

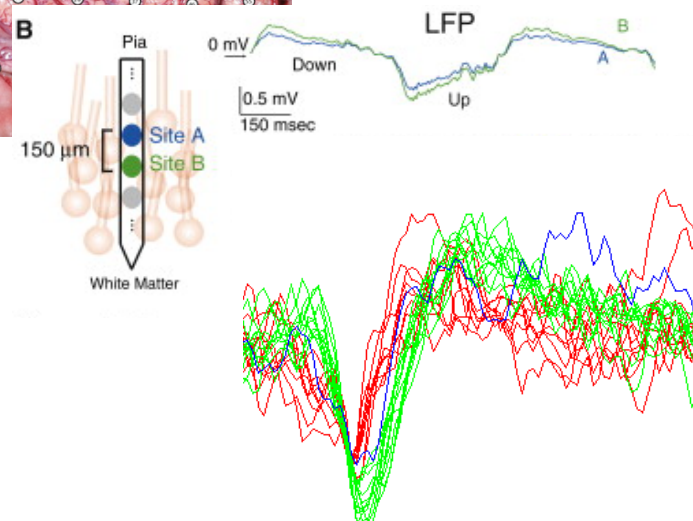
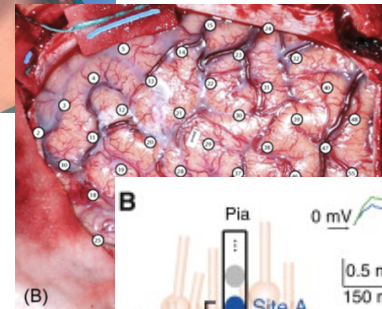
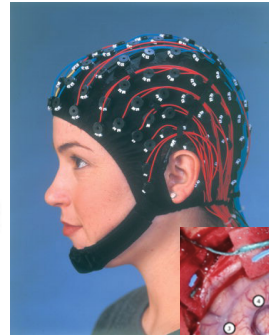
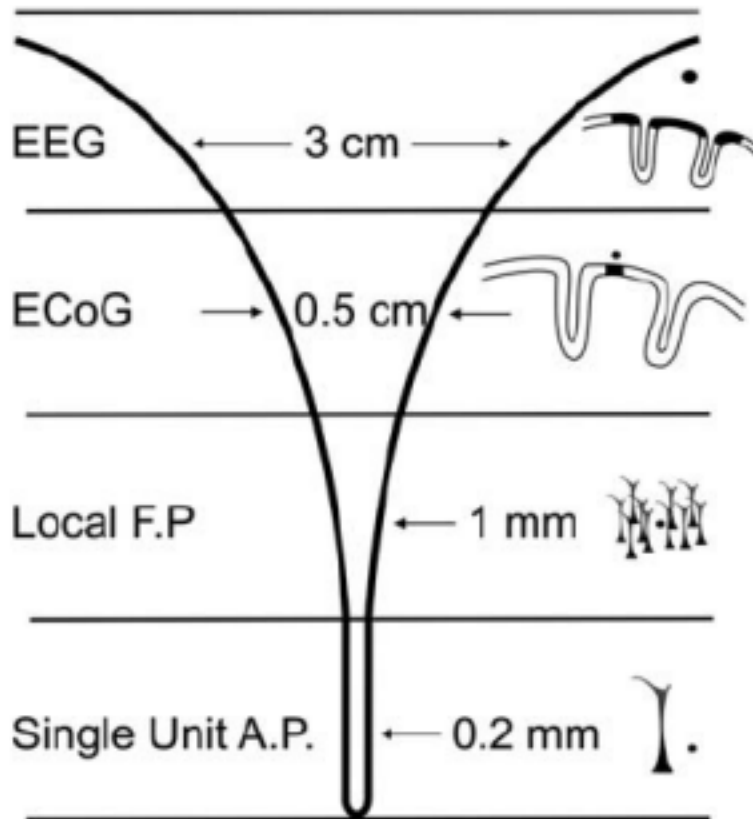
Information in Phase of Low Frequency Motor Cortex Generated Actions

Preeya Khanna

ComplexFest: June 1, 2013

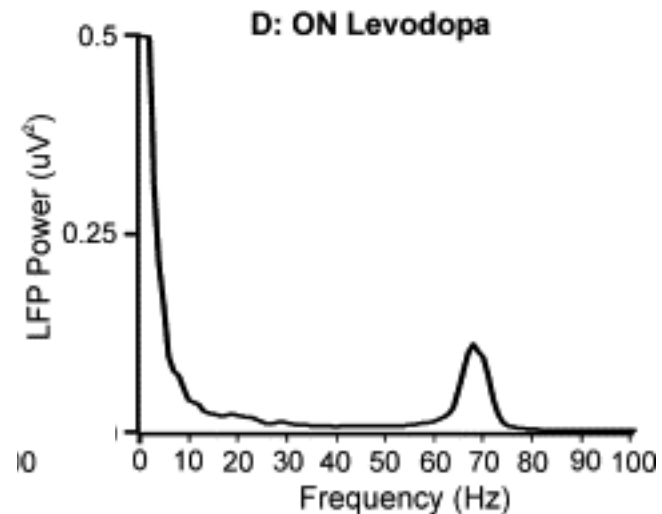
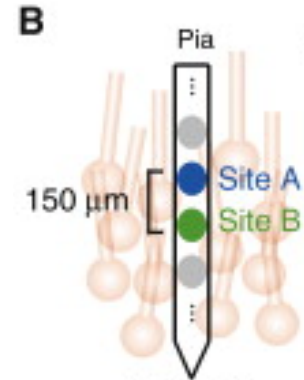
Neural Recordings

Recorded neural activity spatial domains



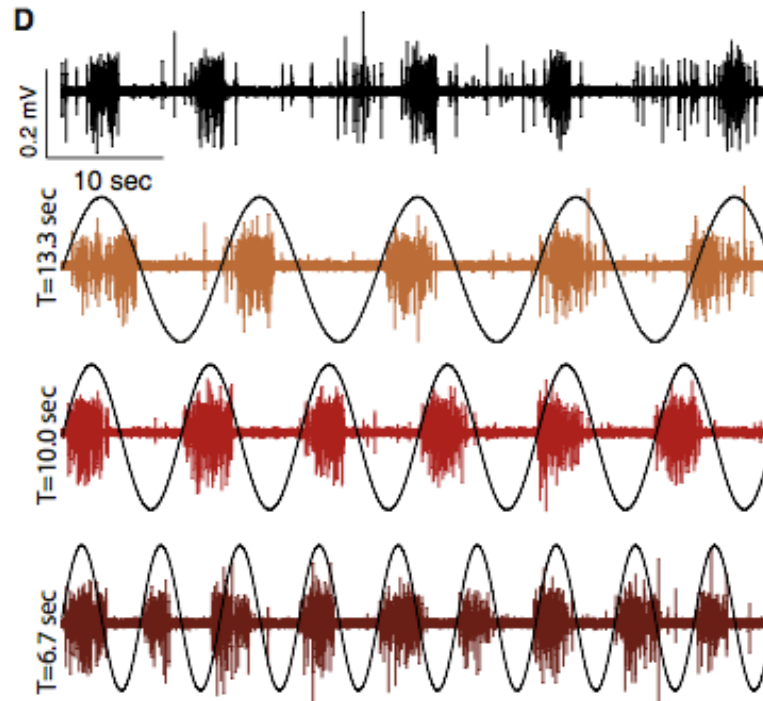
Local Field Potentials

- Extracellular Potentials
 - Synaptic Input to cells
- Slow Oscillatory Components of LFP
 - $1/f$ pattern
 - Low Frequency Bands
 - Delta (0.5 – 4 Hz)
 - Alpha (4 – 8 Hz)
 - Theta (8 -12 Hz)
 - Beta (15-40 Hz)
 - Gamma (40 – 60 Hz)
 - High Gamma (60 – 300 Hz)



LFP / Spike Interactions

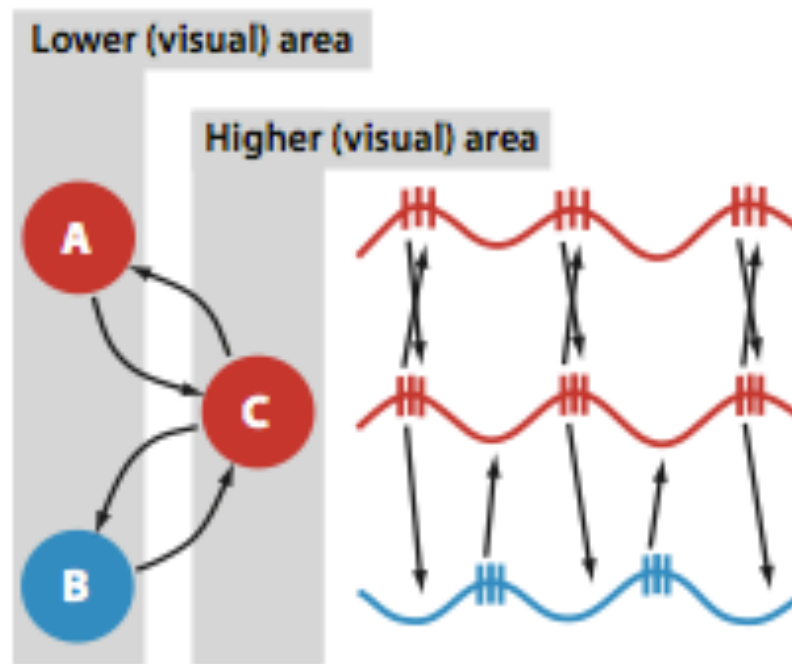
- In slice spikes lock to a preferred phase of oscillation from applied electric field



- Questions: Is there information in the LFP? Does it represent summed ensemble activity? Does it play a role in information processing in the brain?

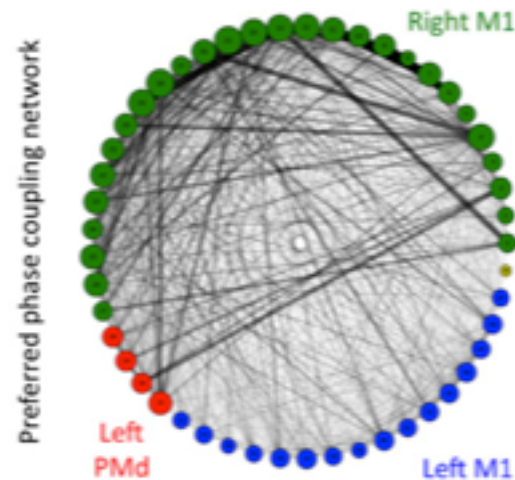
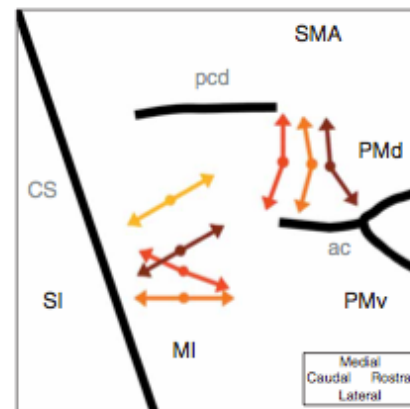
Role of Phase-Locking

- Enables communication through modulation of coherence
- Modulation of coherence 'opens the window' for processing spikes from lower areas



Phase in Motor Cortex

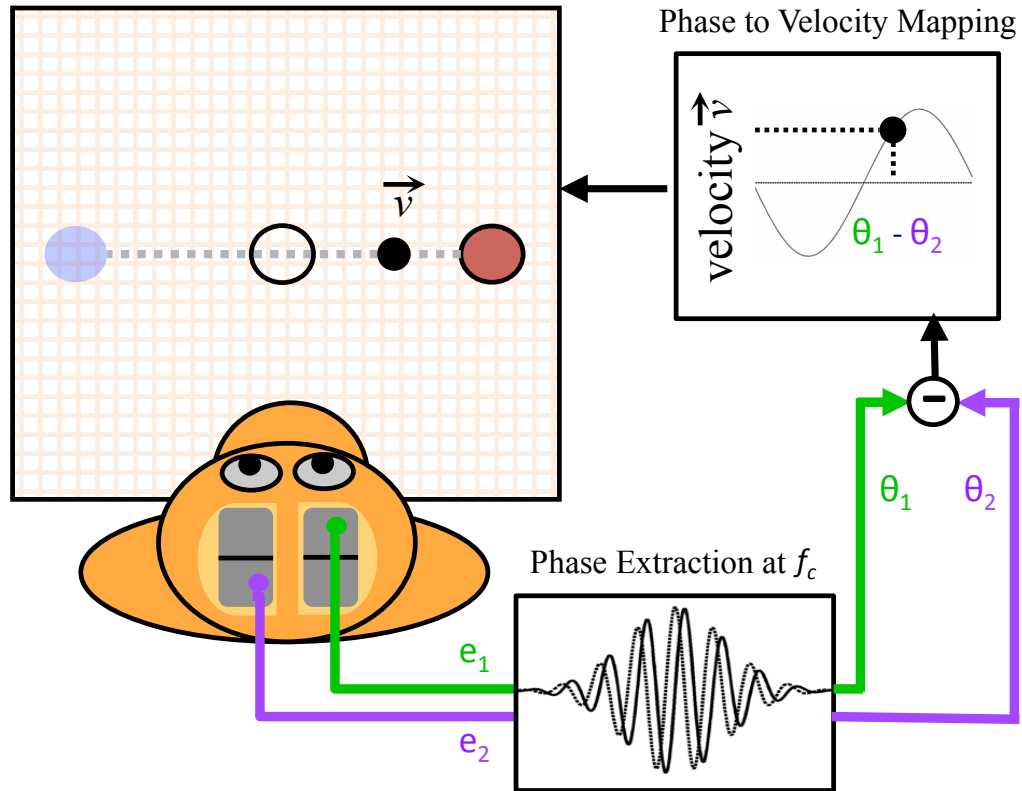
- Rubino & Hatsopolous (2006)
 - Calculated Beta Phase gradient before 'Go' cue
 - Rippling beta waves through PMd, M1
- Canolty et. al (2010)
 - Phase-coupling networks to predict spiking
 - Distal LFPs and LFP-LFP coupling
- Fetz (2013)
 - Oscillations are result of attention

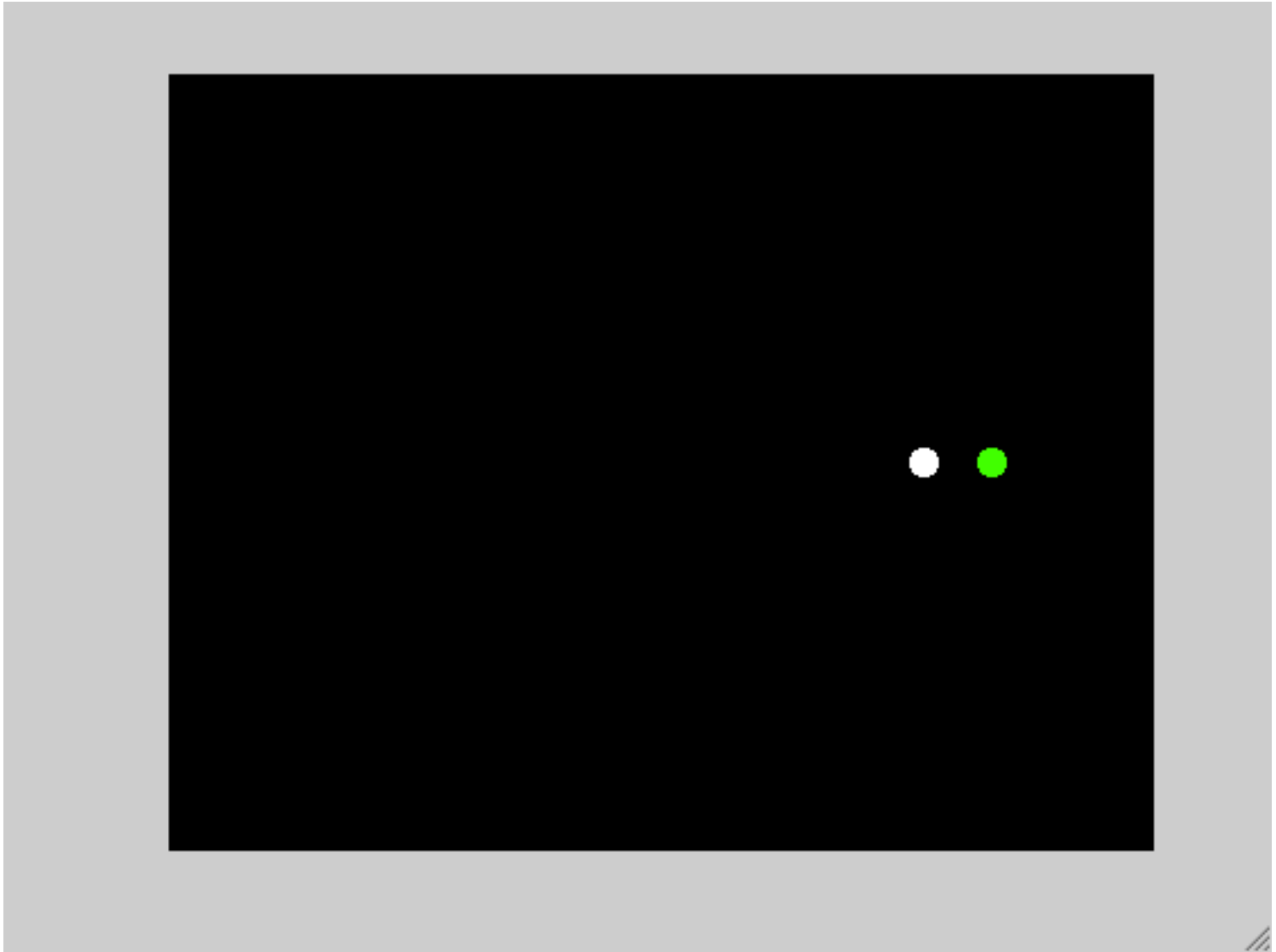


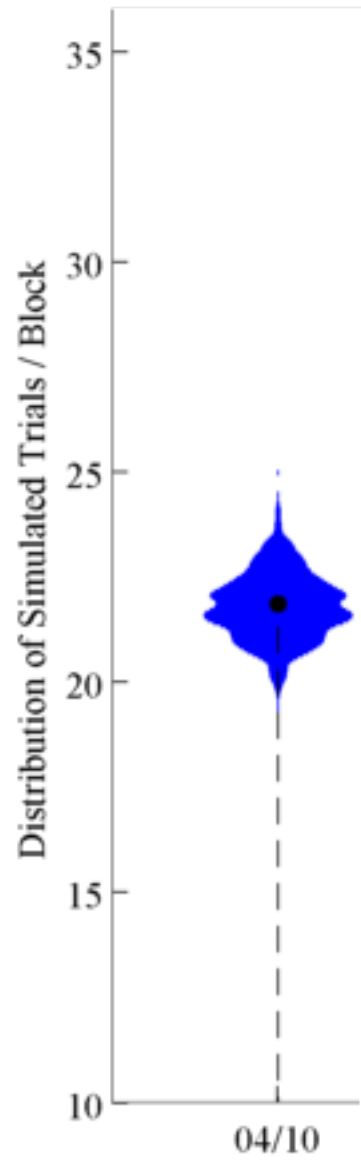
One Approach: Phase-BMI

- Brain – Machine Interface task controlled by phase differences
- Question: Can subjects volitionally modulate phase differences?
- If so, can be used as a useful paradigm to study oscillations?

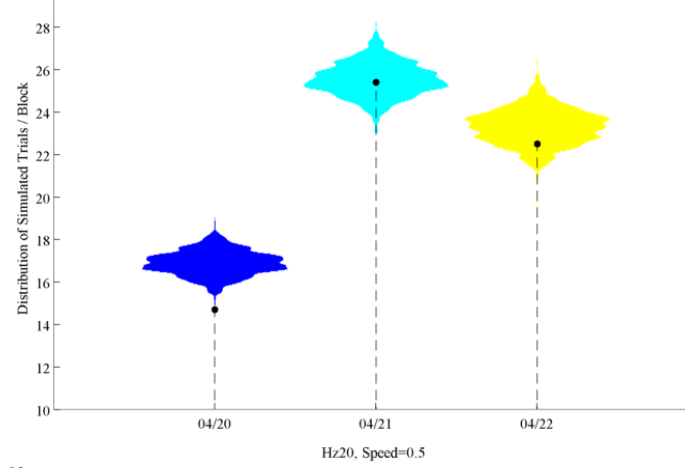
BMI Task



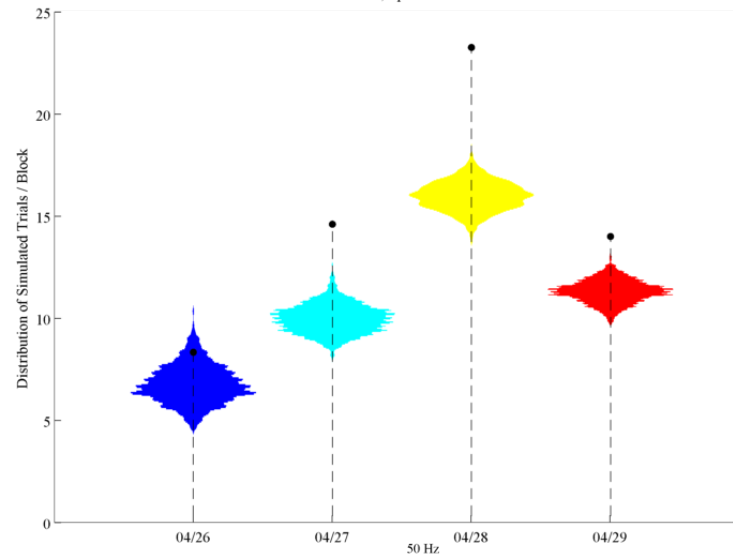




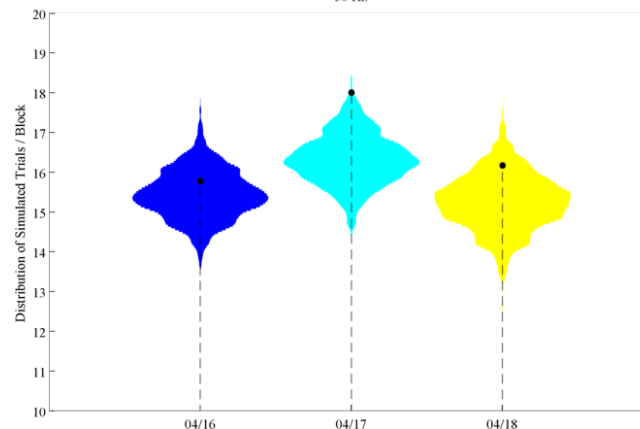
- 10 Hz



- 20 Hz

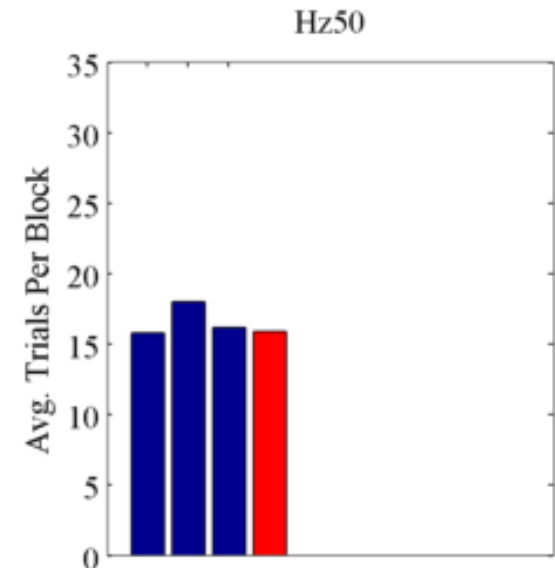
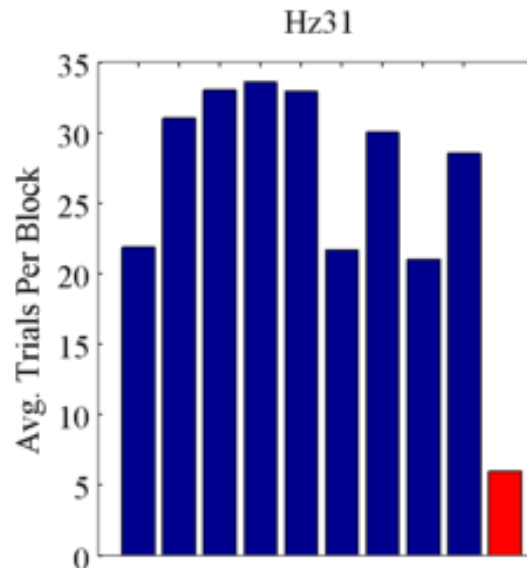
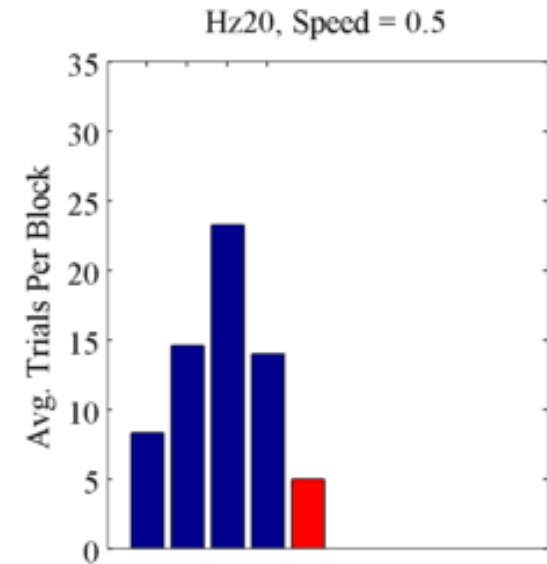
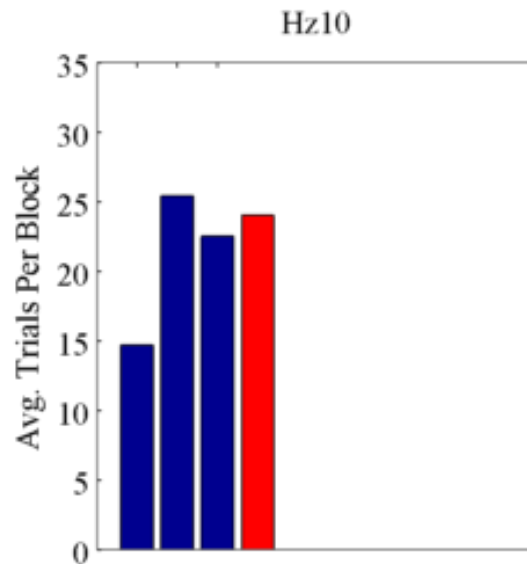


- 50 Hz



Other Chance Calculations

- Avg. Trials Per Block vs. Screen Off



Transition to Modeling

- Questions:
 - How is he doing this?
 - What are the differences between moving left, right, and baseline when he excels at the task?
- Approaches
 - Coupled Oscillator Model
 - With Phase Resetting Curve
 - Comparison of Epsilon Machines for Left/Right Conditions

Coupled Oscillator Model

$$\frac{\partial}{\partial t} \theta_1(t) = \omega - \kappa_{12} \sin(\theta_1 - \theta_2 - \mu_{12}) + v_1(t)$$

$$\frac{\partial}{\partial t} \theta_2(t) = \omega - \kappa_{12} \sin(\theta_2 - \theta_1 - \mu_{12}) + v_2(t)$$

ω = center frequency

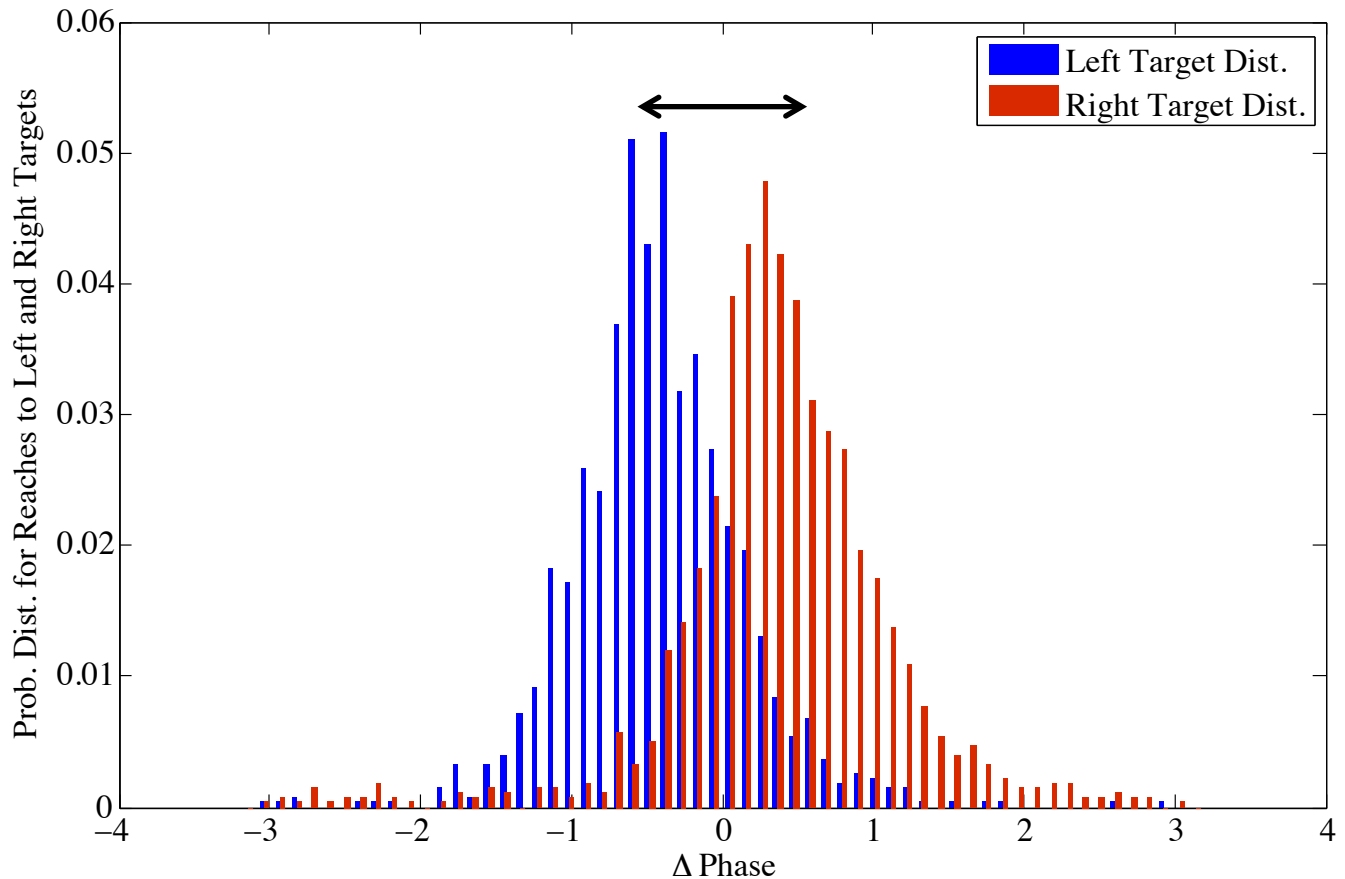
κ_{12} = coupling strength between two oscillators

μ_{12} = intrinsic preferred phase between two oscillators

$v_i(t)$ = zero-mean Gaussian noise term

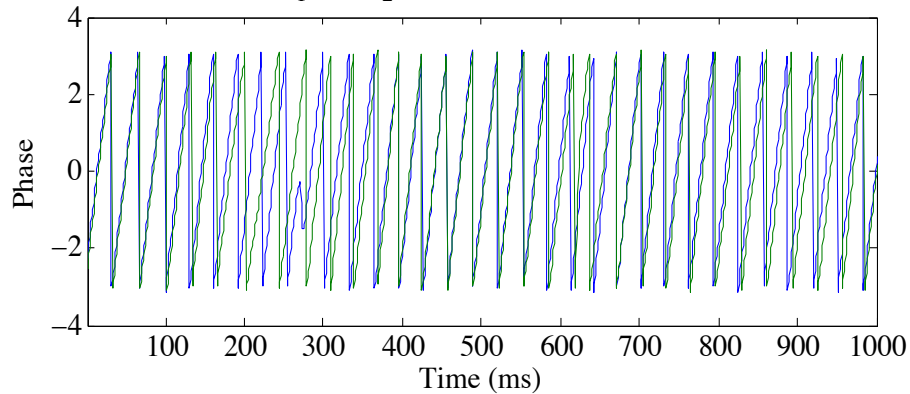
Coupled Oscillator Model

$$\frac{\partial}{\partial t} \theta_1(t) = \omega - \kappa_{12} \sin(\theta_1 - \theta_2 - \mu_{12}) + \nu_1(t)$$

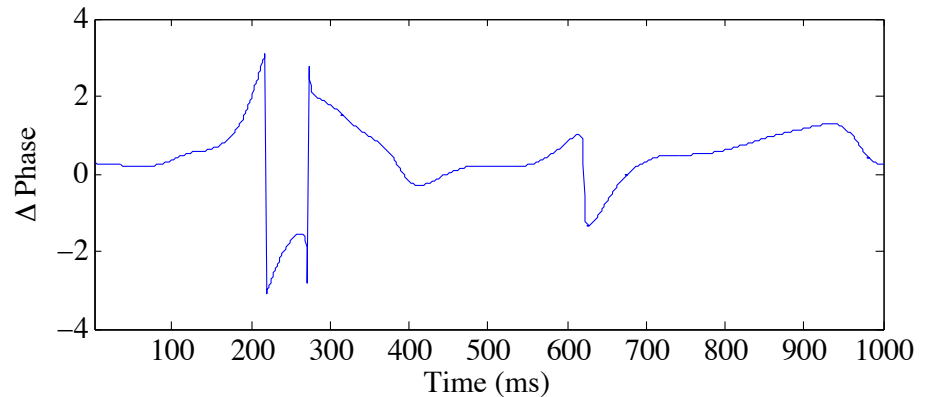
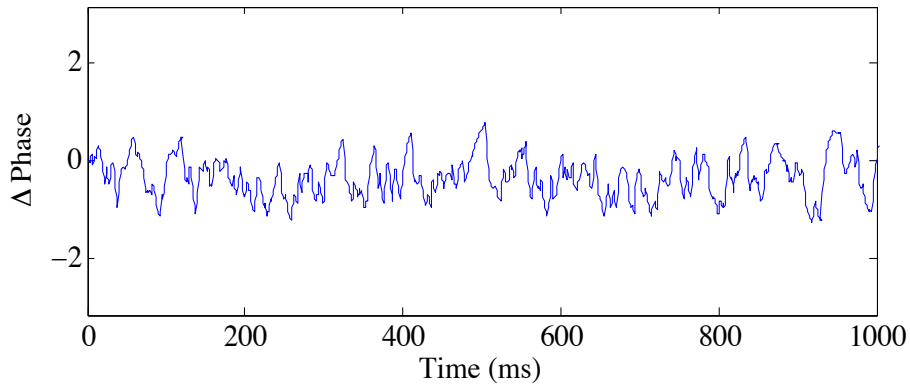
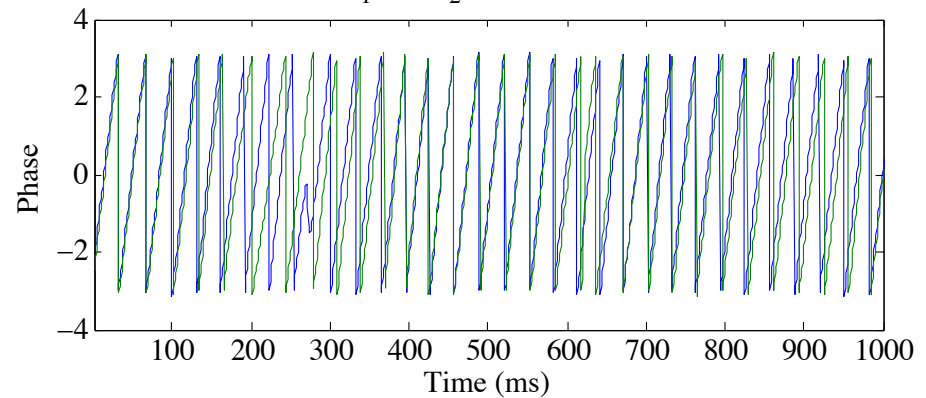


Coupled Oscillatory Model – Fit to Baseline

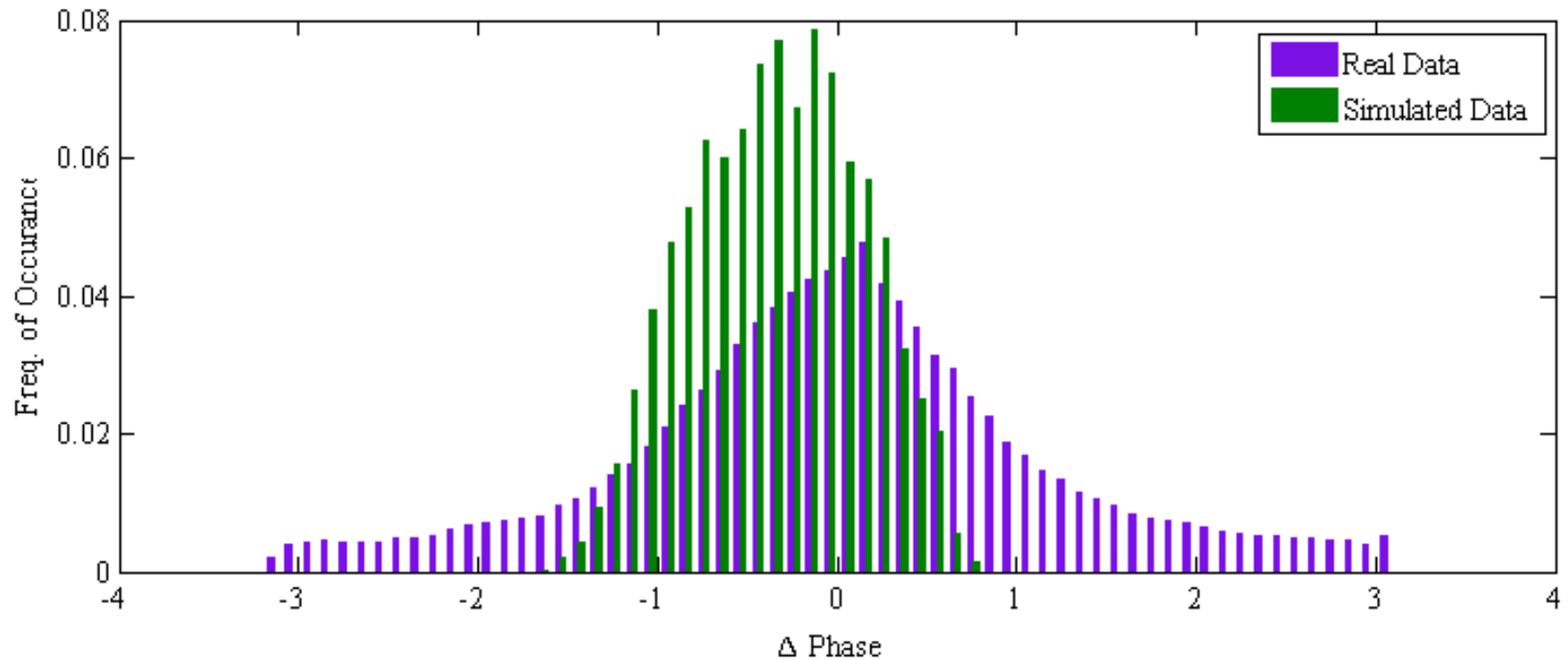
θ_1 and θ_2 from Coupled Osc. Model



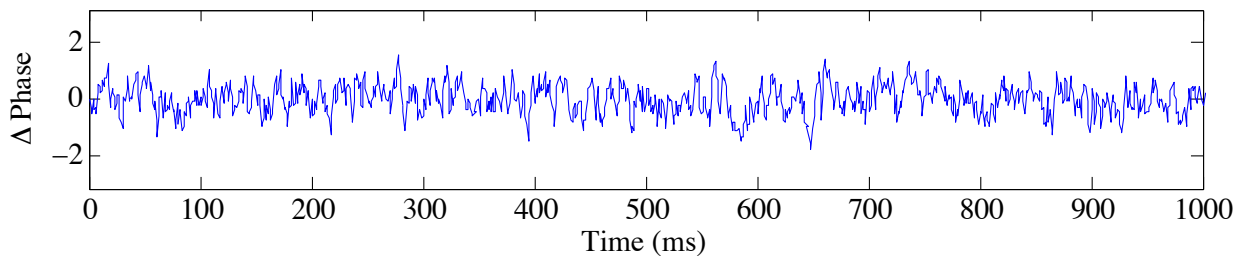
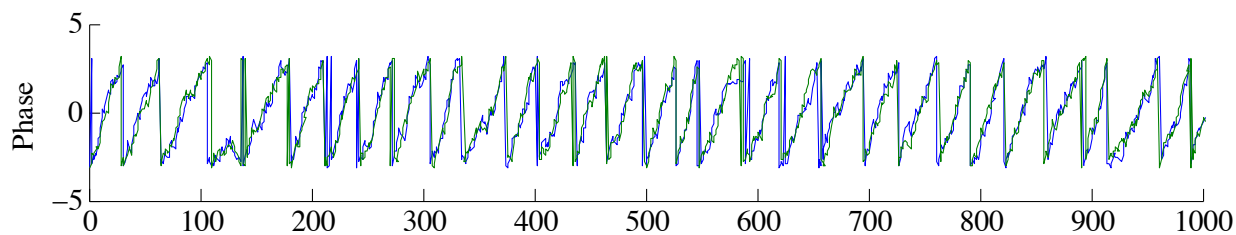
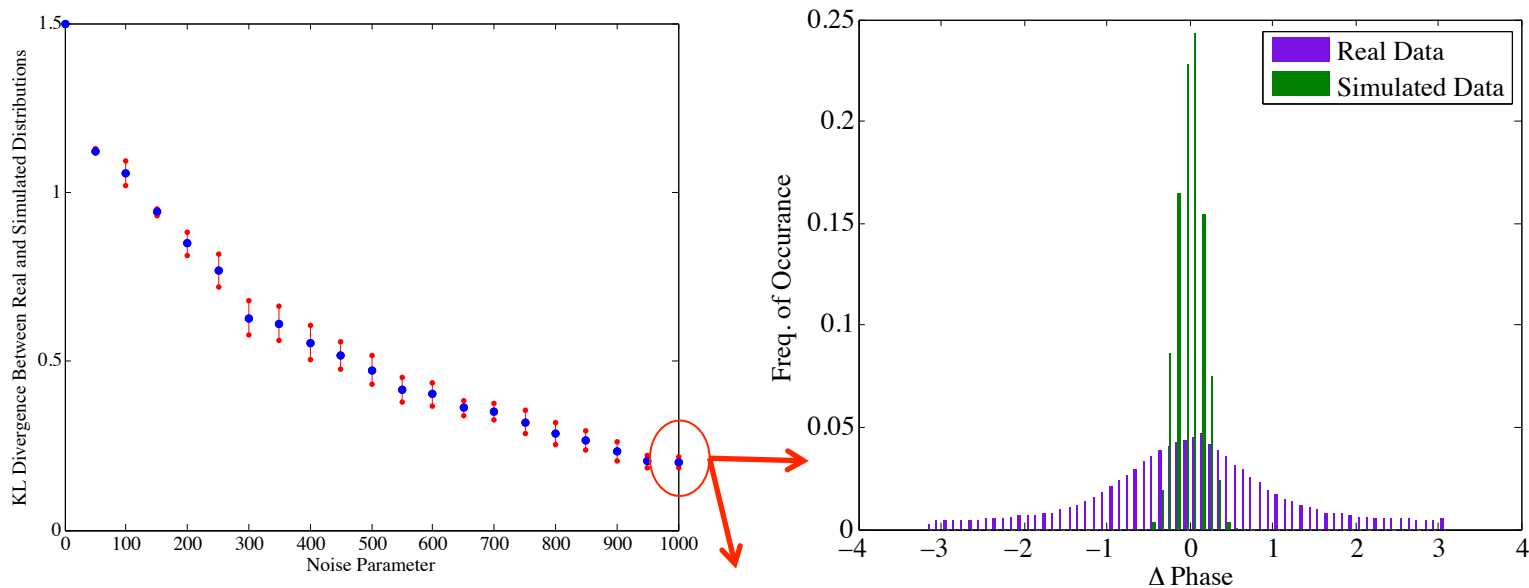
θ_1 and θ_2 from Real Data



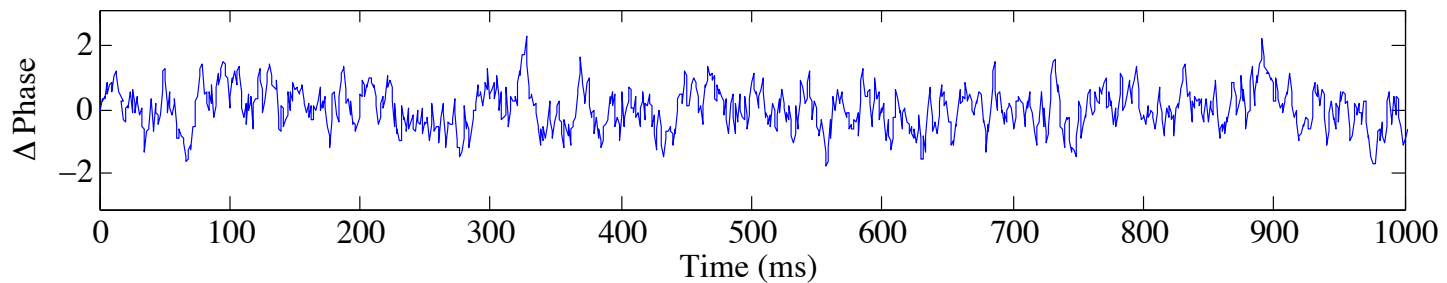
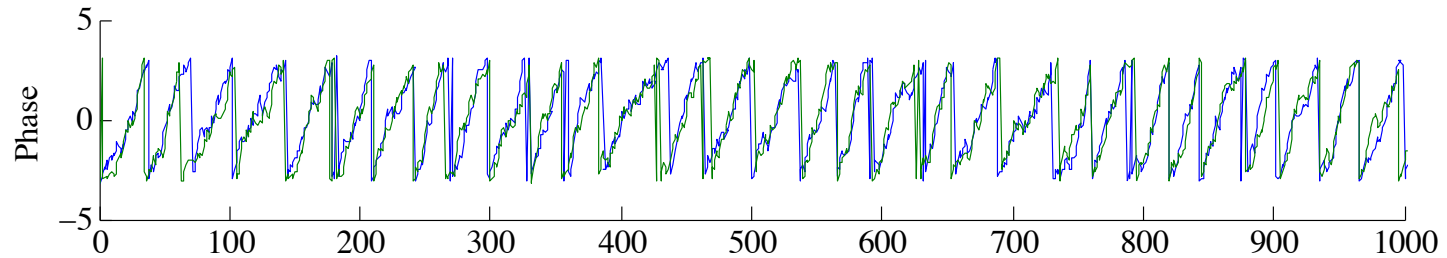
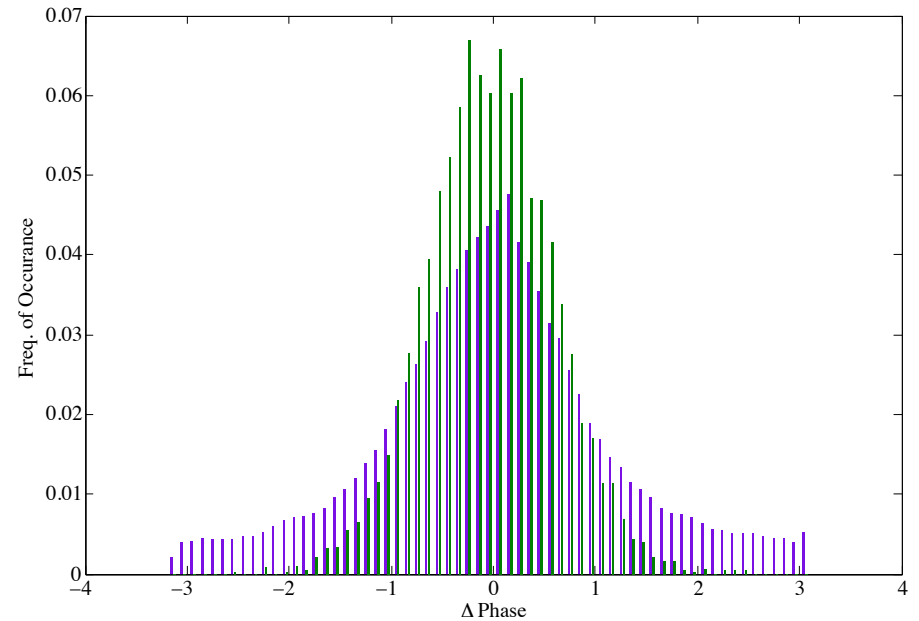
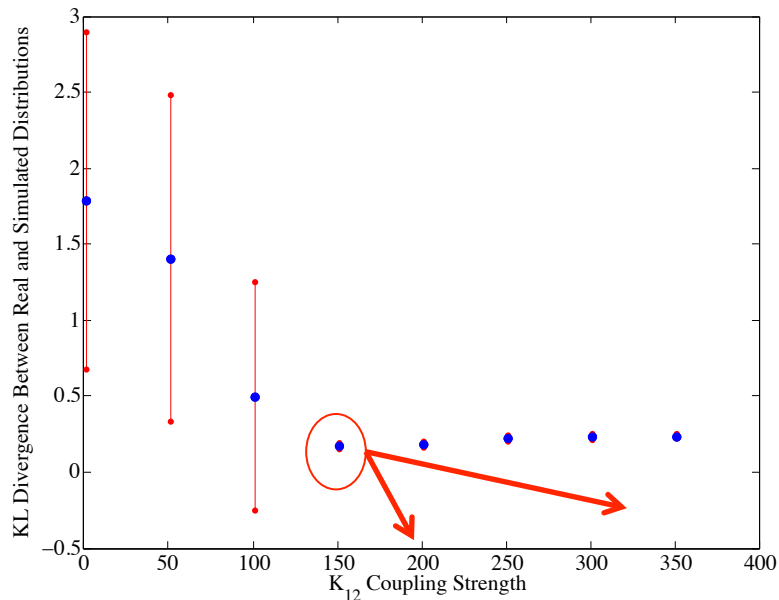
Coupled Oscillatory Model ctd.



$$\frac{\partial}{\partial t} \theta_1(t) = \omega - \kappa_{12} \sin(\theta_1 - \theta_2 - \mu_{12}) + \mathbf{v}_1(t)$$

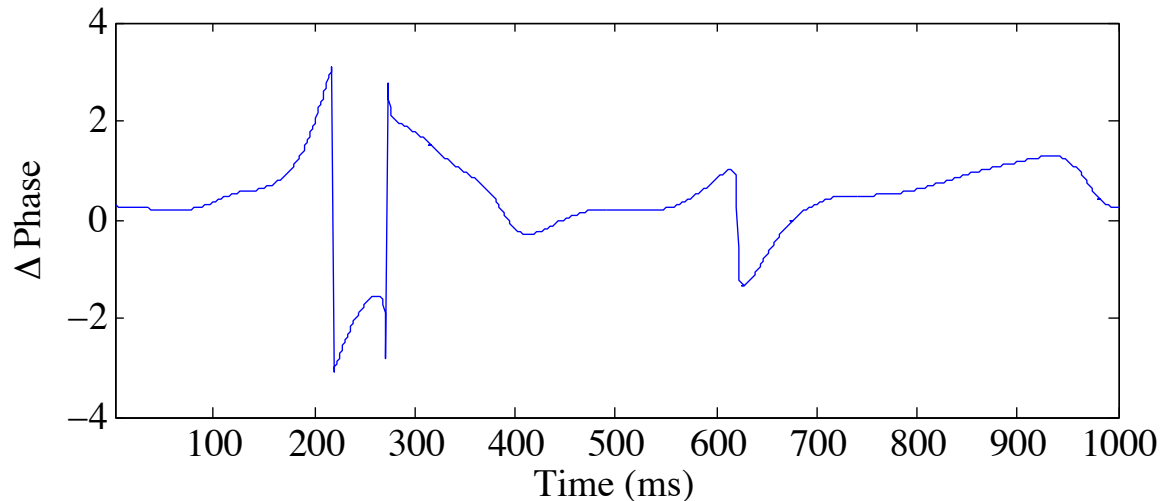


Coupled Oscillatory Model ctd.

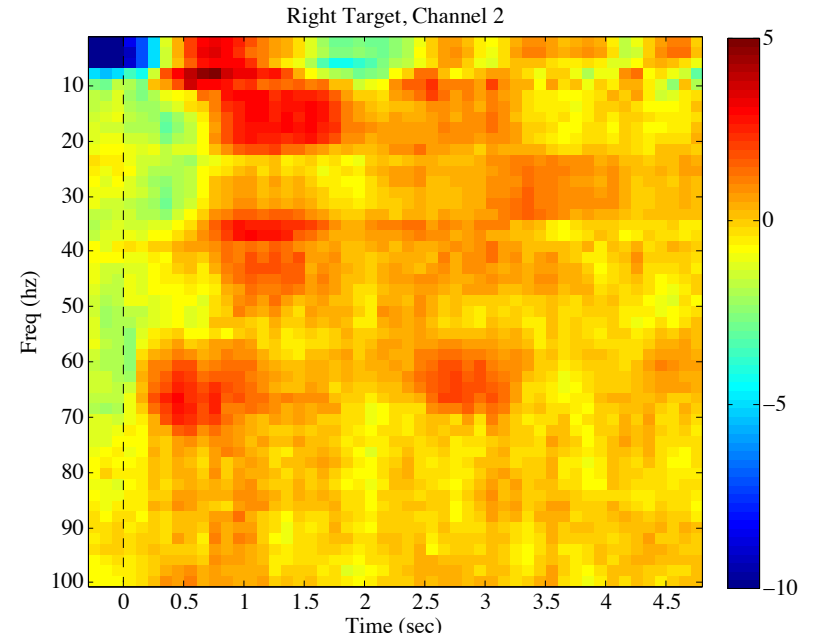
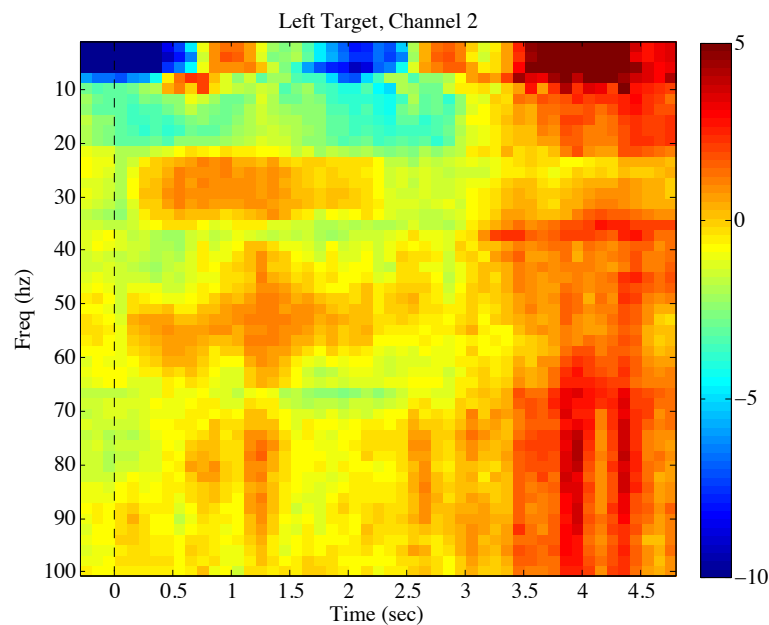
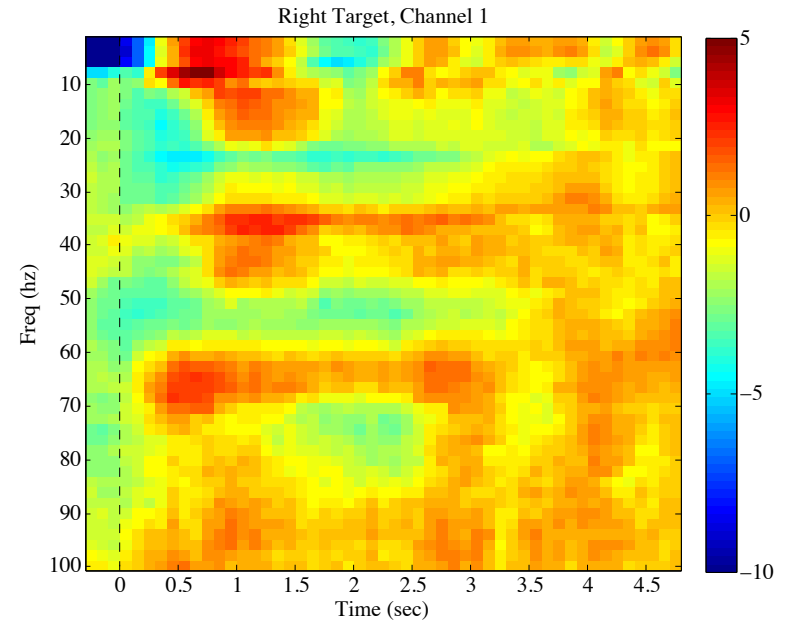
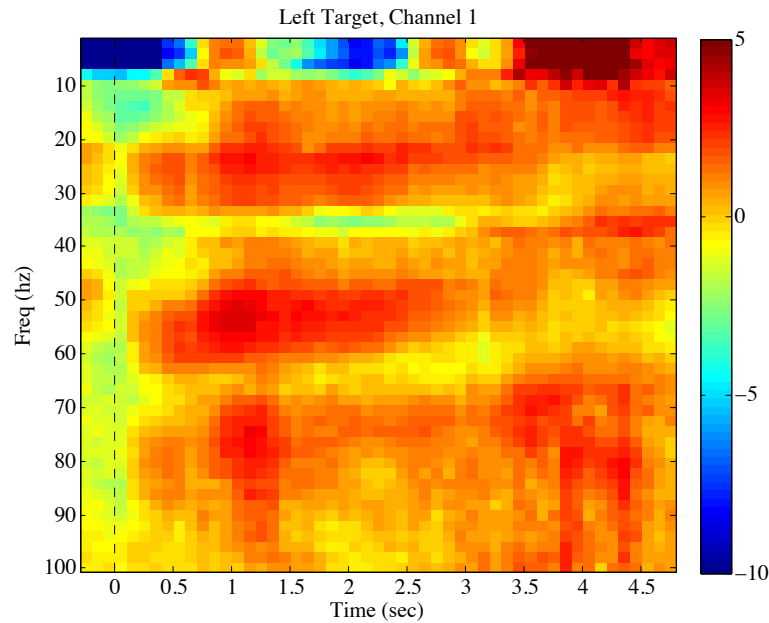


Coupled Oscillatory Model ctd.

- Observations:
 - Phase must be smoother, must vary more
 - “Impulses”
 - Spectrogram



What about during L/R movements?



Phase Resetting Curve

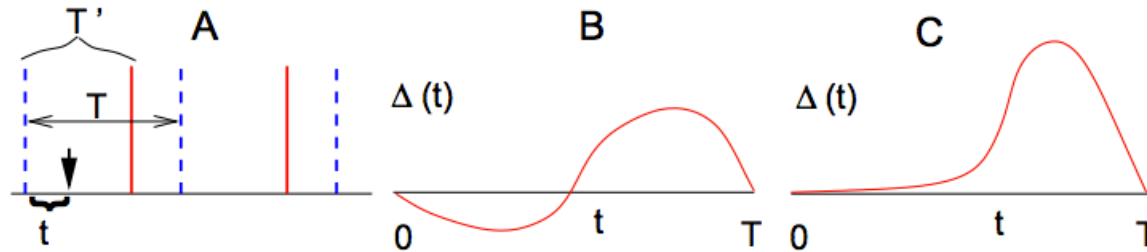


Figure 2: Phase response curves (PRC). (A) Construction of the PRC. Natural period is T . A perturbation arrives at t after the last spike causing the spike to change its time to T' . The PRC, $\Delta(t) = 1 - T'/T$. Dashed pulses show the times at which the oscillator fires without the perturbation and the solid curves show the perturbed firing times. Note that a key assumption is that effect of the perturbation occurs only during the cycle it was given. (B) PRC for the firefly *P. Malaccaae*. (C) PRC for a cortical neuron.

Model:

$$\frac{\partial}{\partial t} \theta_1(t) = \omega - \delta(\theta_2) \Delta \theta_1$$

$$\frac{\partial}{\partial t} \theta_2(t) = \omega - \delta(\theta_1) \Delta \theta_2$$

Modeling

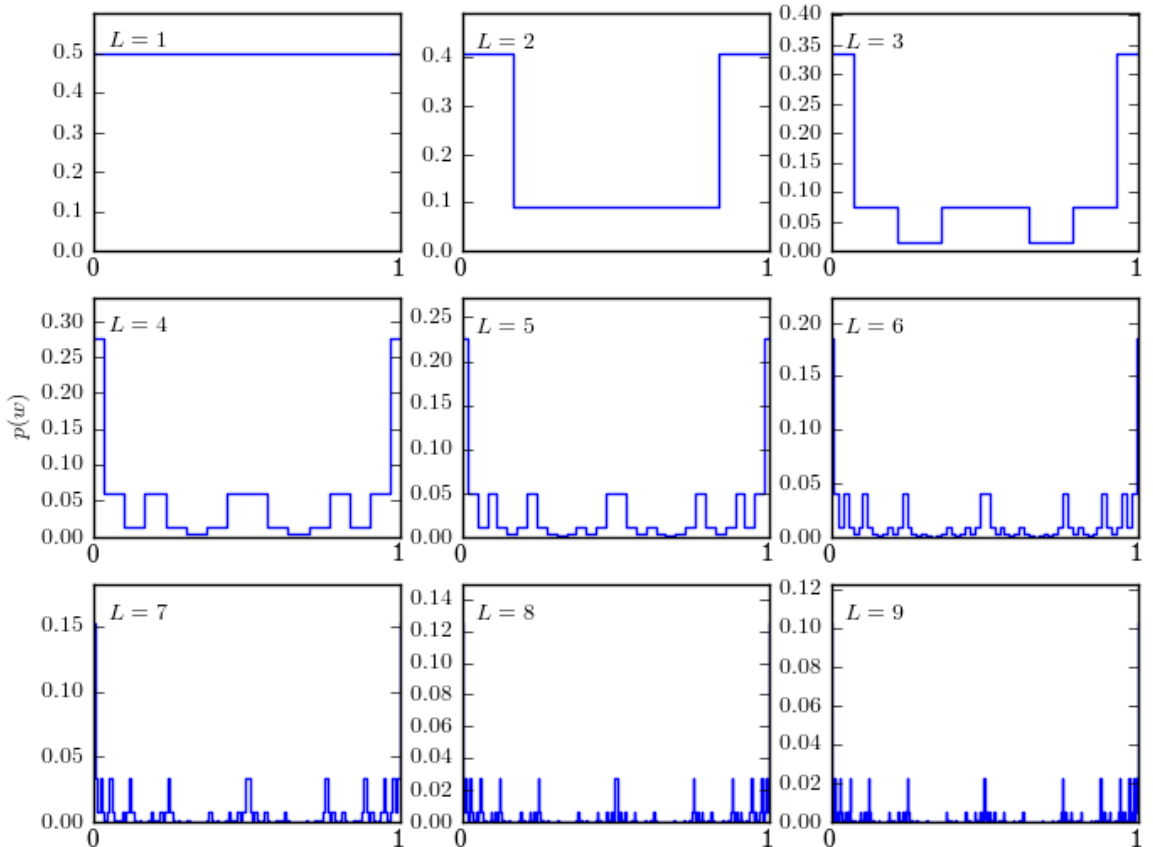
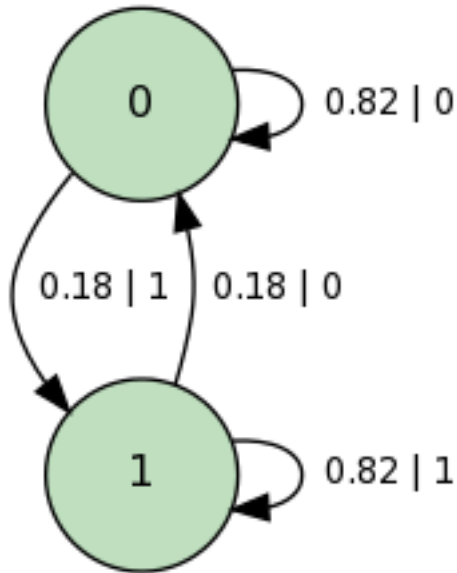
- Dynamical System Model
 - Coupled Oscillator
 - ...with Phase Resetting
- Epsilon Machine comparisons:
 - To Left and Right targets
 - Partitioned as:
 - $\theta > 0, \theta \leq 0$
 - $d\theta > 0, d\theta \leq 0$

Partition Data

- Epsilon Machine comparisons:
 - Baseline, Left, and Right targets
 - Partitioned as:
 - $\theta > 0, \theta \leq 0$
 - $d\theta > 0, d\theta \leq 0$

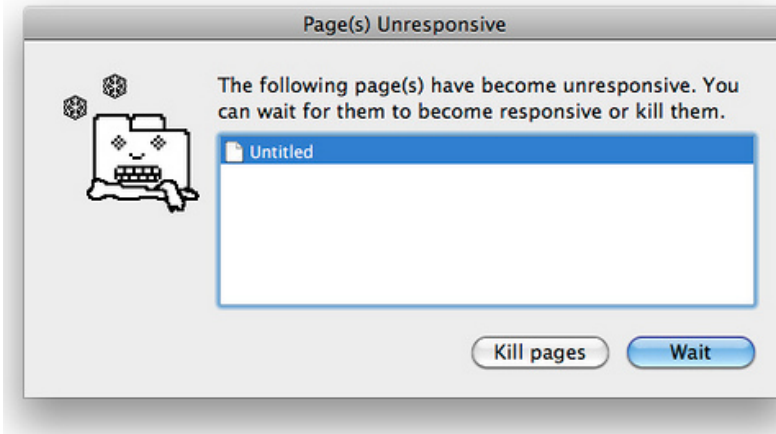
Baseline

- Baseline phase during Screen Off



Baseline

Inferred Machine	$h\mu$	$C\mu$	E
Baseline	0.67647	0.99996	0.32348
Right			
Left			



...but then I kept crashing my browser

Conclusions / Future Directions

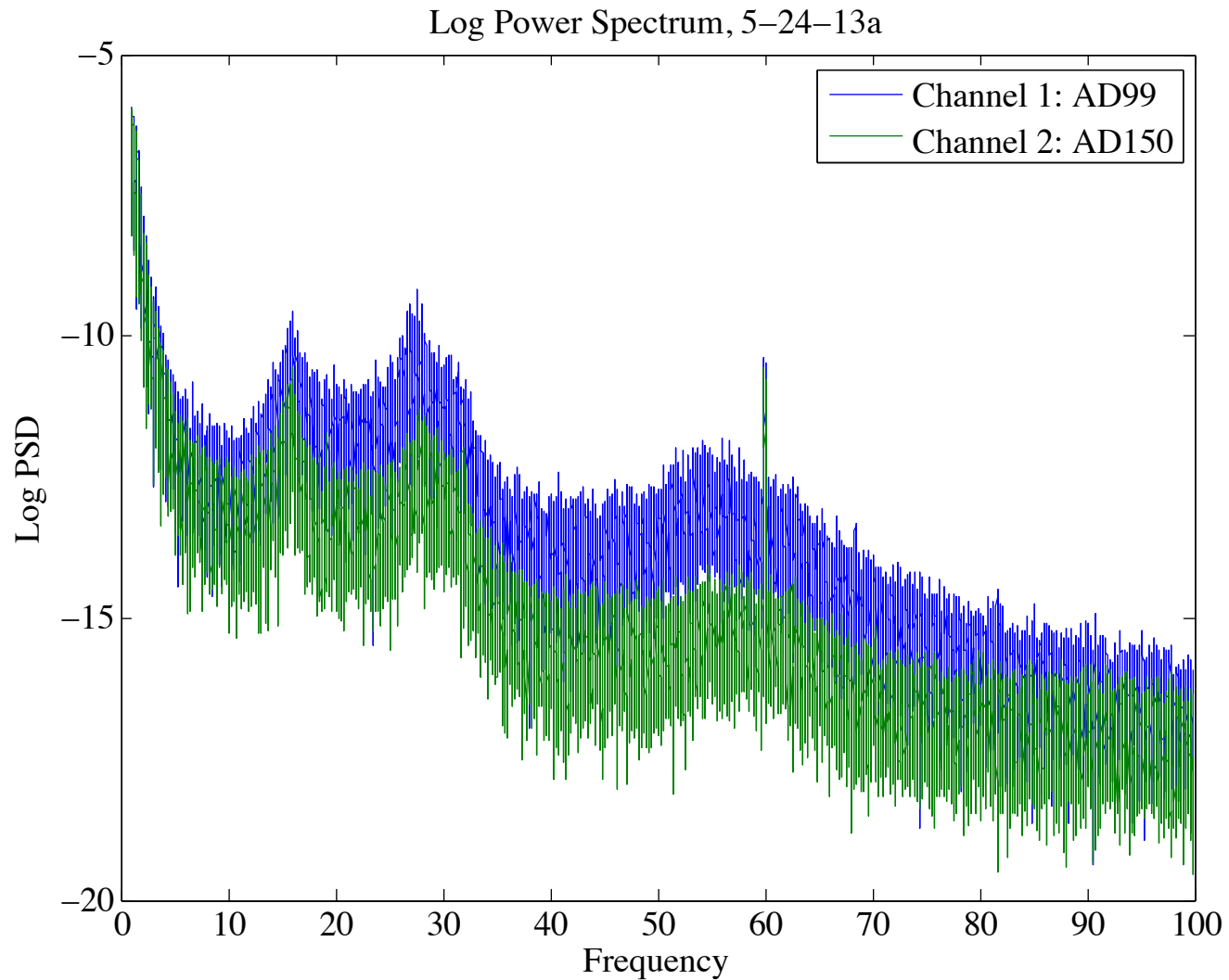
- Conclusions
 - Dynamic Coupled Oscillating Model may not be sufficient to describe Phase-BMI
 - Adding Phase Resetting Curve may capture impulses
- Future Directions
 - Comparison of Epsilon Machine for moving left vs. moving right

Thanks!

- Dr. Crutchfield
- The Carmena Lab
- Sebastian



Why 20, 30, 40 Hz? Why not 10, 50 Hz?



Why 20, 30, 40 Hz? Why not 10, 50 Hz?

- Correlation Coefficients of frequency decomposition:

