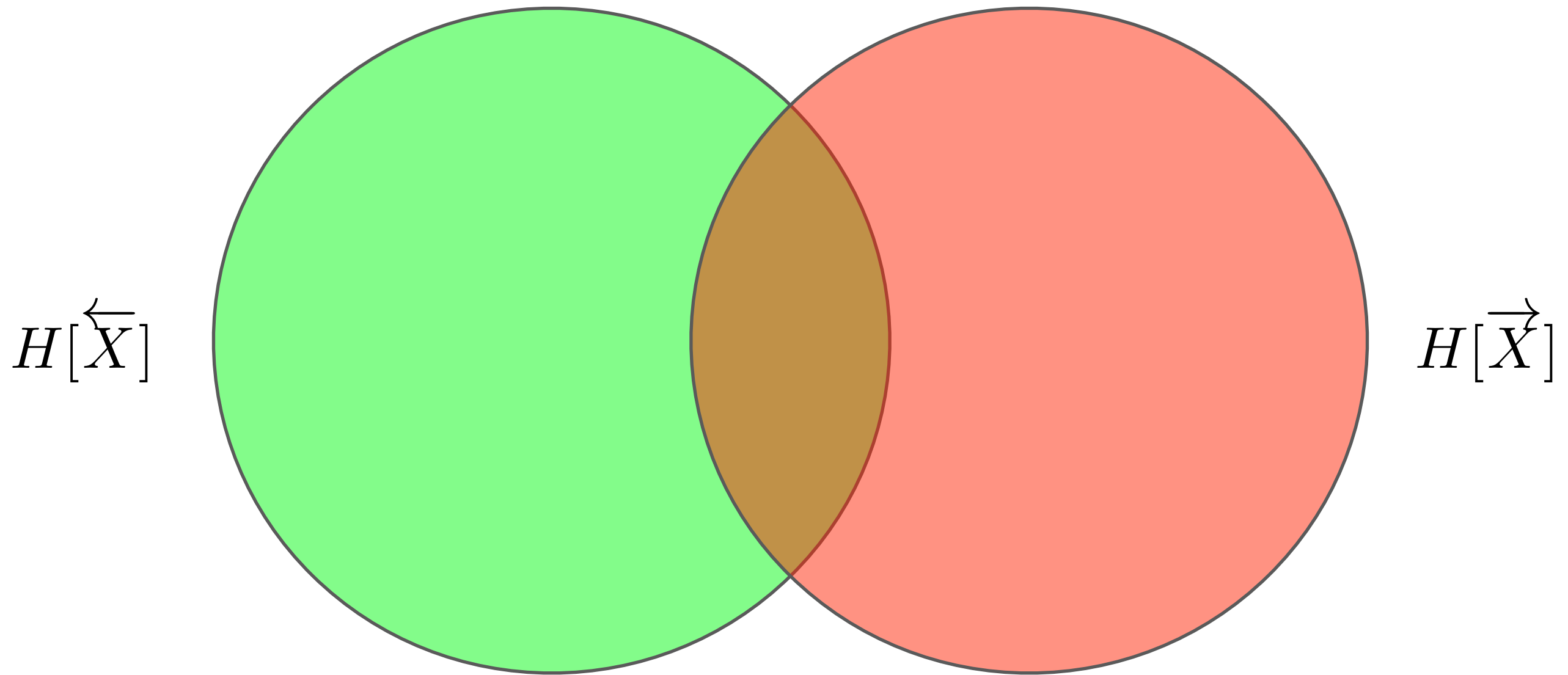
# Information Diagrams for Processes

## Process I-diagram:



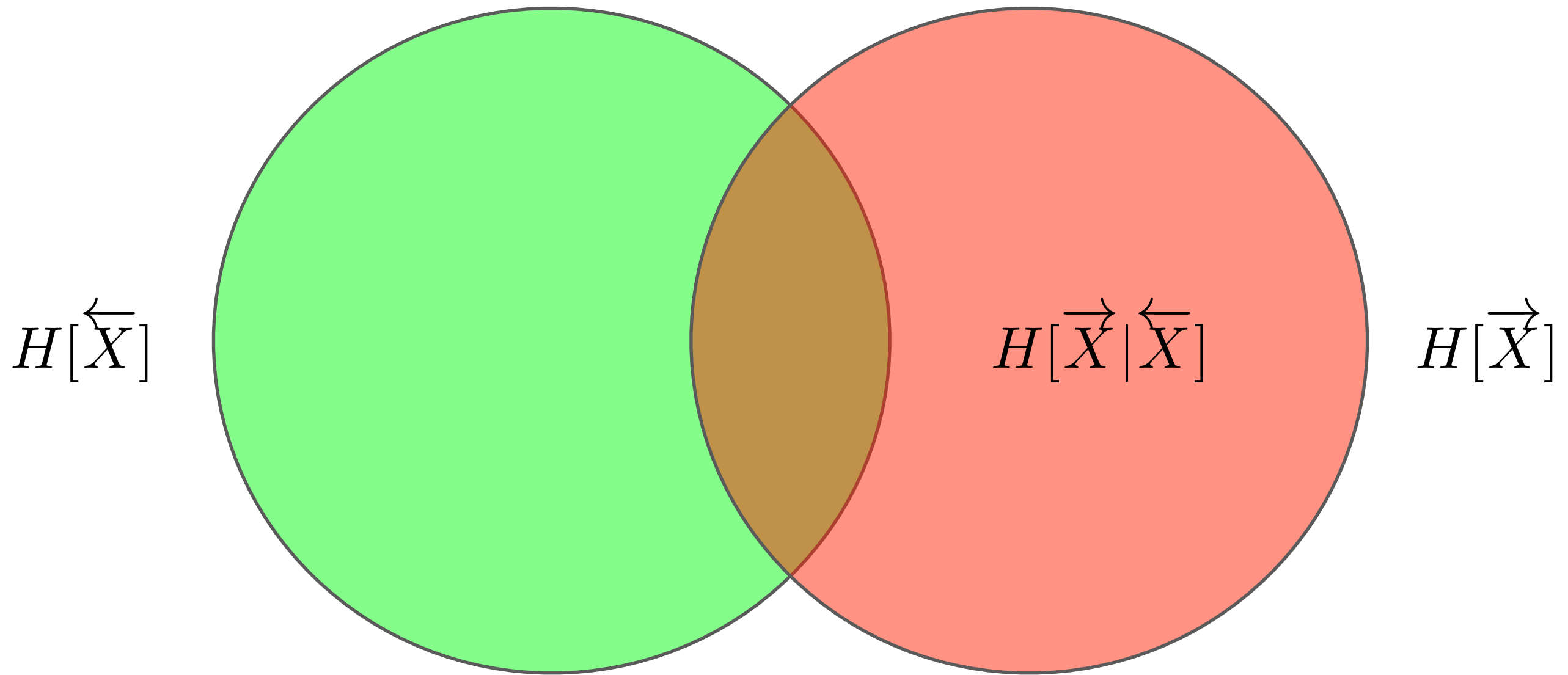
# Information Diagrams for Processes

Process I-diagram:



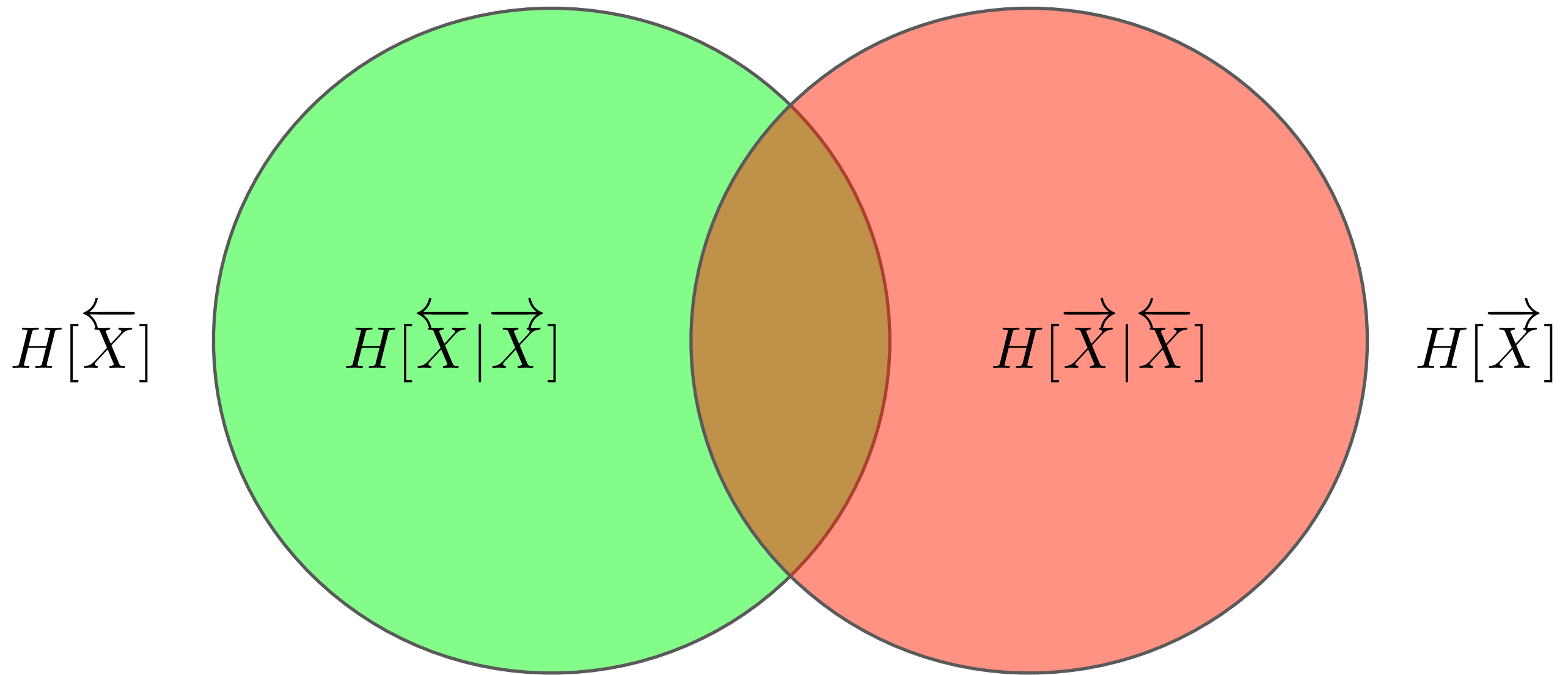
# Information Diagrams for Processes

Process I-diagram:



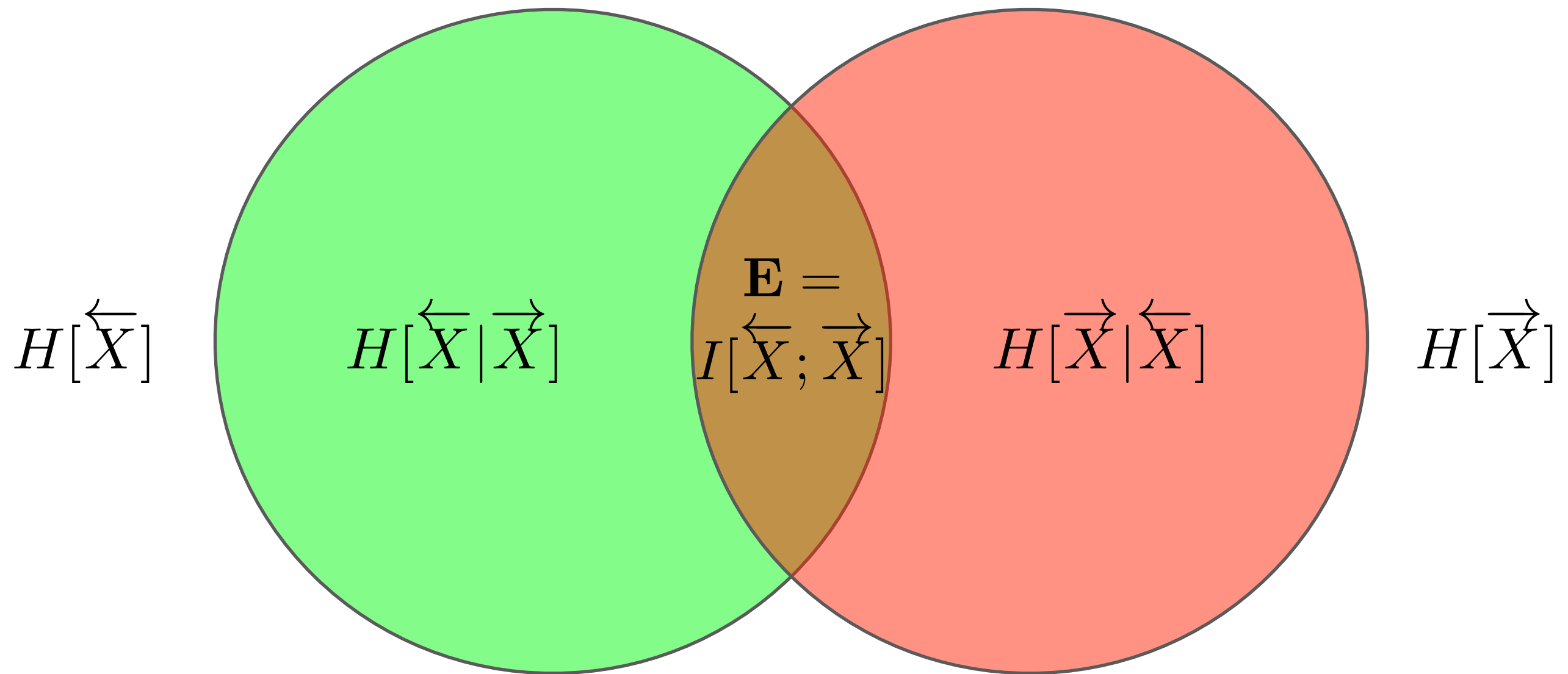
# Information Diagrams for Processes

Process I-diagram:



# Information Diagrams for Processes

## Process I-diagram:



# Information Diagrams for Processes

Process I-diagram using  $\varepsilon$ -machine:

Start with 3-variable I-diagram and whittle down:

Past as composite random variable:  $\overleftarrow{X}$

Future as composite random variable:  $\overrightarrow{X}$

Causal states:  $\mathcal{S} \in \mathcal{S}$

Information measures:

$$H[\overleftarrow{X}] \quad H[\overrightarrow{X}] \quad H[\mathcal{S}] \quad \cdots \quad I[\overrightarrow{X}; \overleftarrow{X}; \mathcal{S}] \quad \cdots \quad H[\overrightarrow{X}, \overleftarrow{X}, \mathcal{S}]$$

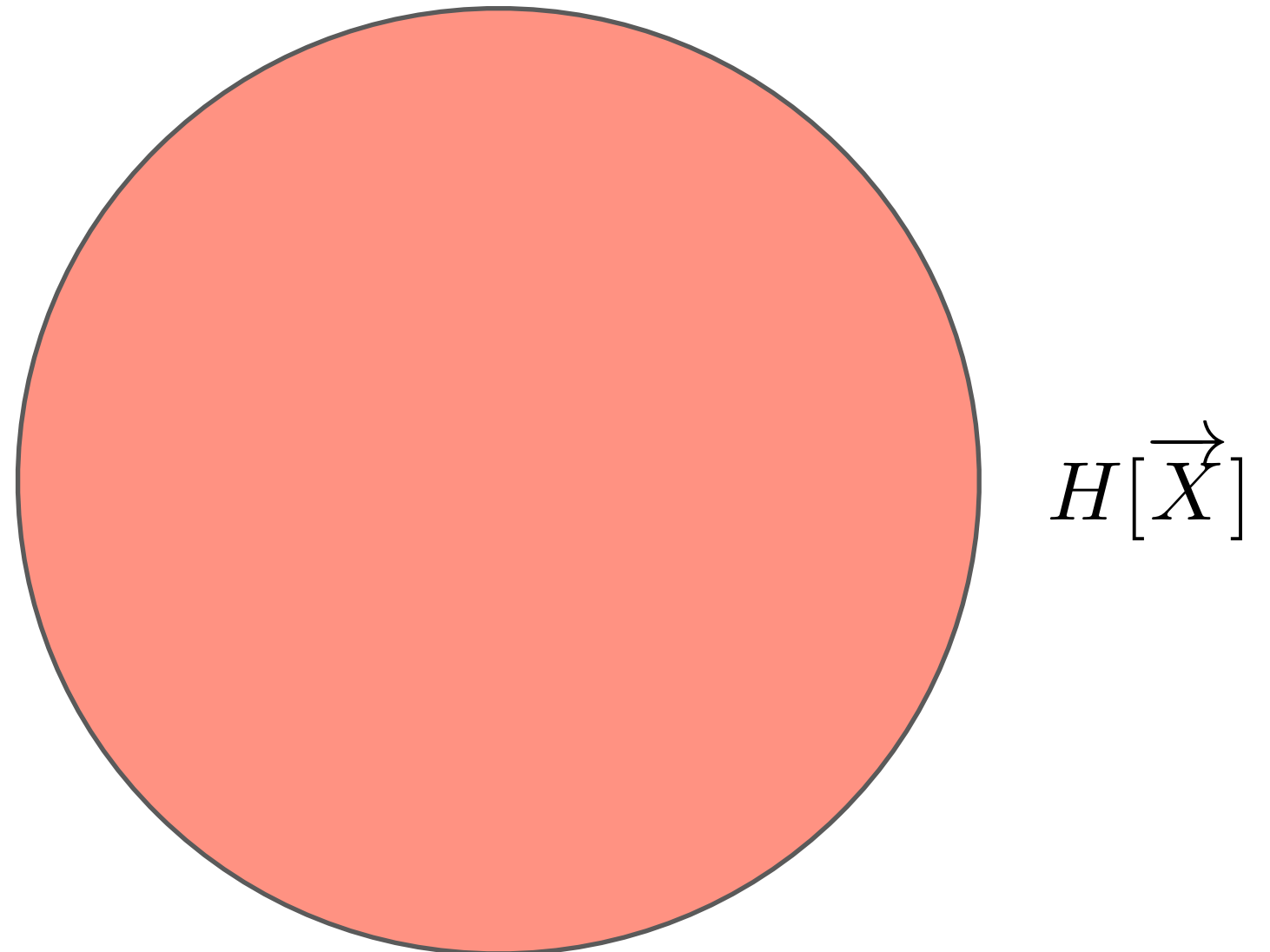
There are  $8 = 2^3$  atomic information measures.

# Information Diagrams for Processes

## Process I-diagram using $\varepsilon$ -machine ...

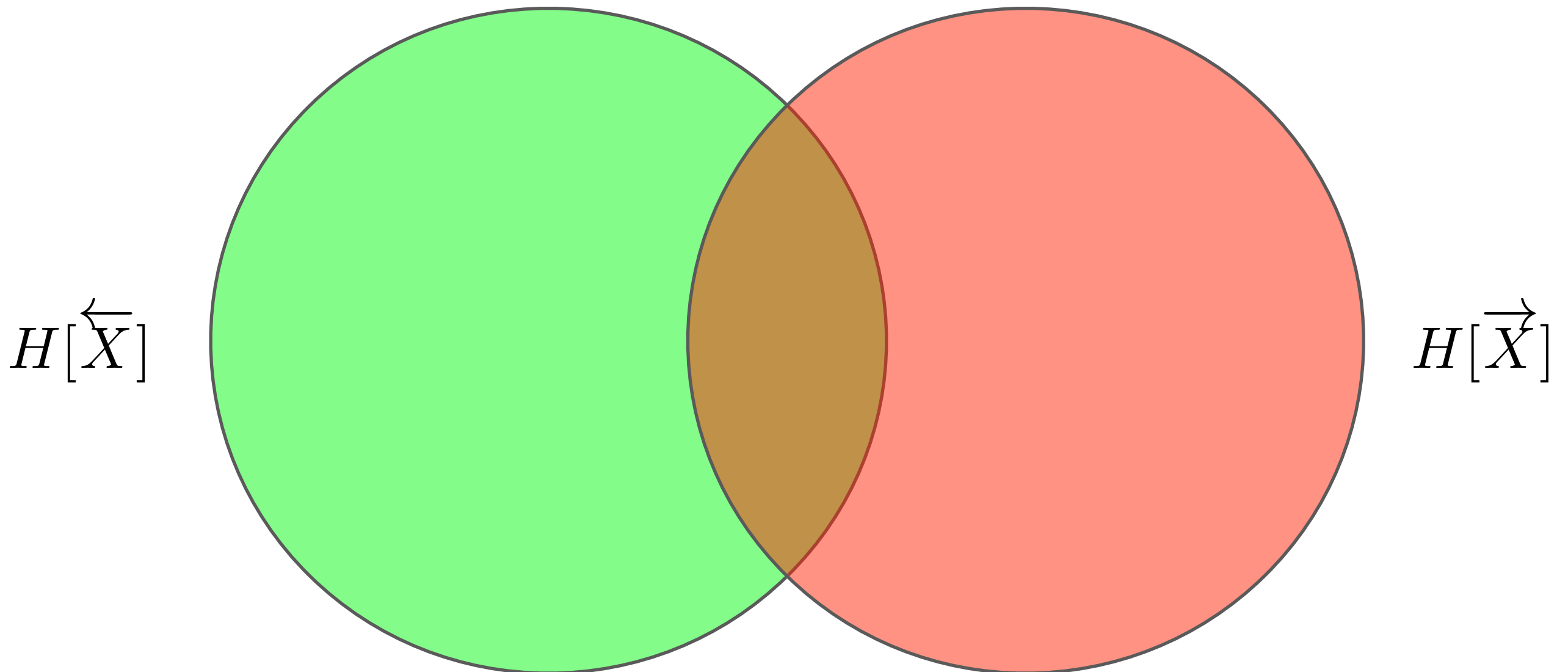
# Information Diagrams for Processes

Process I-diagram using  $\varepsilon$ -machine ...



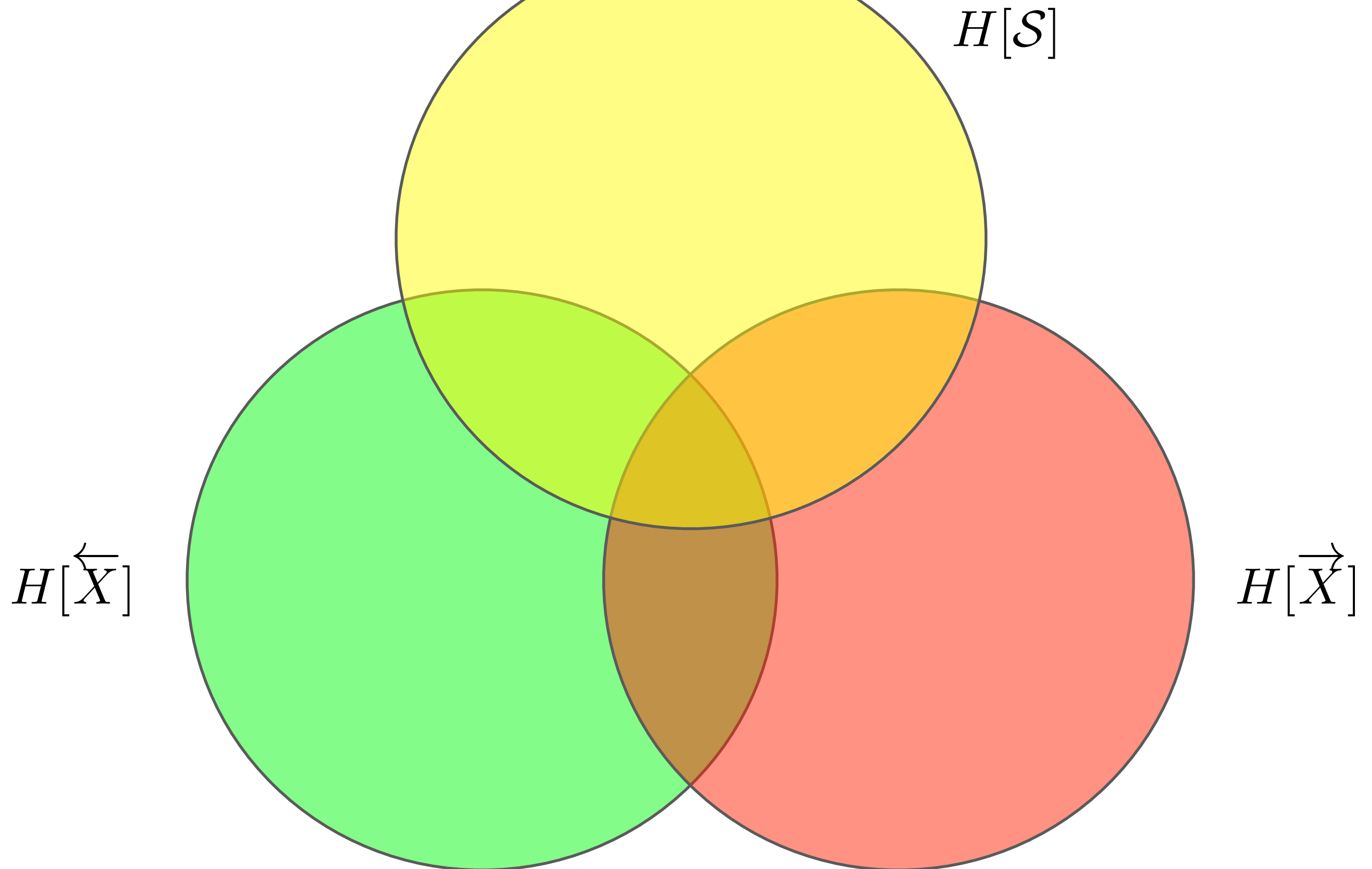
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Process I-diagram using  $\varepsilon$ -machine ...



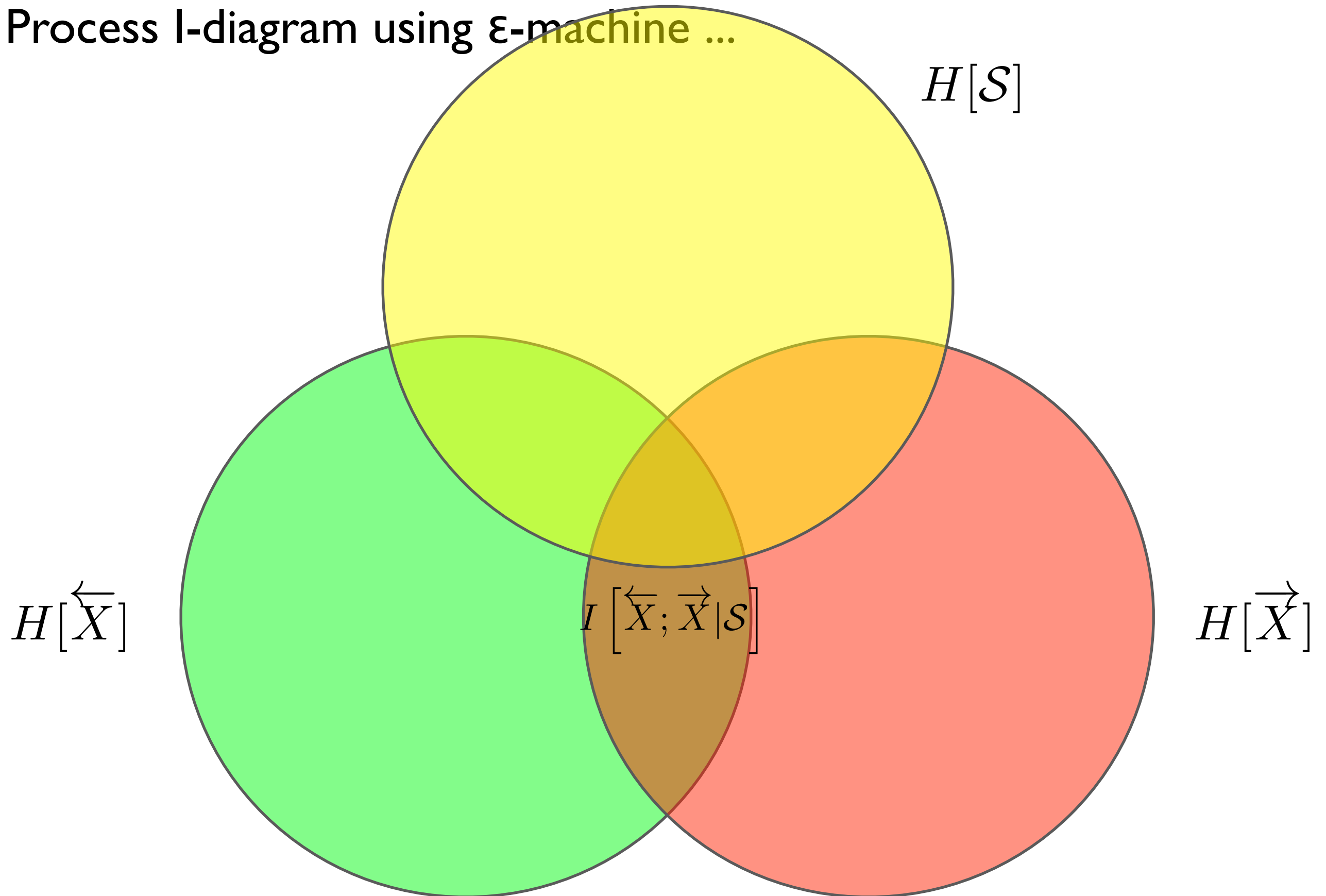
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Process I-diagram using  $\varepsilon$ -machine ...



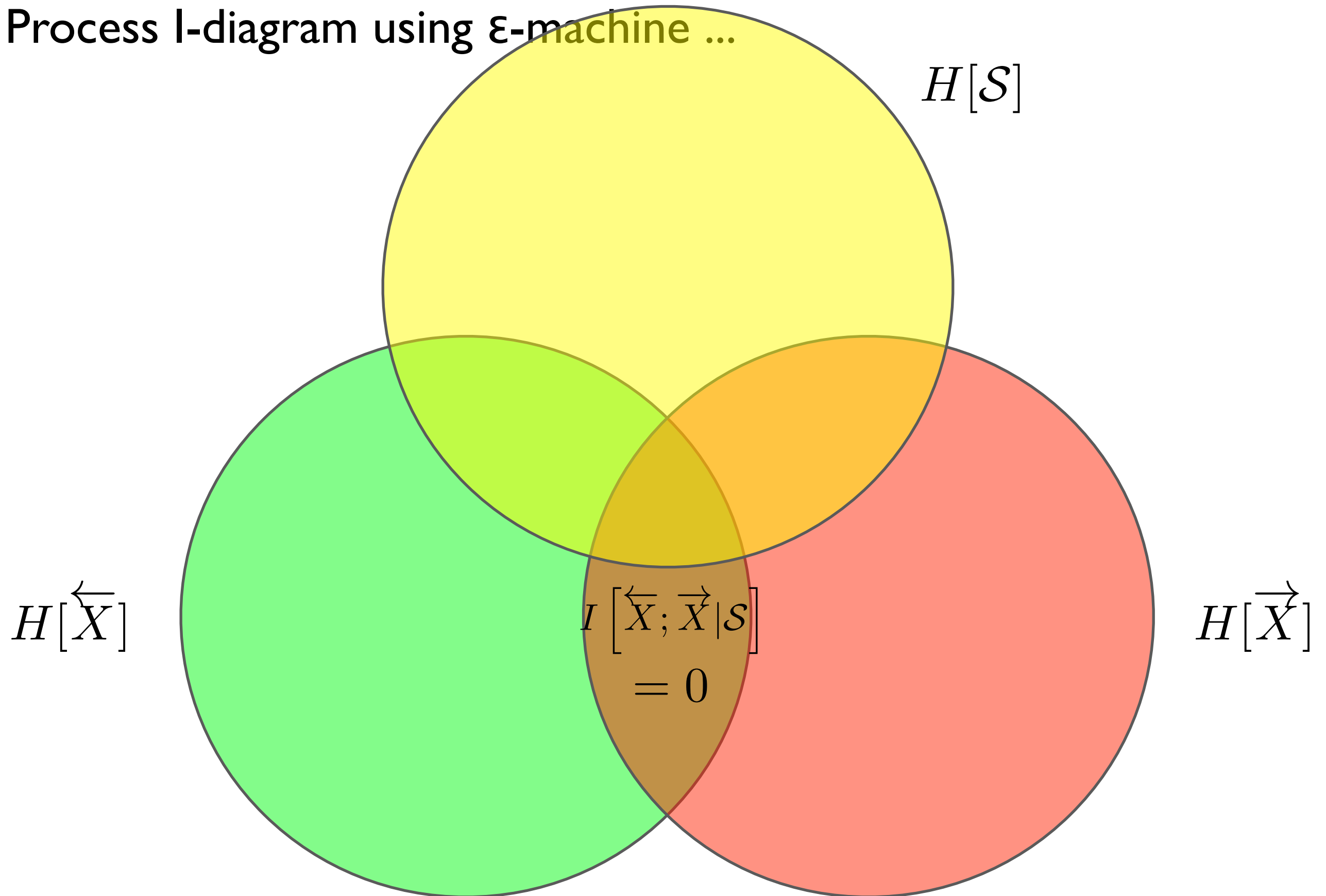
# Information Diagrams for Processes

Process I-diagram using  $\varepsilon$ -machine ...



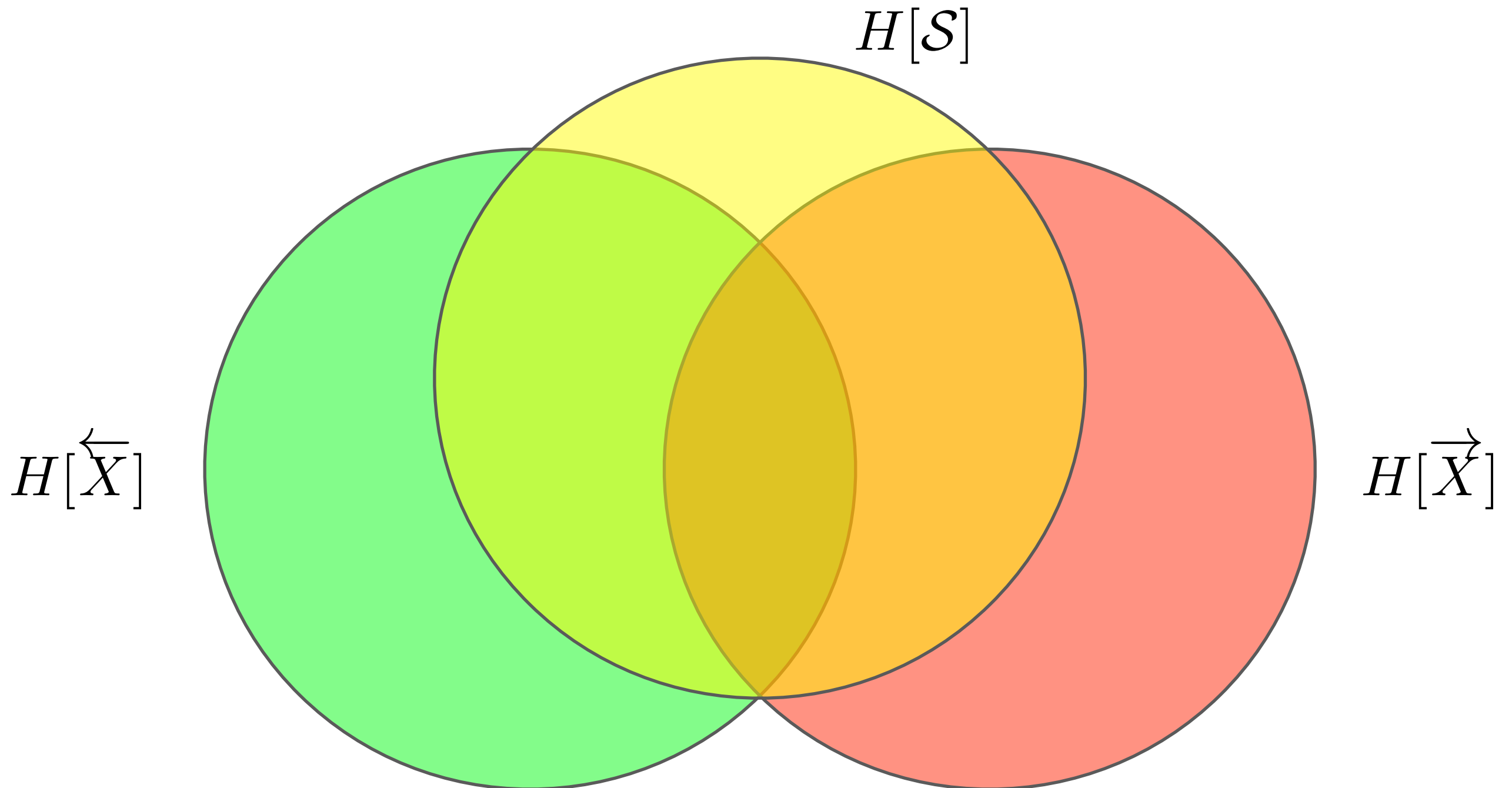
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Process I-diagram using  $\varepsilon$ -machine ...



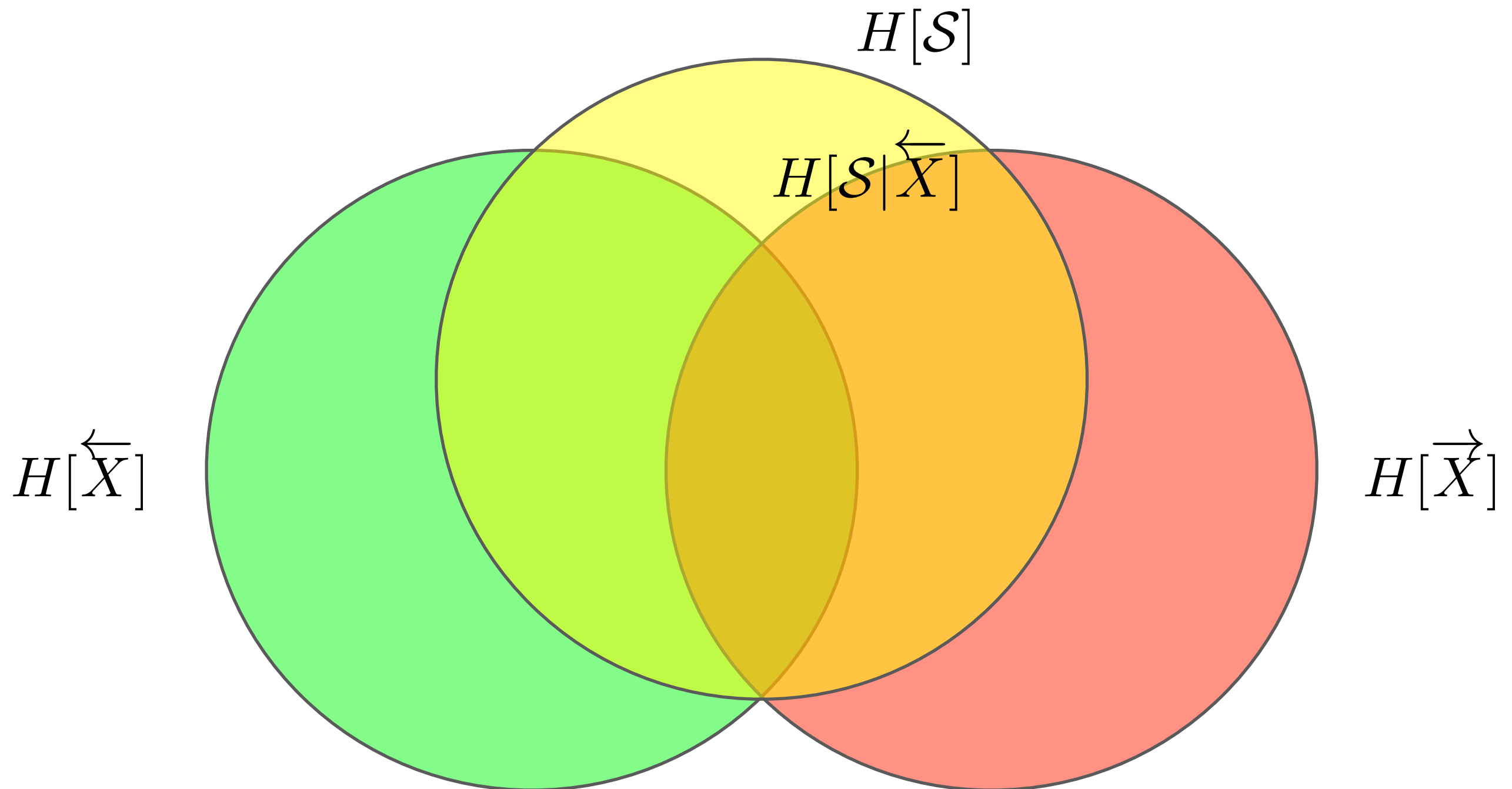
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Process I-diagram using  $\varepsilon$ -machine ...



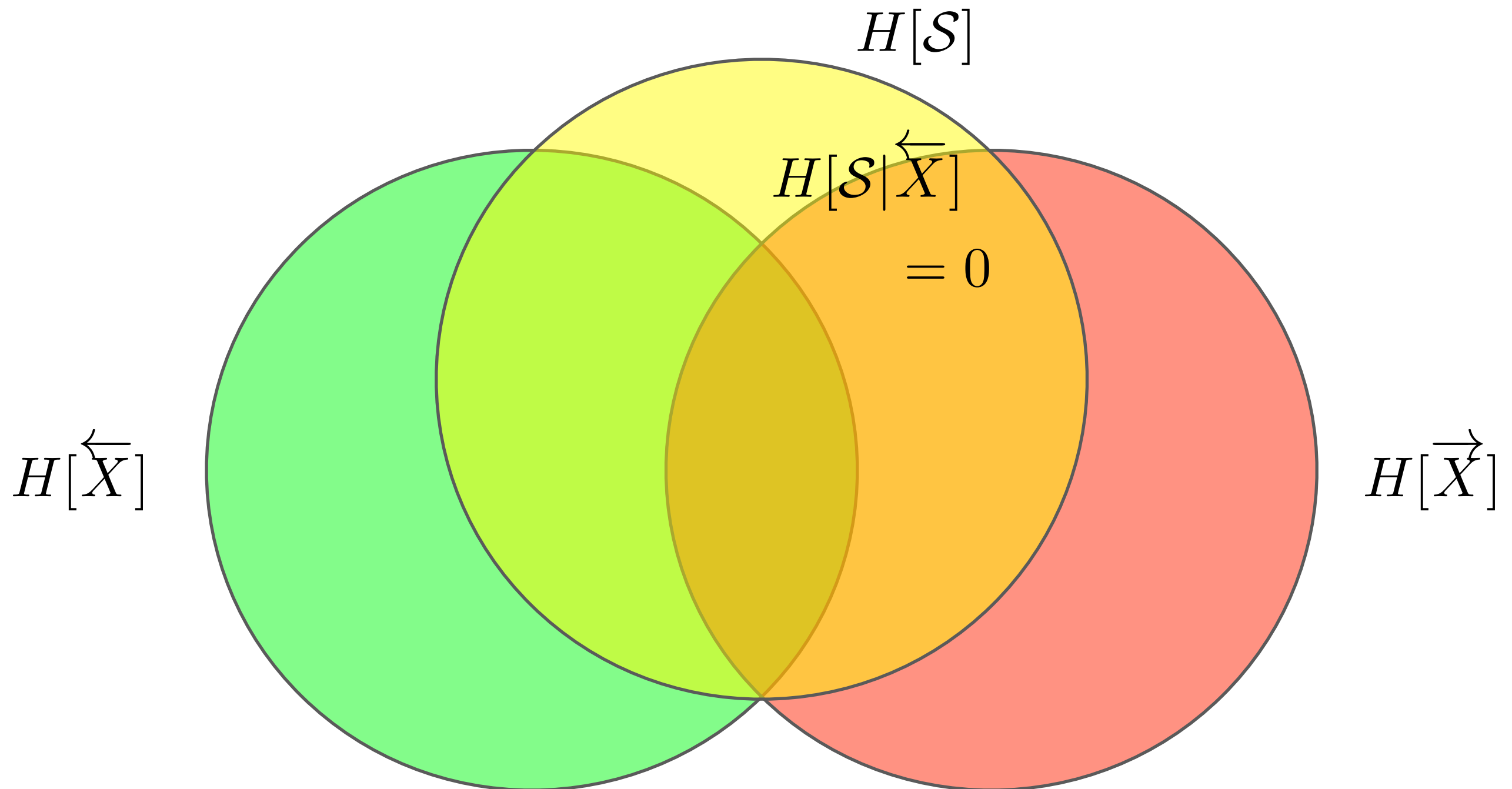
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Process I-diagram using  $\varepsilon$ -machine ...



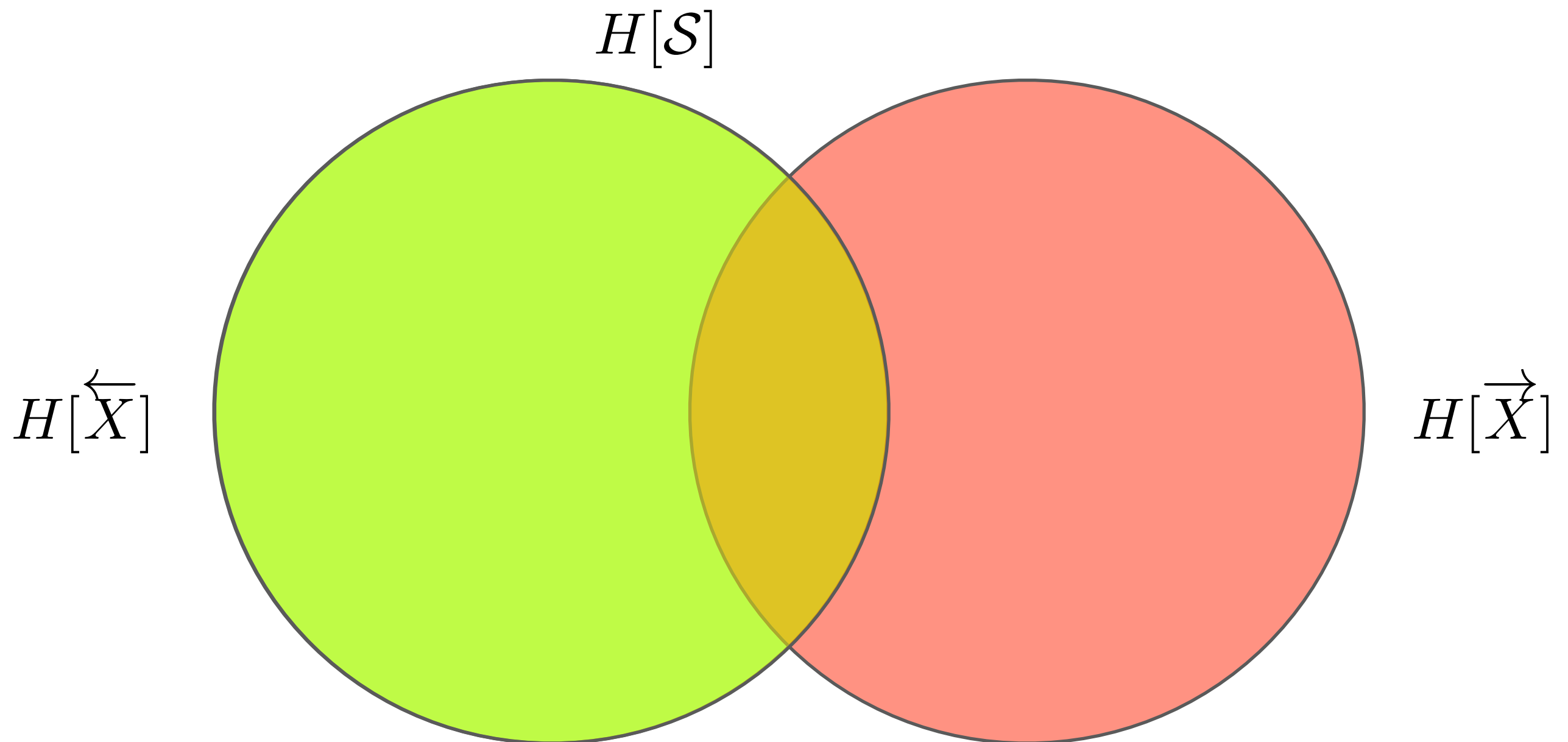
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Process I-diagram using  $\varepsilon$ -machine ...



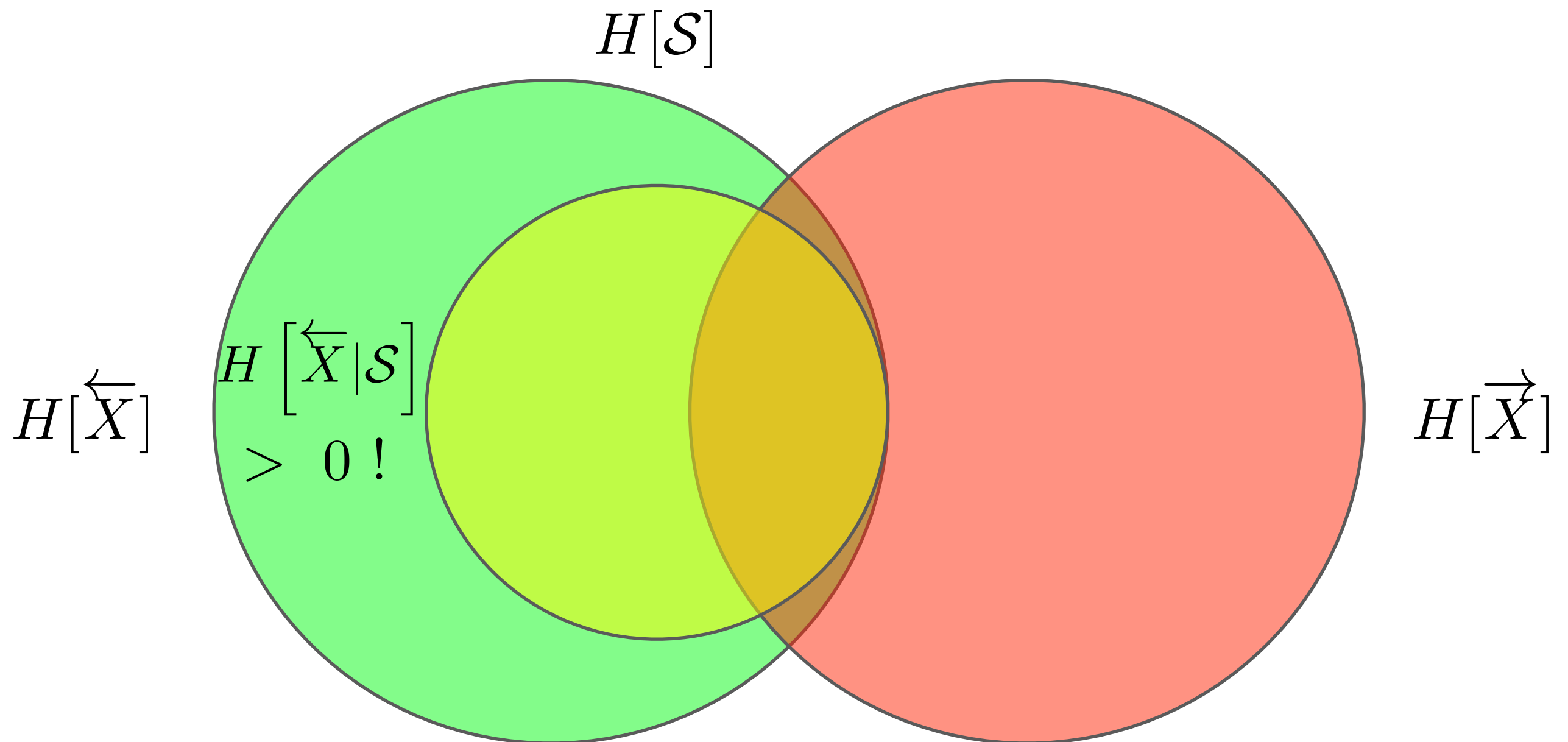
# Information Diagrams for Processes

Process I-diagram using  $\varepsilon$ -machine ...



# Information Diagrams for Processes

## Process I-diagram using $\varepsilon$ -machine ...

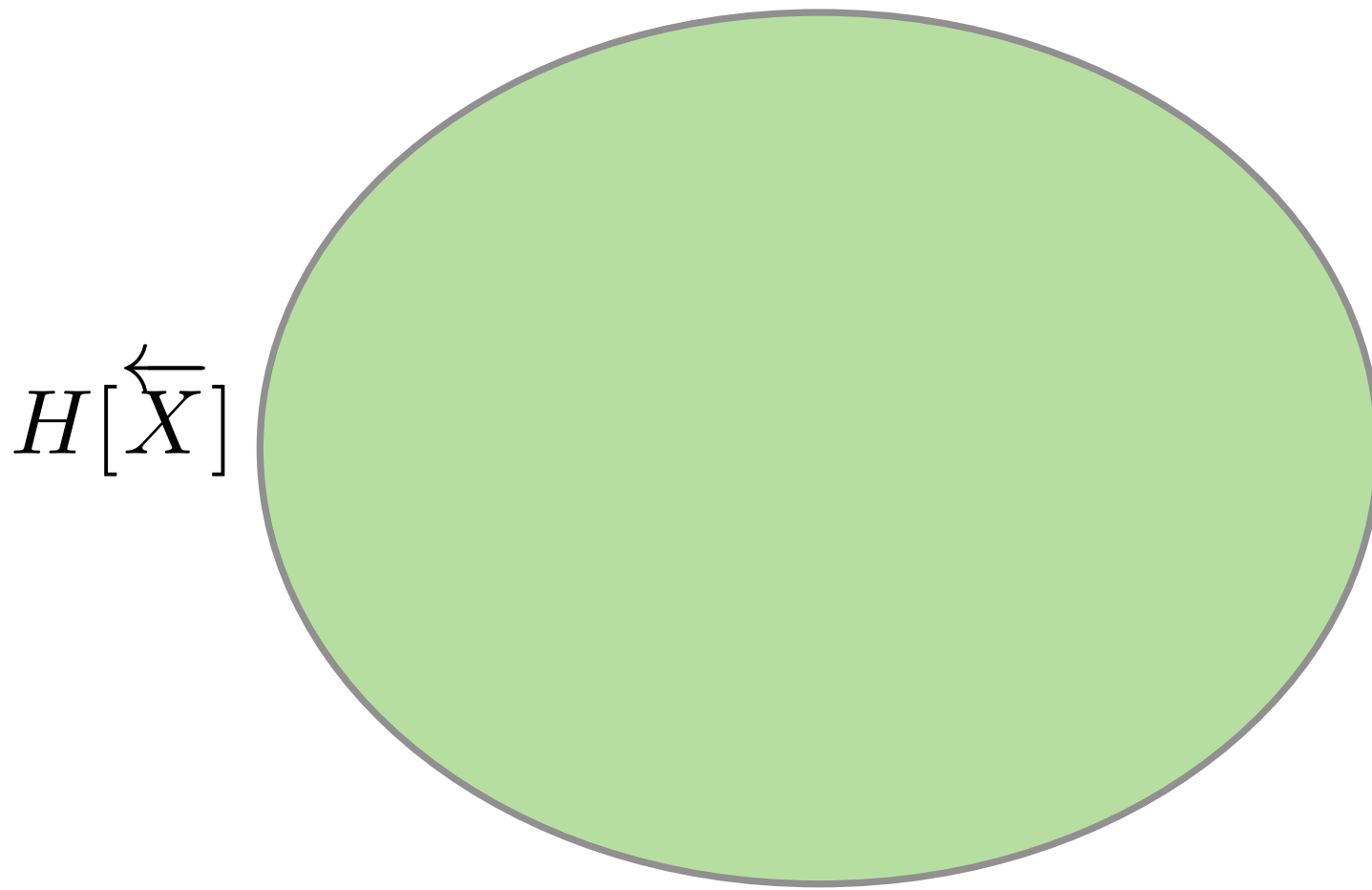


# Information Diagrams for Processes

$\varepsilon$ -Machine I-diagram:

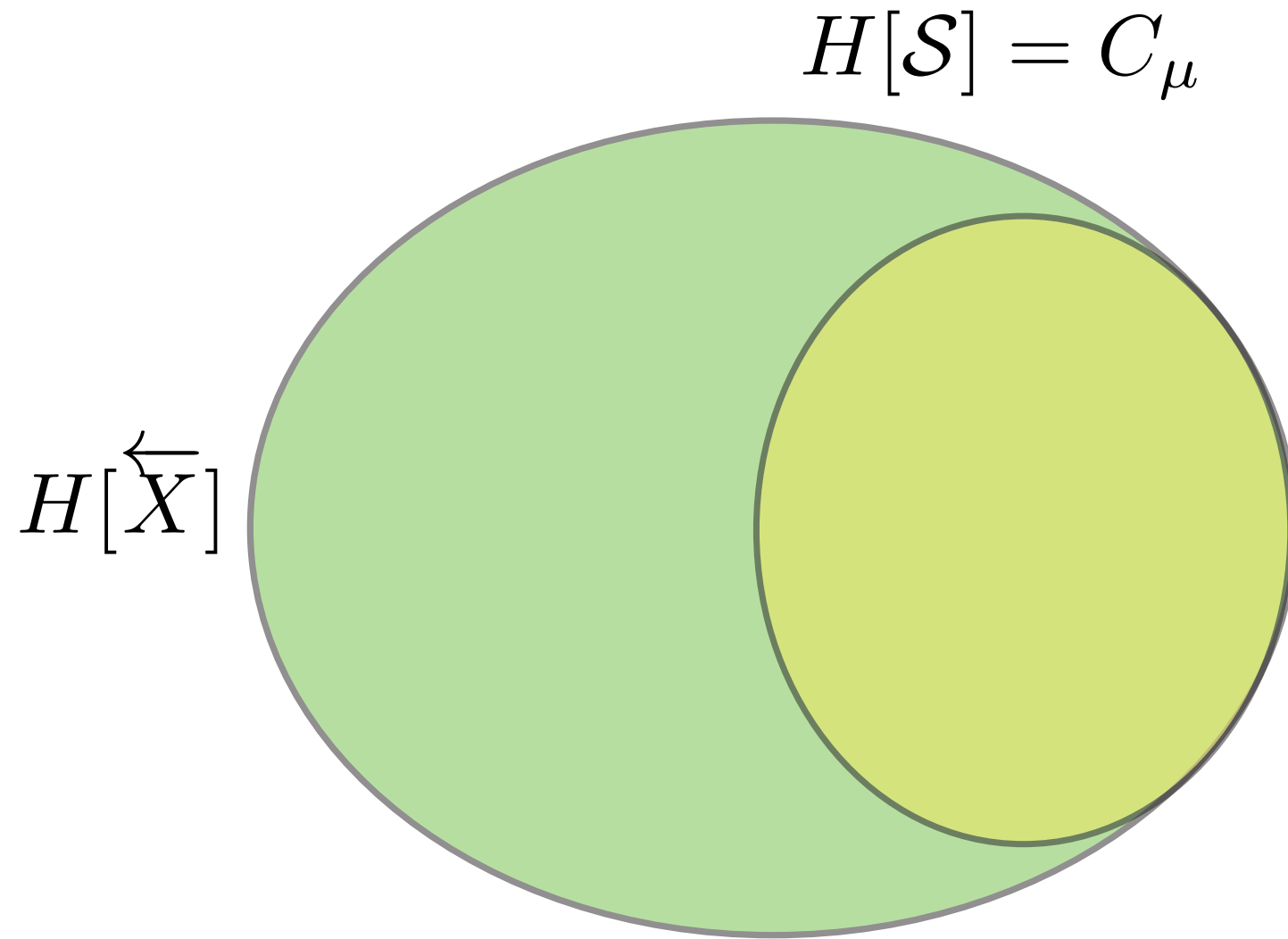
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$\varepsilon$ -Machine I-diagram:



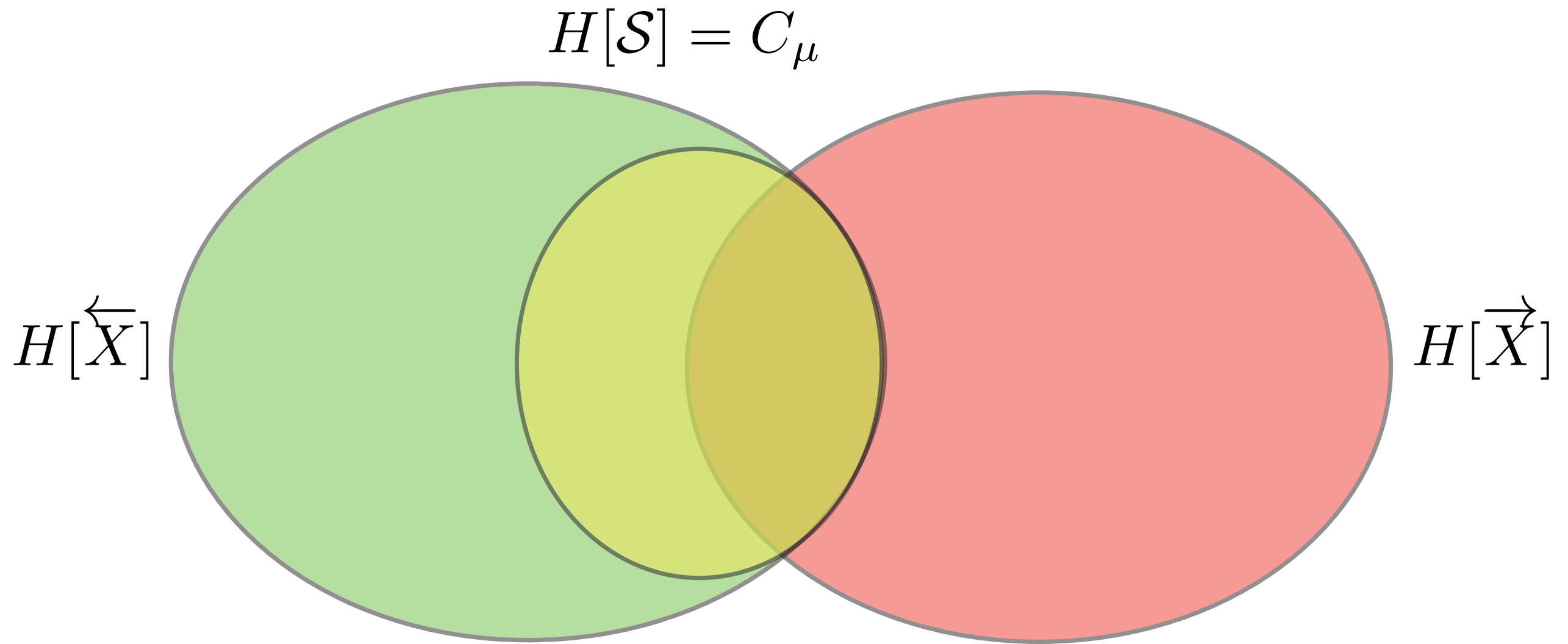
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$\varepsilon$ -Machine I-diagram:



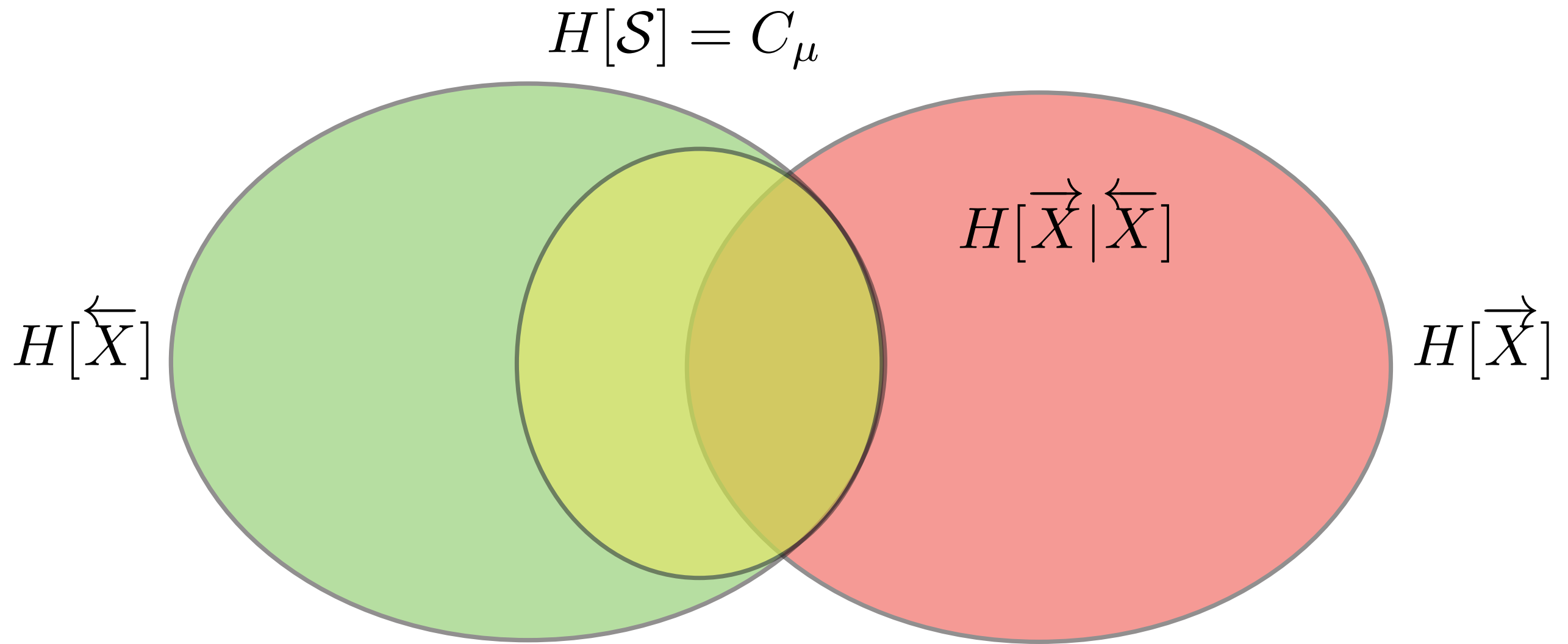
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$\varepsilon$ -Machine I-diagram:



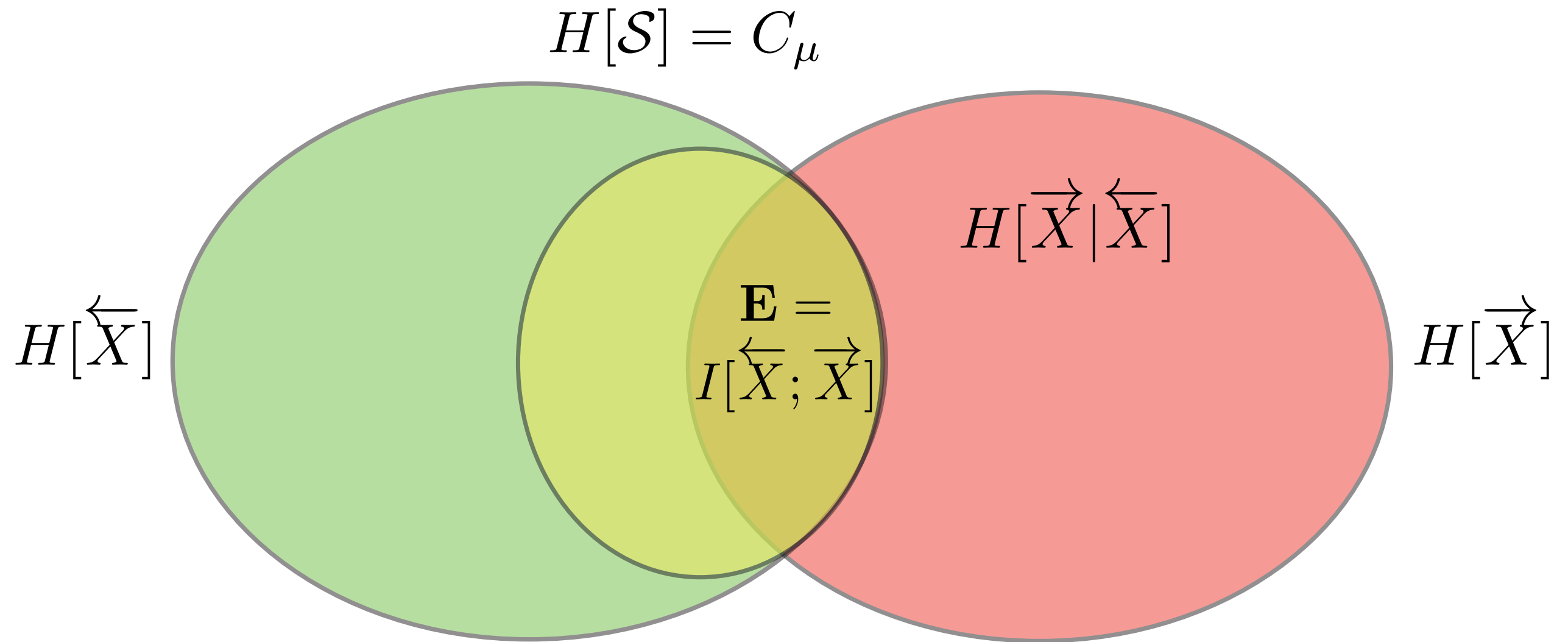
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$\varepsilon$ -Machine I-diagram:



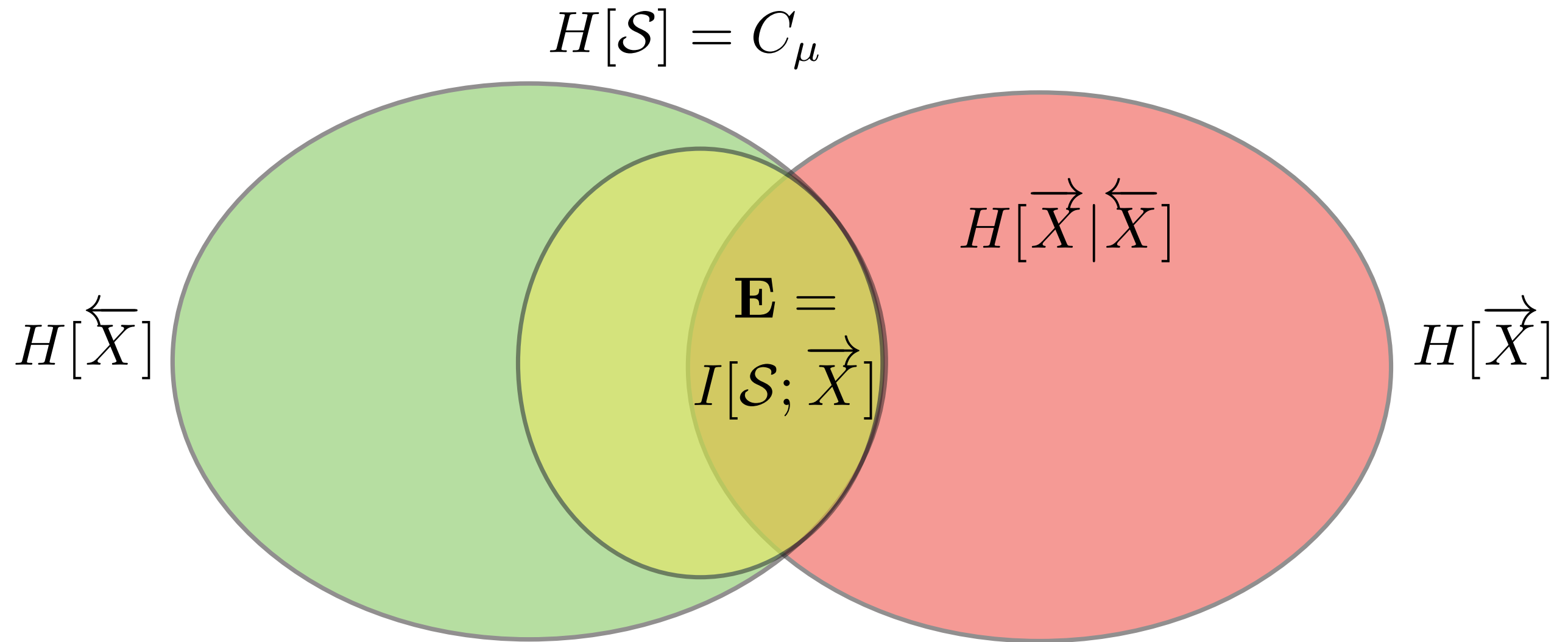
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$\varepsilon$ -Machine I-diagram:



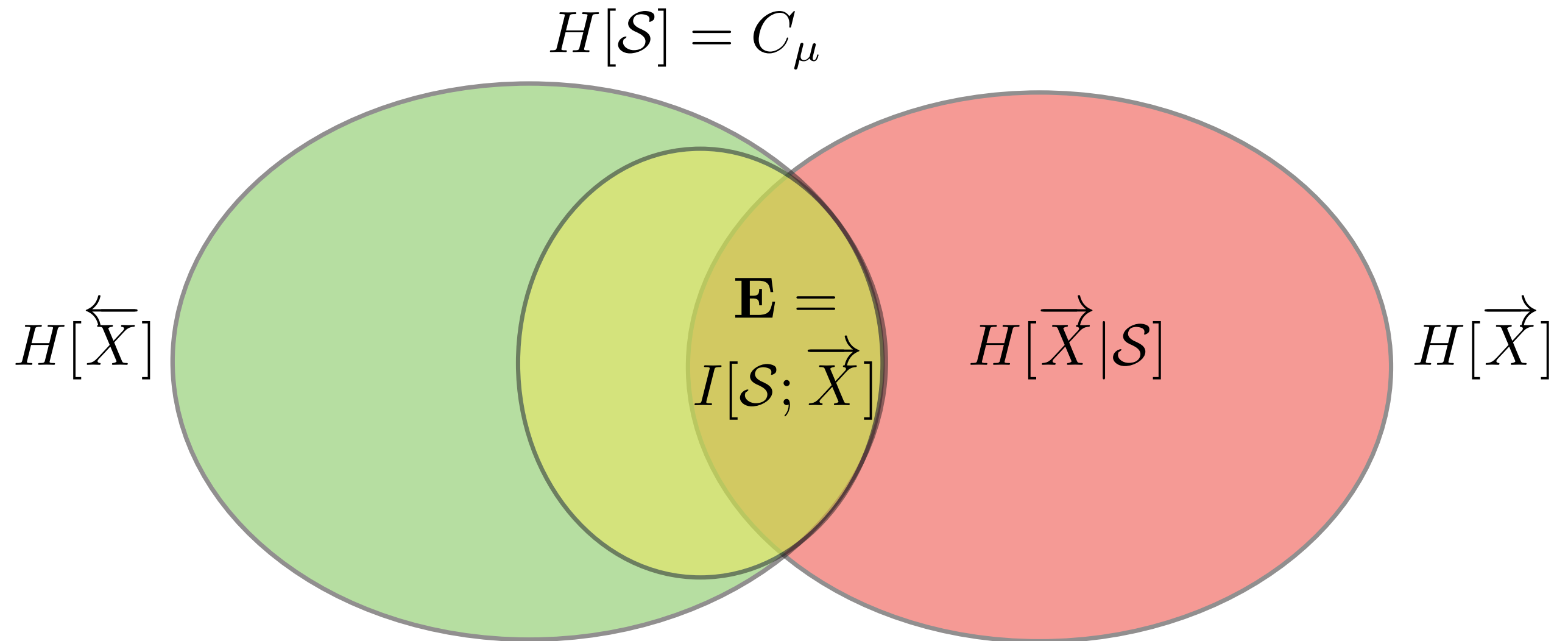
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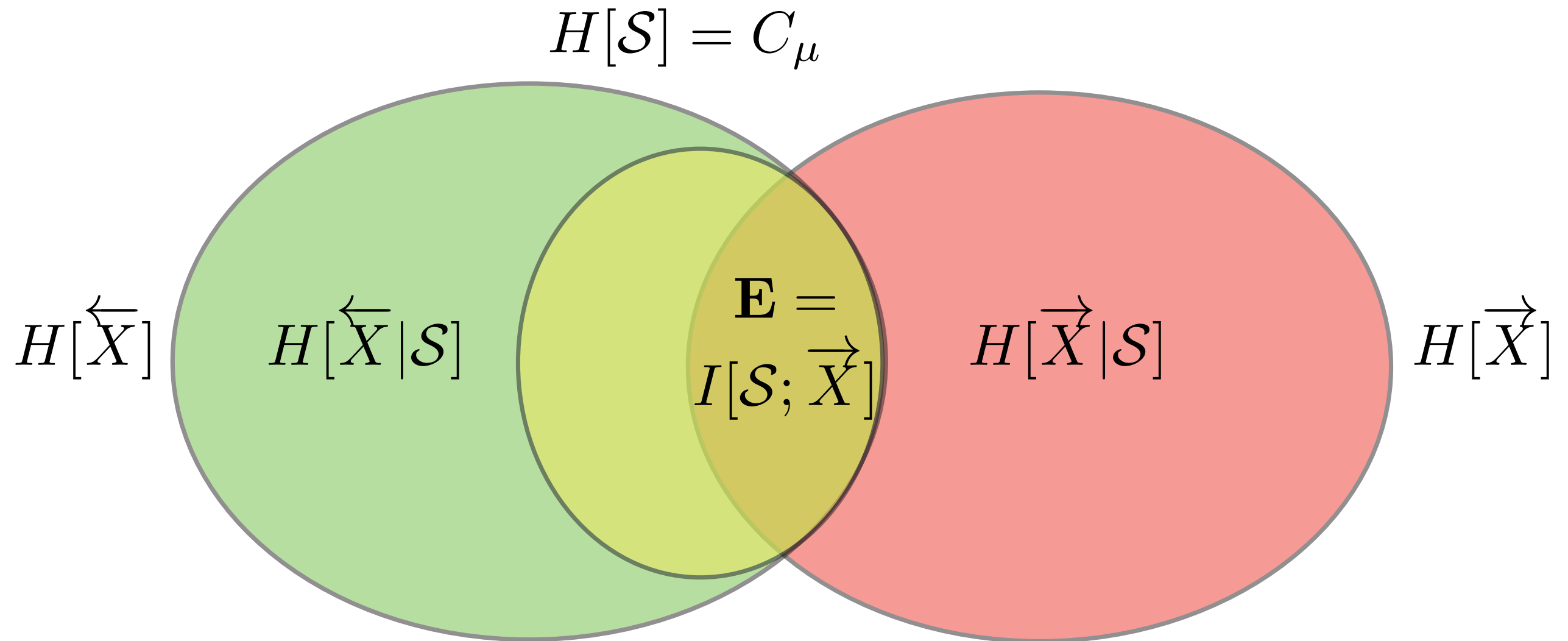
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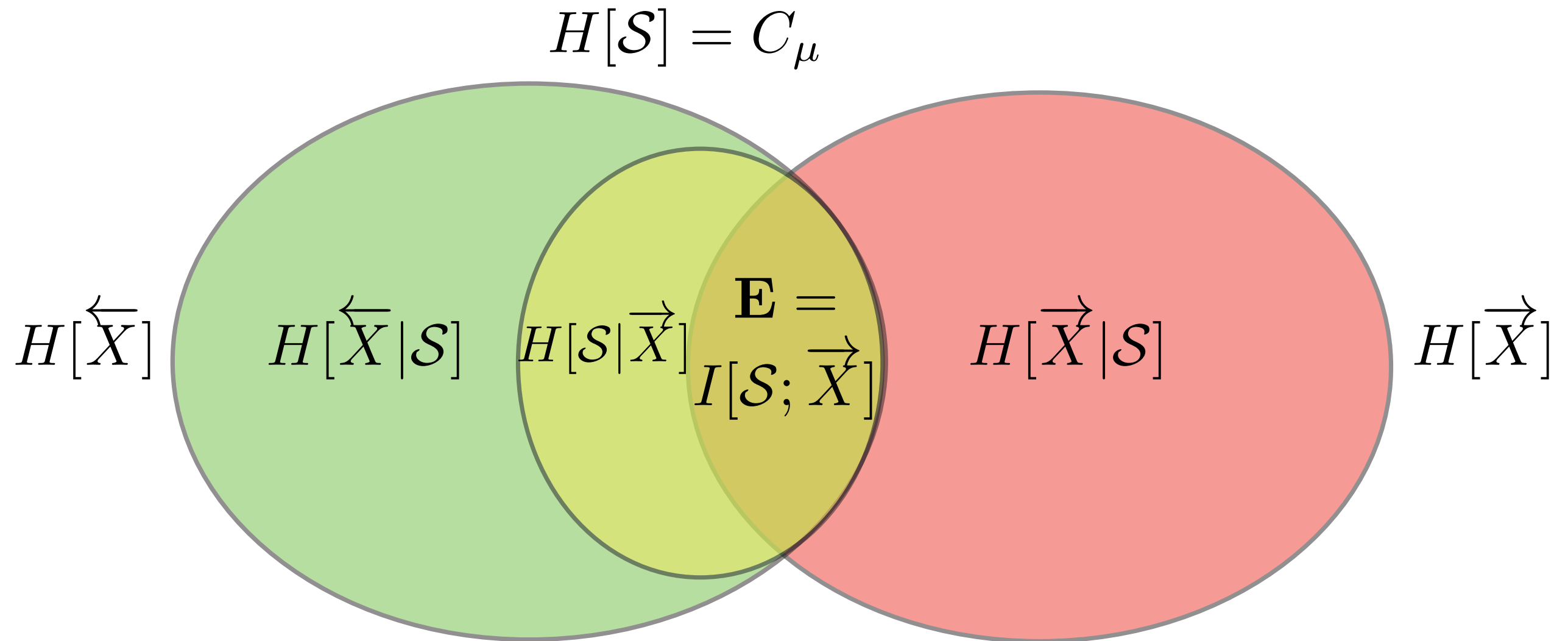
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$\varepsilon$ -Machine I-diagram:



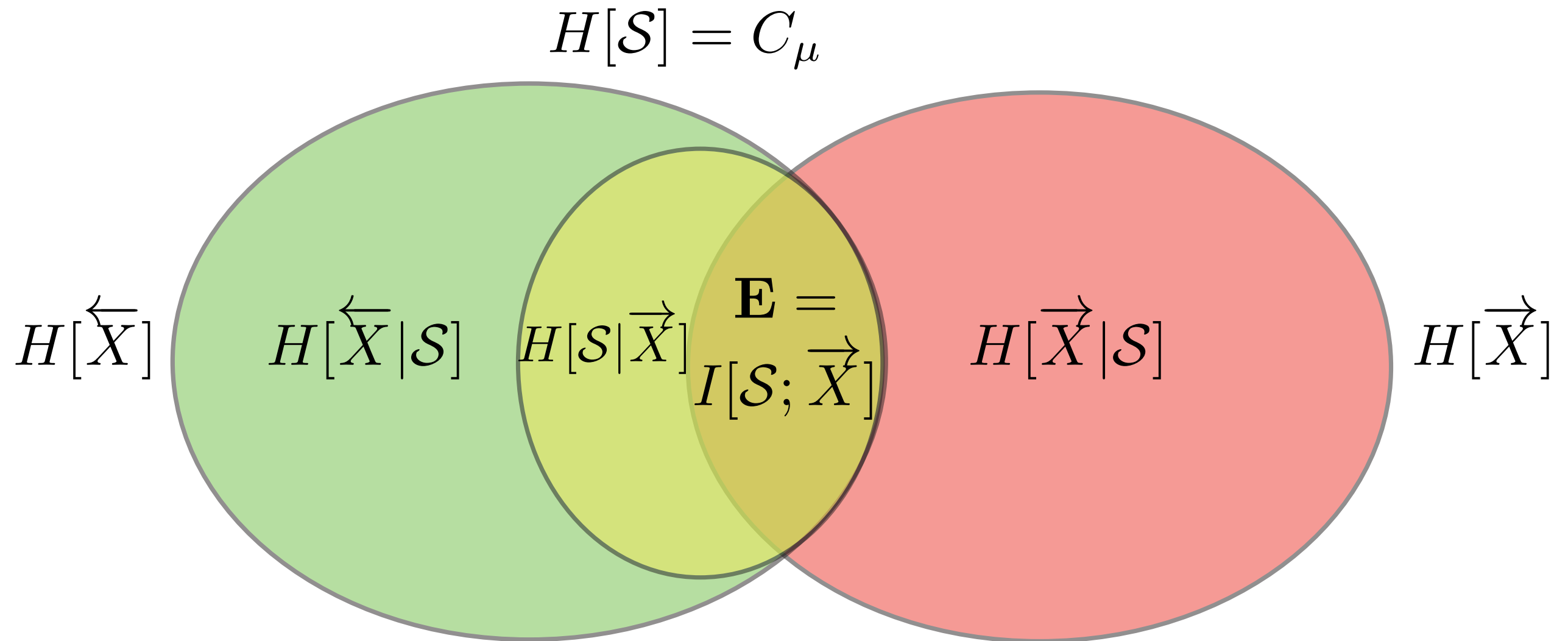
# Information Diagrams for Processes

$\varepsilon$ -Machine I-diagram:



# Information Diagrams for Processes

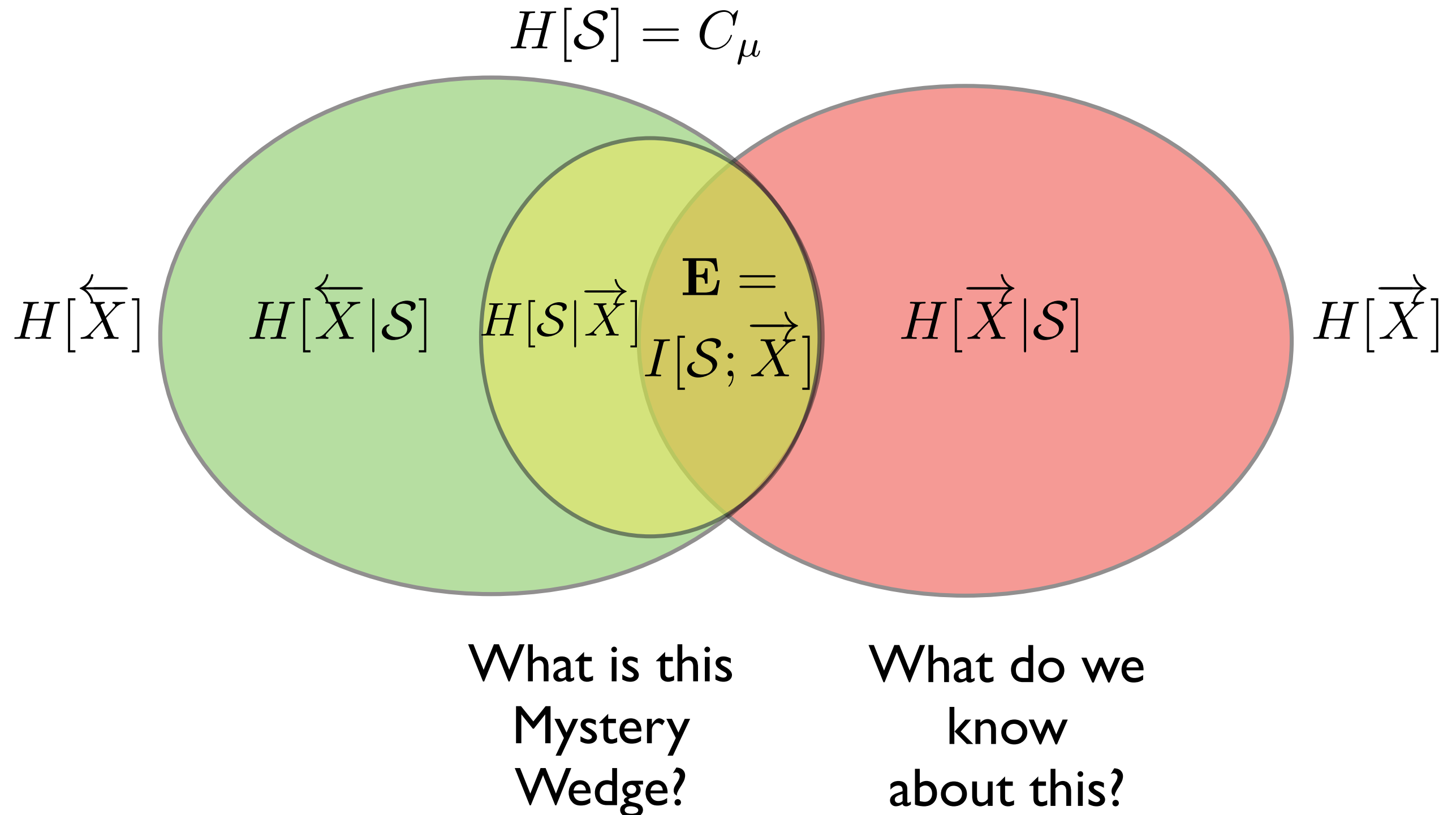
$\varepsilon$ -Machine I-diagram:



What do we  
know  
about this?

# Information Diagrams for Processes

$\varepsilon$ -Machine I-diagram:



# Information Diagrams for Processes

What is  $H[\vec{X}|\mathcal{S}]$ ?

Unpredictability:  $H[\vec{X}^L|\mathcal{S}] = Lh_\mu$

Proof Sketch:

$$\begin{aligned} H[\vec{X}^L|\mathcal{S}] &= H[\vec{X}^L|\overleftarrow{X}] \\ &= H[X_0X_1 \dots X_{L-1}|\overleftarrow{X}] \\ &= H[X_1 \dots X_{L-1}|\overleftarrow{X}X_0] + H[X_0|\overleftarrow{X}] \\ &= H[X_1 \dots X_{L-1}|\overleftarrow{X}] + H[X_0|\overleftarrow{X}] \\ &\vdots \\ &= H[X_{L-1}|\overleftarrow{X}] + \dots + H[X_1|\overleftarrow{X}] + H[X_0|\overleftarrow{X}] \\ &= LH[X_0|\overleftarrow{X}] \\ &= Lh_\mu \end{aligned}$$

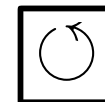
# Information Diagrams for Processes

What is Mystery Wedge?  $H[\mathcal{S}|\vec{X}]$

Uncertainty of causal state given future. Implications?

Recall Bound on Excess Entropy:  $\mathbf{E} \leq C_\mu$

$$\begin{aligned}\text{Proof sketch: } \mathbf{E} &= I[\overleftarrow{X}; \vec{X}] \\ &= H[\vec{X}] - H[\vec{X}|\overleftarrow{X}] \\ &= H[\vec{X}] - H[\vec{X}|\mathcal{S}] \\ &= I[\vec{X}; \mathcal{S}] \\ &= H[\mathcal{S}] - H[\mathcal{S}|\vec{X}] \\ &\leq H[\mathcal{S}] \\ &= C_\mu\end{aligned}$$



# Information Diagrams for Processes

What is Mystery Wedge?  $H[\mathcal{S}|\vec{X}]$

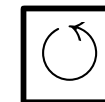
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I am the  
Mystery Wedge!



# Information Diagrams for Processes

What is Mystery Wedge?  $H[S|\vec{X}]$

Wedge is the inaccessibility of hidden state information!

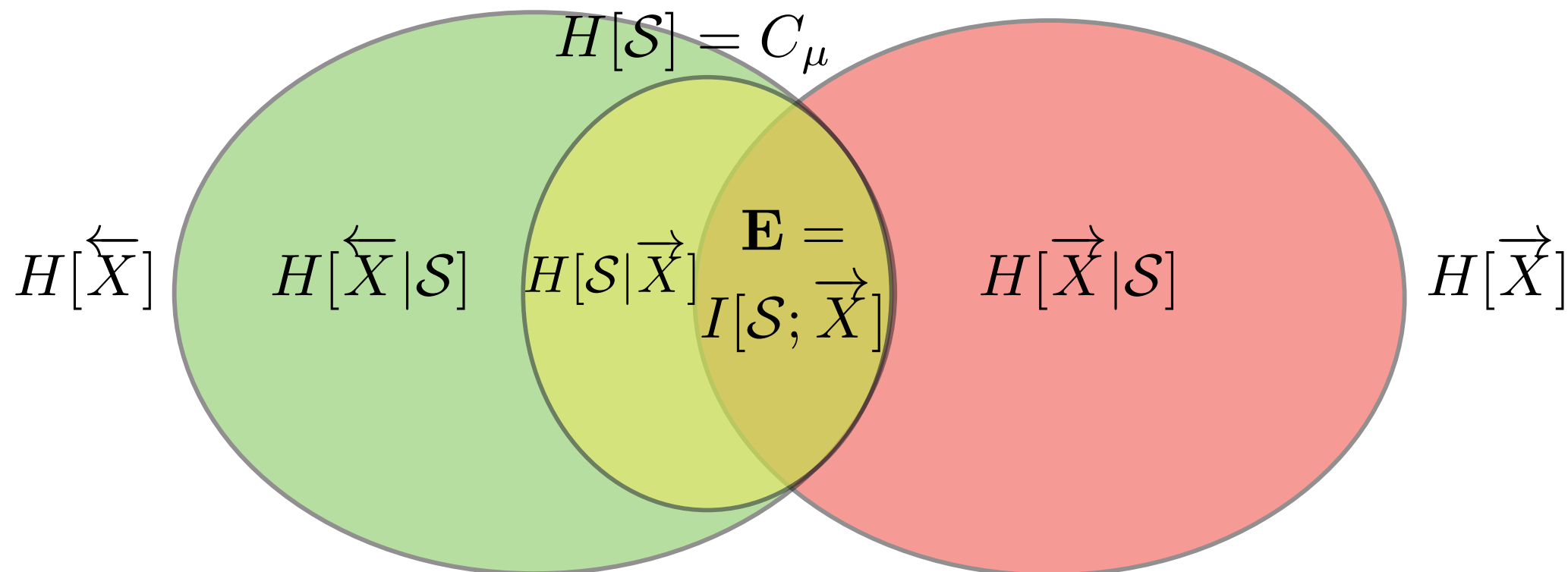
$$H[S|\vec{X}] = C_\mu - \mathbf{E}$$

Wedge controls Internal - Observed

The **Process Crypticity**:

$$\chi = C_\mu - \mathbf{E}$$

Controls how much internal state information is observable.



# How to get $\mathbf{E}$ from $\epsilon M$ ?

# DIRECTIONAL COMPUTATIONAL MECHANICS

- Theorem:

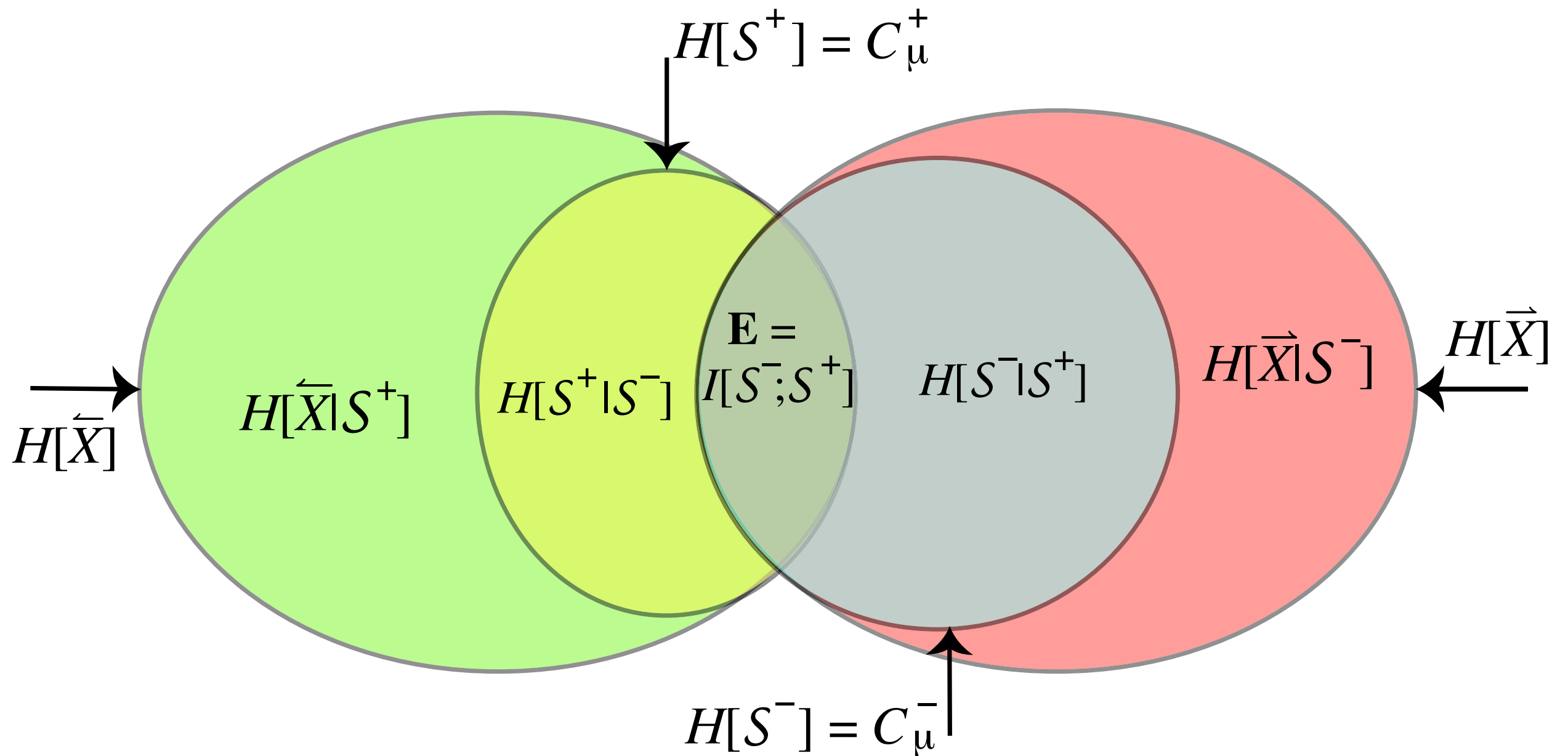
$$\mathbf{E} = I[\mathcal{S}^+; \mathcal{S}^-]$$

- Effective transmission capacity of channel between forward and reverse processes.
- Time agnostic representation: The **BiMachine**.

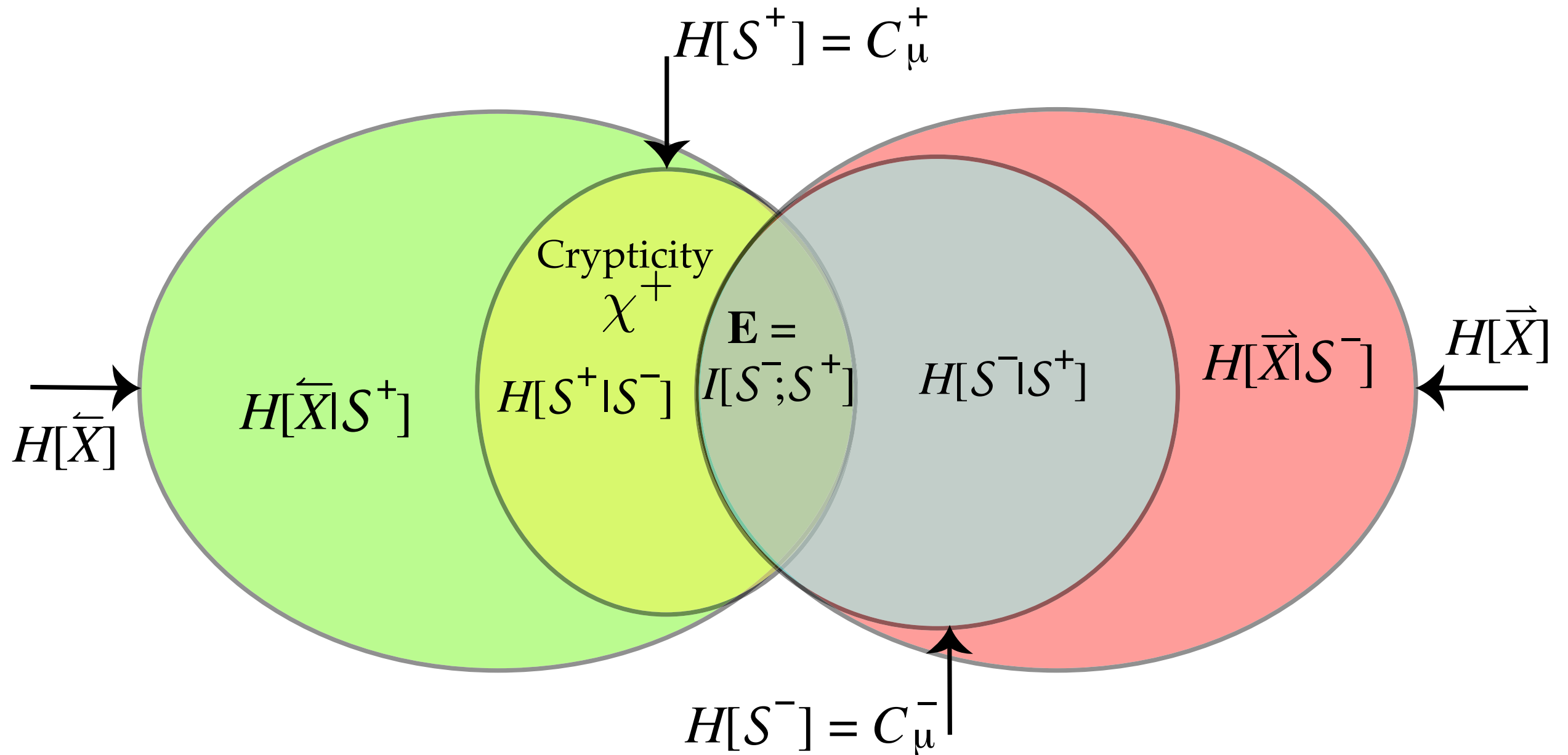
J. P. Crutchfield, C. J. Ellison, and J. R. Mahoney, “Time's Barbed Arrow: Irreversibility, Crypticity, and Stored Information”, Physical Review Letters **103**:9 (2009) 094101.

Complexity Lecture 2: Intrinsic Computation (CSSS 2013) Jim Crutchfield

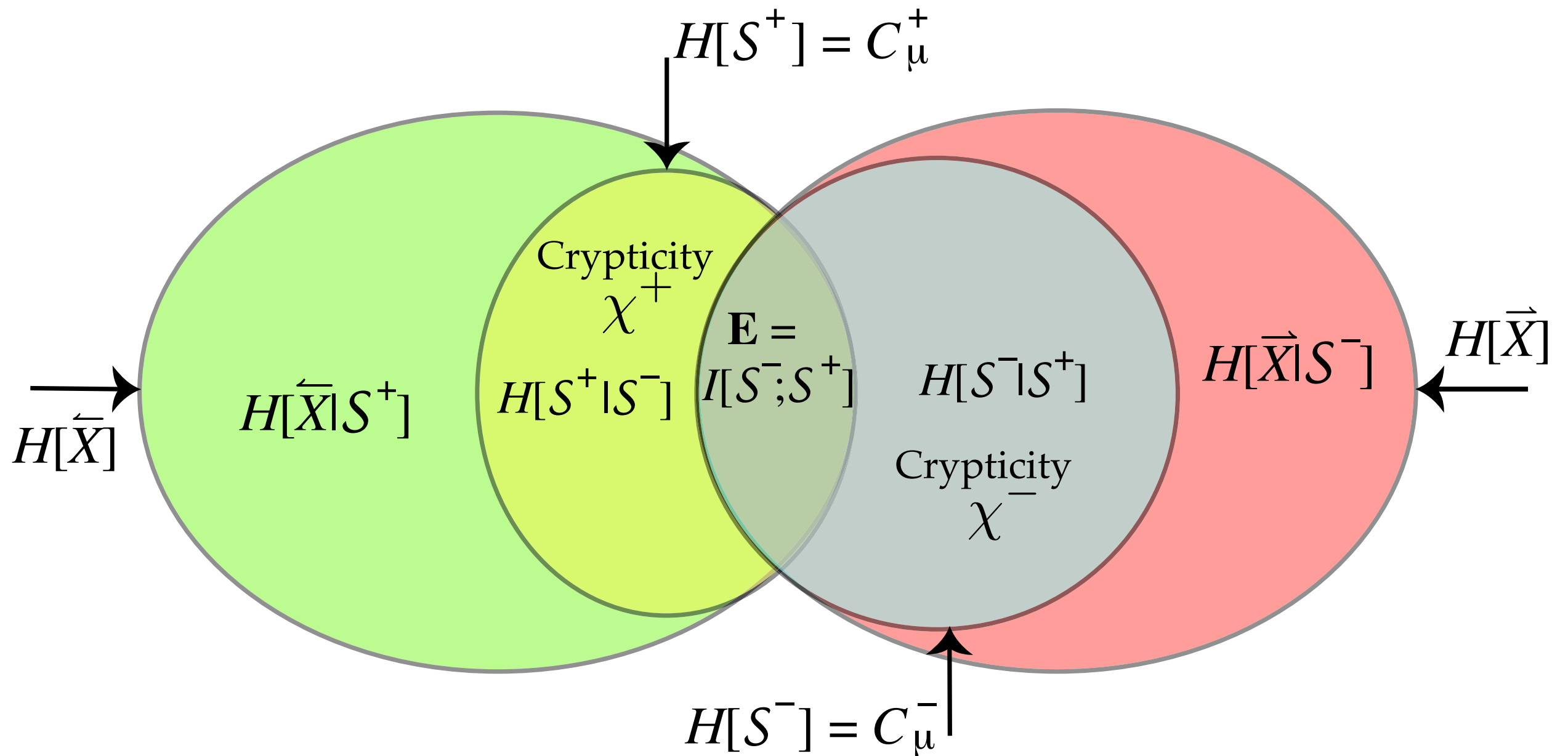
# Forward-Reverse $\varepsilon$ -Machine Information Diagram



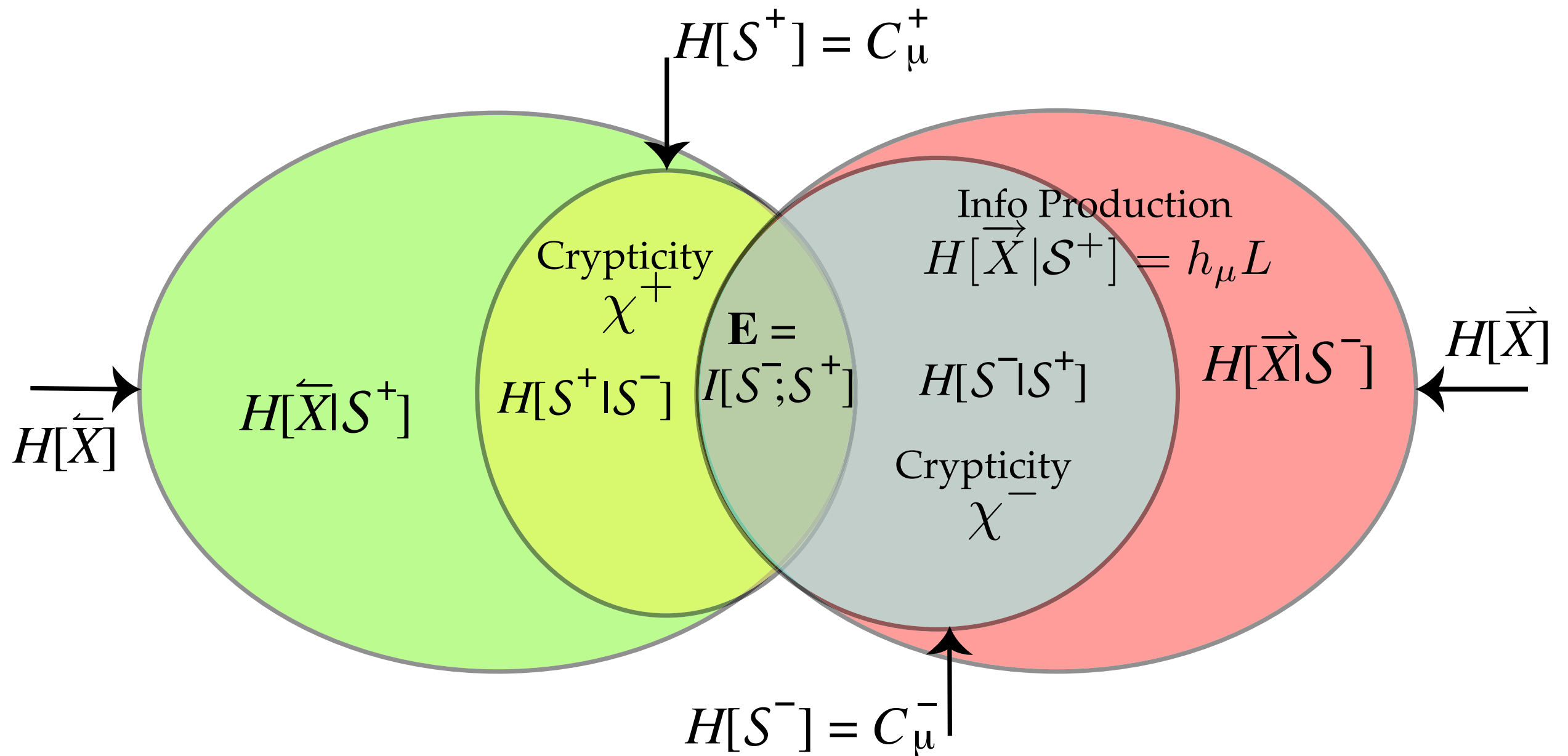
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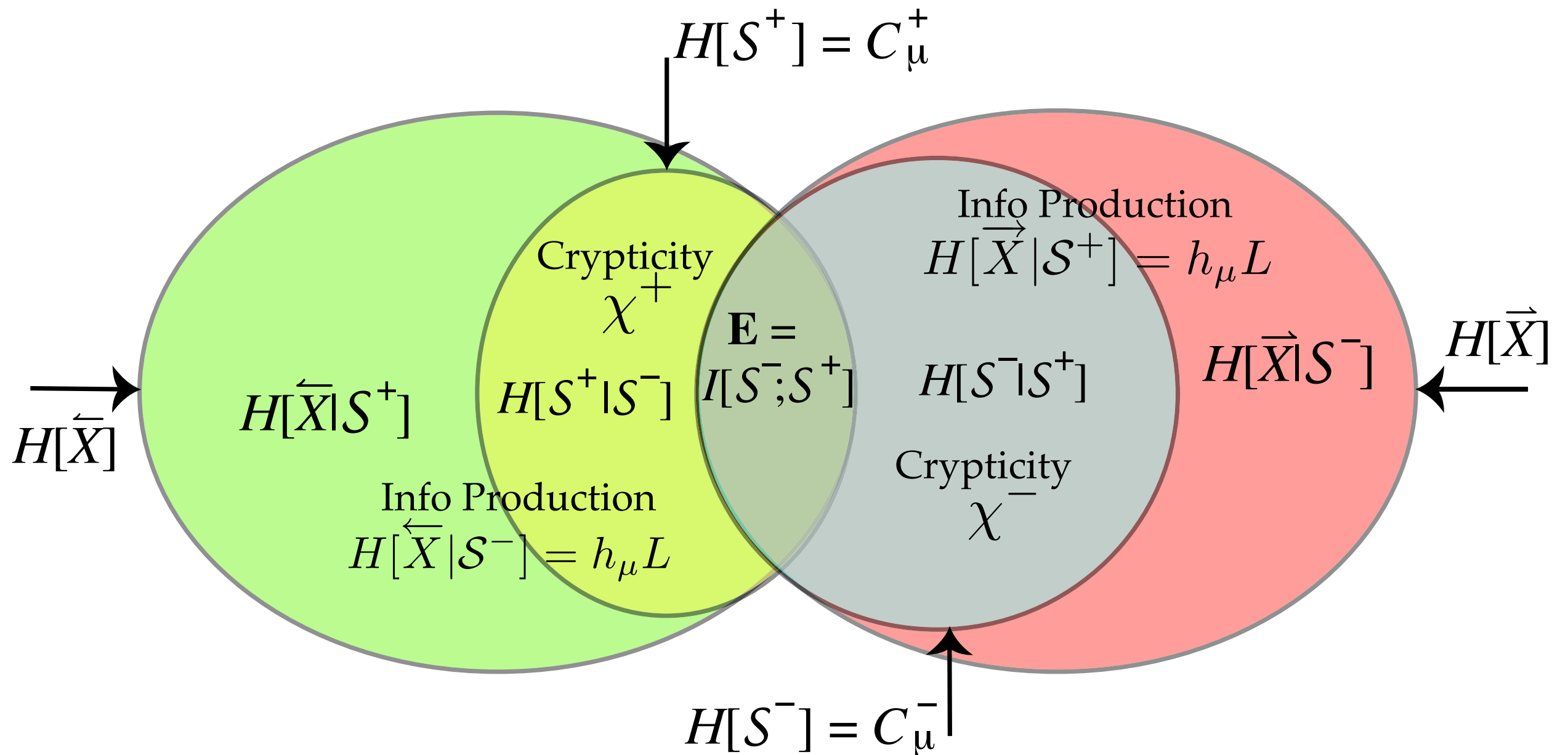
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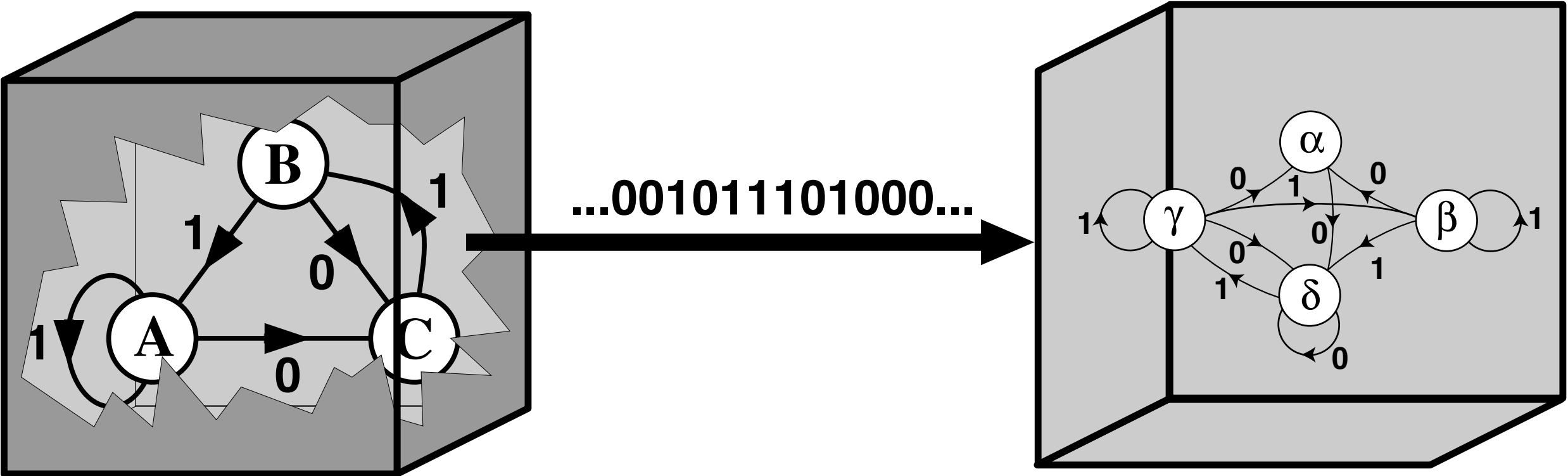


# Forward-Reverse $\varepsilon$ -Machine Information Diagram



# Intrinsic Computation ...

Analysis narrative:



**System**

**Instrument**

**Process**

**Modeller**

Forms of Chaos:  
Deterministic sources  
of novelty  
Mechanisms that produce  
unpredictability  
Sensitive dependence on  
initial condition  
Sensitive dependence on  
parameter

Measurement Theory:  
Partitions  
Optimal Instrument:  
 $\max_{\{P\}} h_{\mu}$   
 $\min_{\{P\}} C_{\mu}$

How random?  
 $\lambda, H(L), h_{\mu}$   
How structured?  
 $C_{\mu}, E, T, G, \mathcal{R}$

Universal model:  
 $\epsilon$  – Machine  
Pattern defined  
Causal Architecture  
Intrinsic Computation

# Intrinsic Computation ...

A system is **unpredictable**

if it has positive entropy rate:  $h_\mu > 0$

A system is **complex**

if it has positive structural complexity measures:  $C_\mu > 0$

A system is **emergent**

if its structural complexity measures increase over time:

$$C_\mu(t') > C_\mu(t), \text{ if } t' > t$$

A system is **hidden**

if its crypticity is positive:  $\chi > 0$

# Complexity!

Thursday: Information Theory for Complex Systems

Complex Processes

Information & Memory in Processes

Interactive Labs: Nix

Friday: Intrinsic Computation

Measuring Structure

Intrinsic Computation

Optimal Models

Interactive Labs: Nix

See online course:

<http://csc.ucdavis.edu/~chaos/courses/ncaso/>