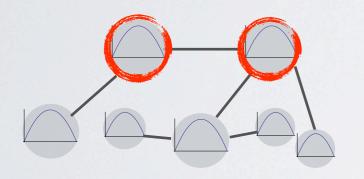
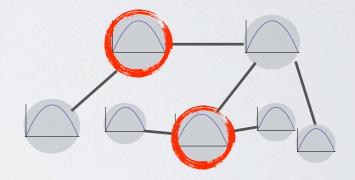
Networks Of Chaotic Maps: A New Network Growth Model, Inferring Topology From Symbolic Dynamics



Final Project NLP, NCASO June 4, 2010



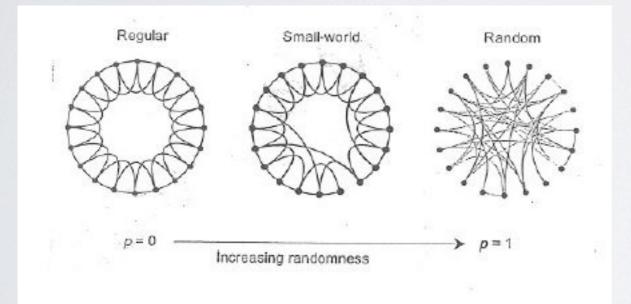
Charlie Brummitt Graduate Group in Applied Math <u>cbrummitt@math.ucdavis.edu</u>

CLASSIC NETWORK GROWTH MODELS

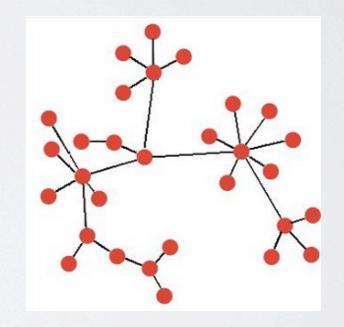
Watts-Strogatz

Preferential Attachment

randomly, independently rewire links of a grid



new nodes form links with probability proportional to target's degree



Generate "small-world" networks with properties like small diameter, high clustering, power-law degree distributions

DYNAMIC LINKS, DYNAMIC NODES

- Many network growth models have dynamic links but static nodes
- But in many real world systems nodes are dynamic
 - e.g., neurons, Internet routers, airports, people
- Motivates network growth models with dynamic nodes

NETWORK OF MAPS

- Undirected graph
- Nodes: logistic maps f(x) = rx(1 x)(or other one-dimensional maps)
- 300 nodes, 5000 edges (randomly chosen)
- Evolution: $x_i(t+1) = (1-\epsilon)f(x_i(t)) + \frac{\frac{1}{\epsilon}}{k_i}\sum_{\substack{j \in B(i) \\ degree}} f(x_j(t))$

Each node evolves according to its own logistic map and an evenly weighted sum over its neighbors

GLOBAL REWIRING ALGORITHM

P. Gong and C. Van Leeuwen, 2004. D. van den Berg and C. van Leeuwen, 2004.

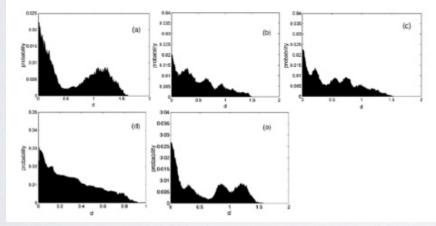
- Iterate for a transient so that the system's on an attractor
- Iterate for more time steps, and after each update, rewire:
 I.Choose a node at random (the "pivot")
 - 2. Find which other node is most coherent with the pivot, i.e., which minimizes $d_{ij}(t) = |x_i(t) x_j(t)|$ (the "candidate")
 - 3. If the candidate is already connected to the pivot, do nothing
 - 4. Else form a link between the two, and sever the link between the pivot and its least coherent neighbor (i.e., the neighbor k that maximizes $d_{ik}(t) = |x_i(t) - x_k(t)|$).

GLOBAL REWIRING ALGORITHM

Advantages

- toy model for neurogenesis
- interesting dynamics: below threshold population, dynamic in time:





above threshold, settles onto small-world topology

Disadvantages

- artificial choice of who rewires (requires random number generator)
- unrealistic choice for targets of new links: link to the most coherent node, no matter where it is in the network

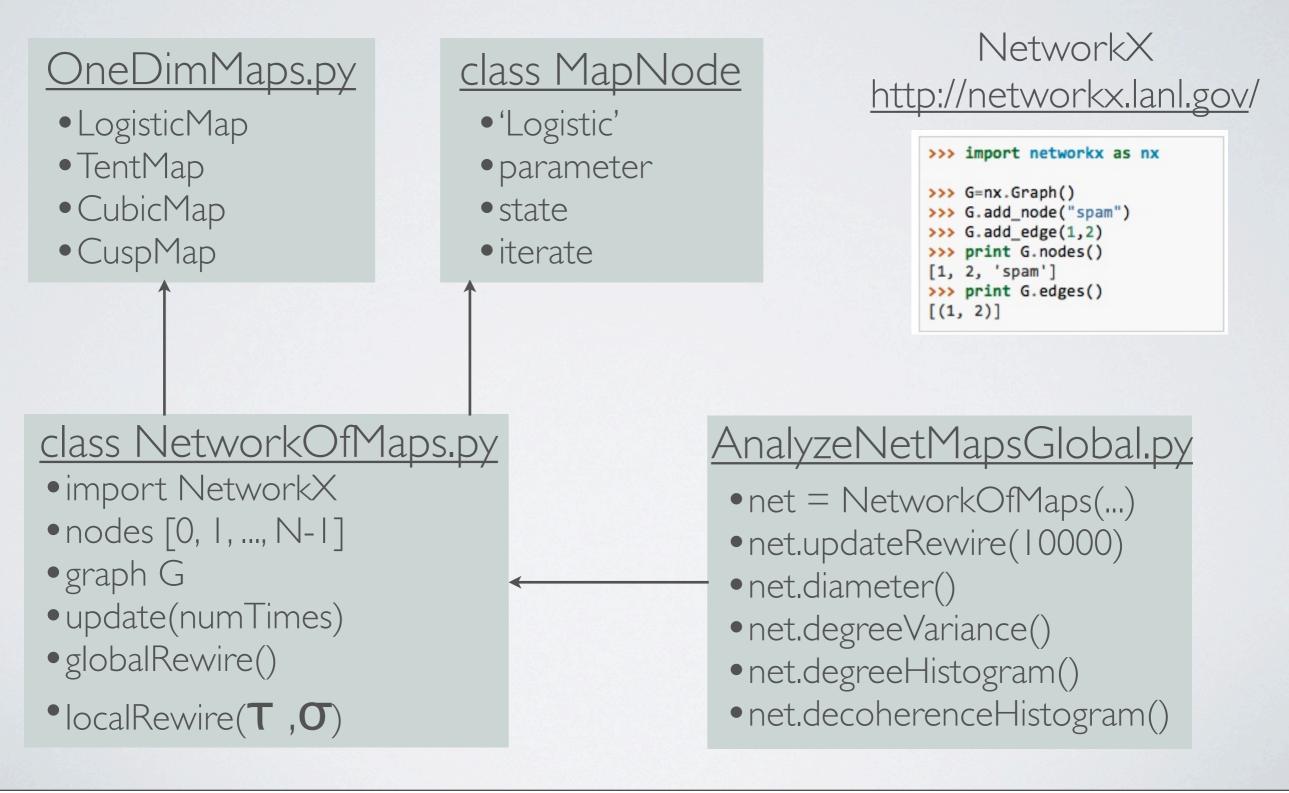
MODIFICATION (I OF 2): WHO REWIRES?

- Nodes rewire whenever their total decoherence with their neighbors $\sum_{j \in B(i)} |x_j(t) x_i(t)|$ exceeds a threshold **T**.
- Interpretation: nodes out of sync with their neighbors get "fed up" and form a new link to achieve greater coherence
- T controls the rate at which nodes rewire their links set T high: nodes rarely rewire set T low: nodes frequently rewire
- Benefit: the nodes truly are autonomous (no random number generator)

MODIFICATION (2 OF 2): WHO WILL BE MY NEW FRIEND?

- Before: form a new link with most coherent node, no matter where it is in the network
- Change: form a link with most coherent node at most σ hops away
- Interpretation: nodes form connections with friends' friends; other nodes are too far away to know about them
- Usually take $\sigma = 2$ or 3 (diameters of our networks ~3 or 4)

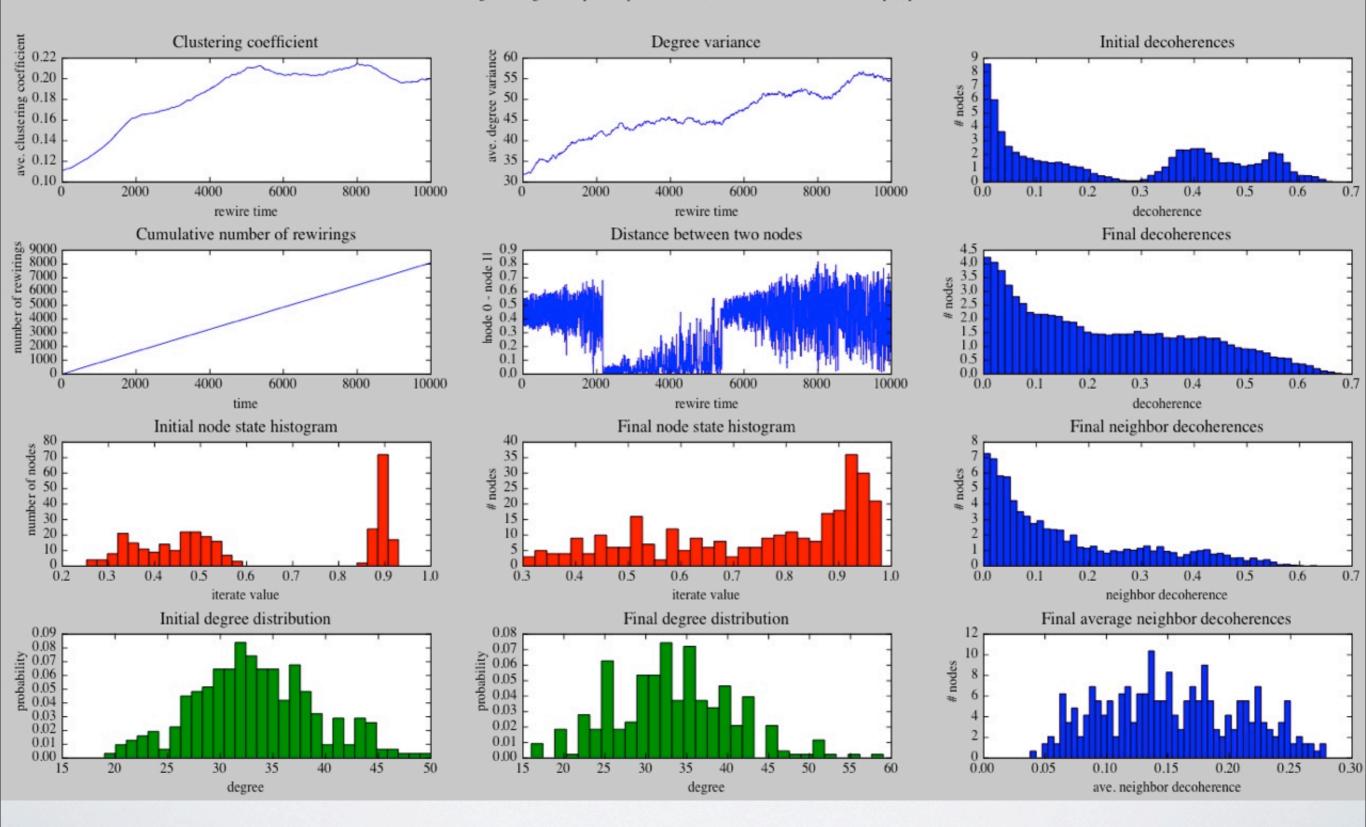
PYTHON IMPLEMENTATION



GLOBAL REWIRING RESULTS

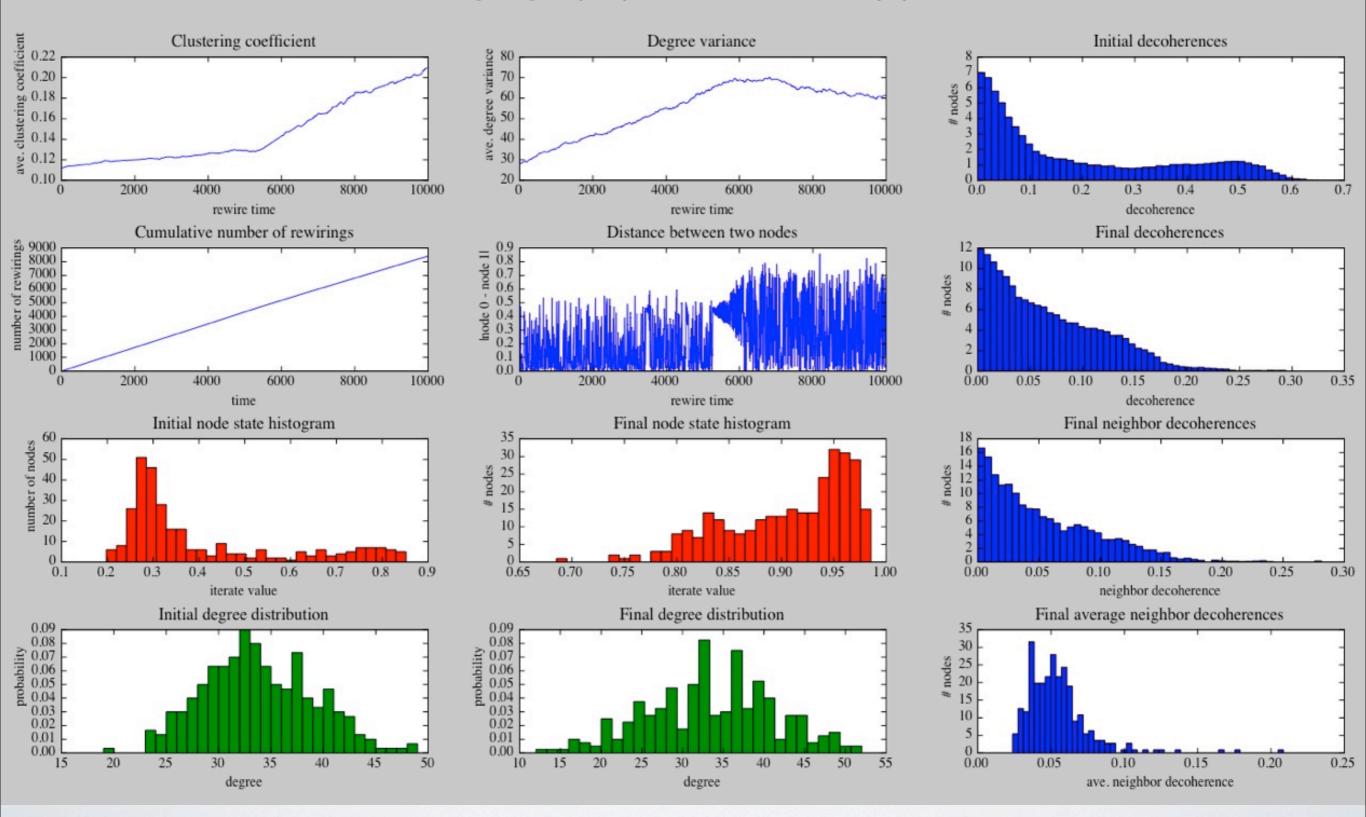
- 300 nodes
- logistic map with r = 4.0
- 5000 edges initially chosen uniformly at random
- transient 1000, then update and rewire 10,000 time steps
- coupling constant $\epsilon = 0.3, 0.4$

Global rewiring, 300 Logistic maps with parameter 4.0, 1000 transients, 10000 time steps, epsilon = 0.3



 $\epsilon = 0.3$

Global rewiring, 300 Logistic maps with parameter 4.0, 1000 transients, 10000 time steps, epsilon = 0.4



 $\epsilon = 0.4$

(i.e., nodes depend more on neighbors)

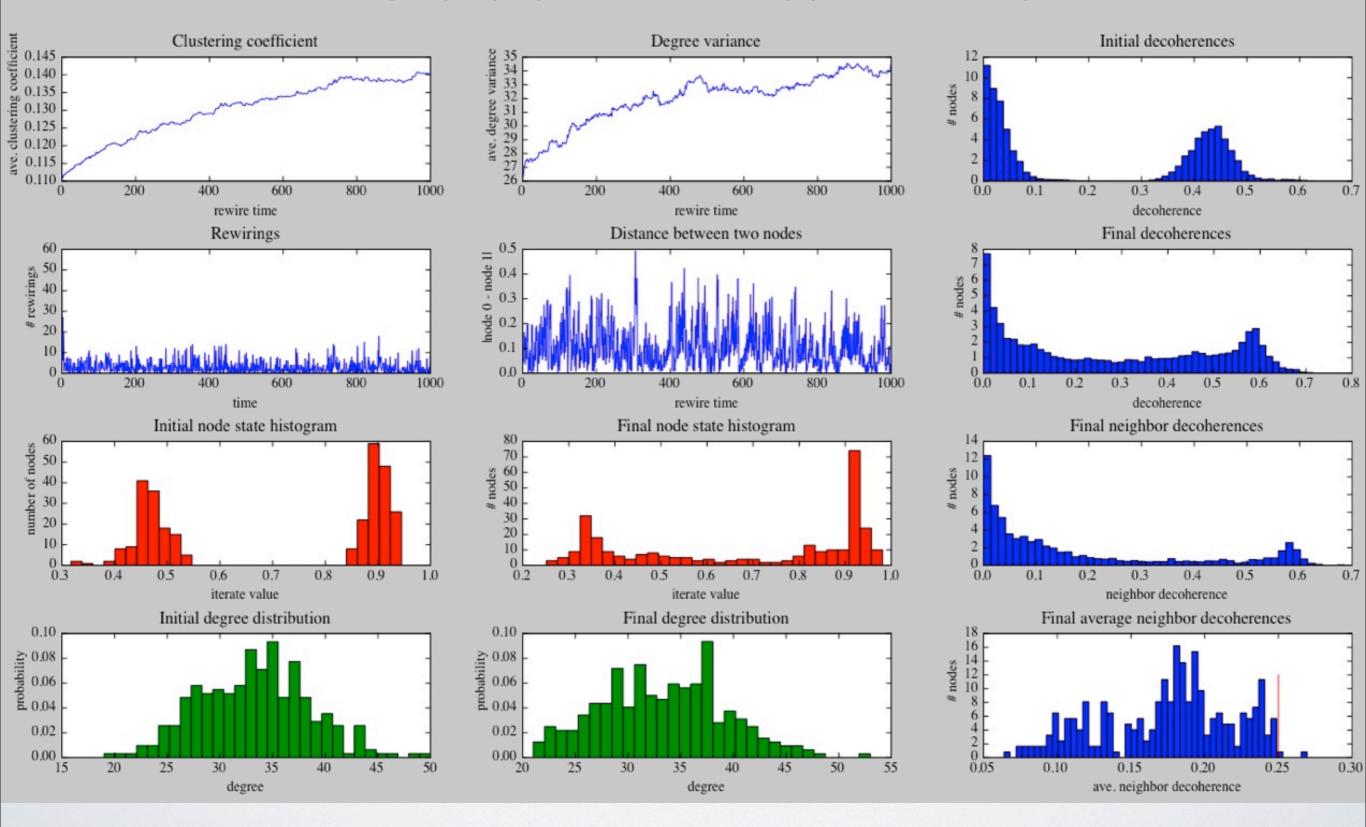
LOCAL REWIRING RESULTS

• 300 nodes

same setup as global rewiring

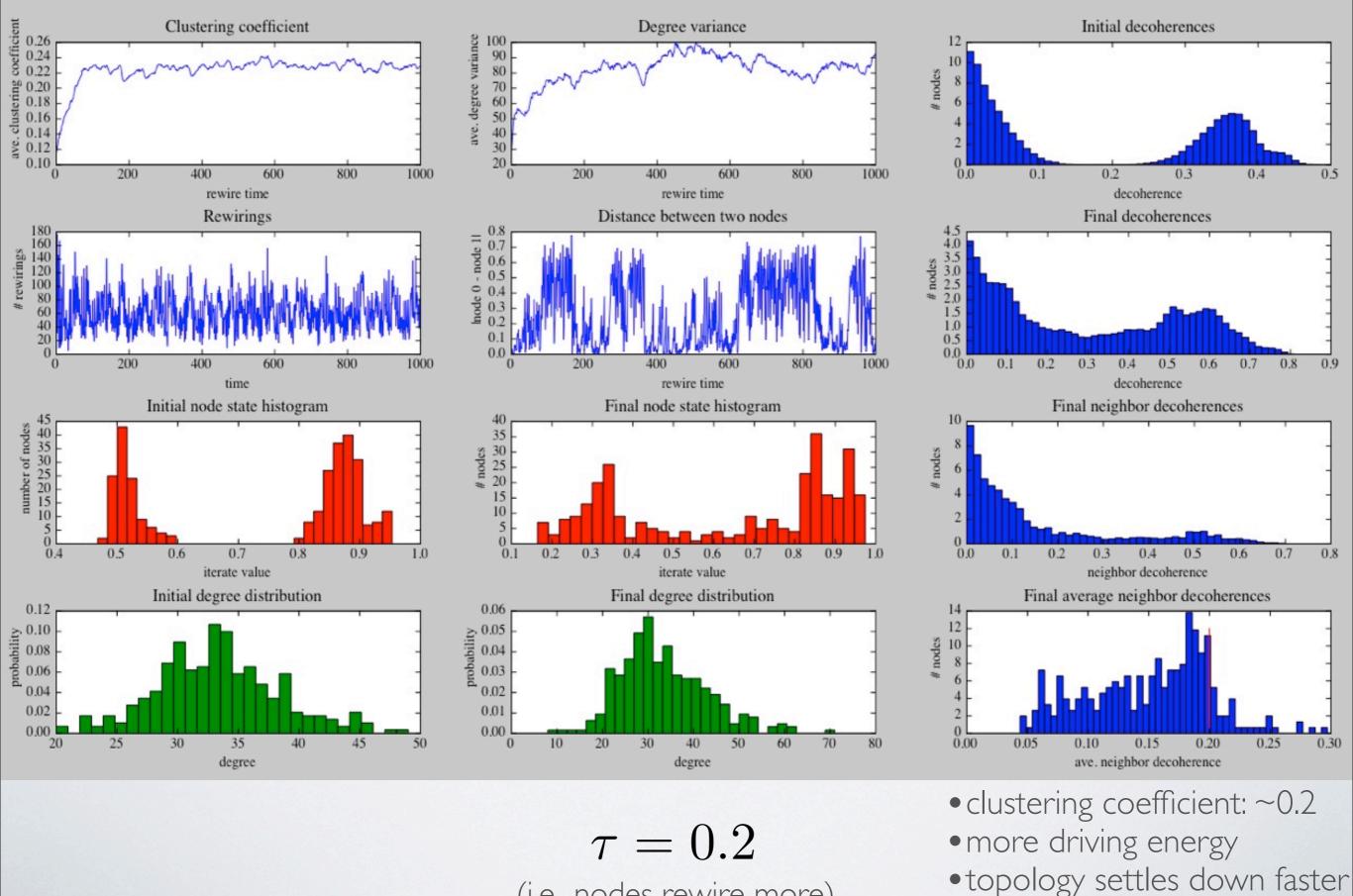
- logistic map with r=4.0
- 5000 edges initially chosen uniformly at random
- transient 1000, then update and rewire 10,000 time steps
- coupling constant $\epsilon = 0.3$
- threshold $\tau = 0.25, 0.2$ max hops $\sigma = 2$ \leftarrow NEW

Local rewiring, 300 Logistic maps with parameter 4.0, 1000 transients, 1000 time steps, epsilon = 0.3, threshold = 0.25, max hops = 2



 $\tau = 0.25$

Local rewiring, 300 Logistic maps with parameter 4.0, 1000 transients, 1000 time steps, epsilon = 0.3, threshold = 0.2, max hops = 2

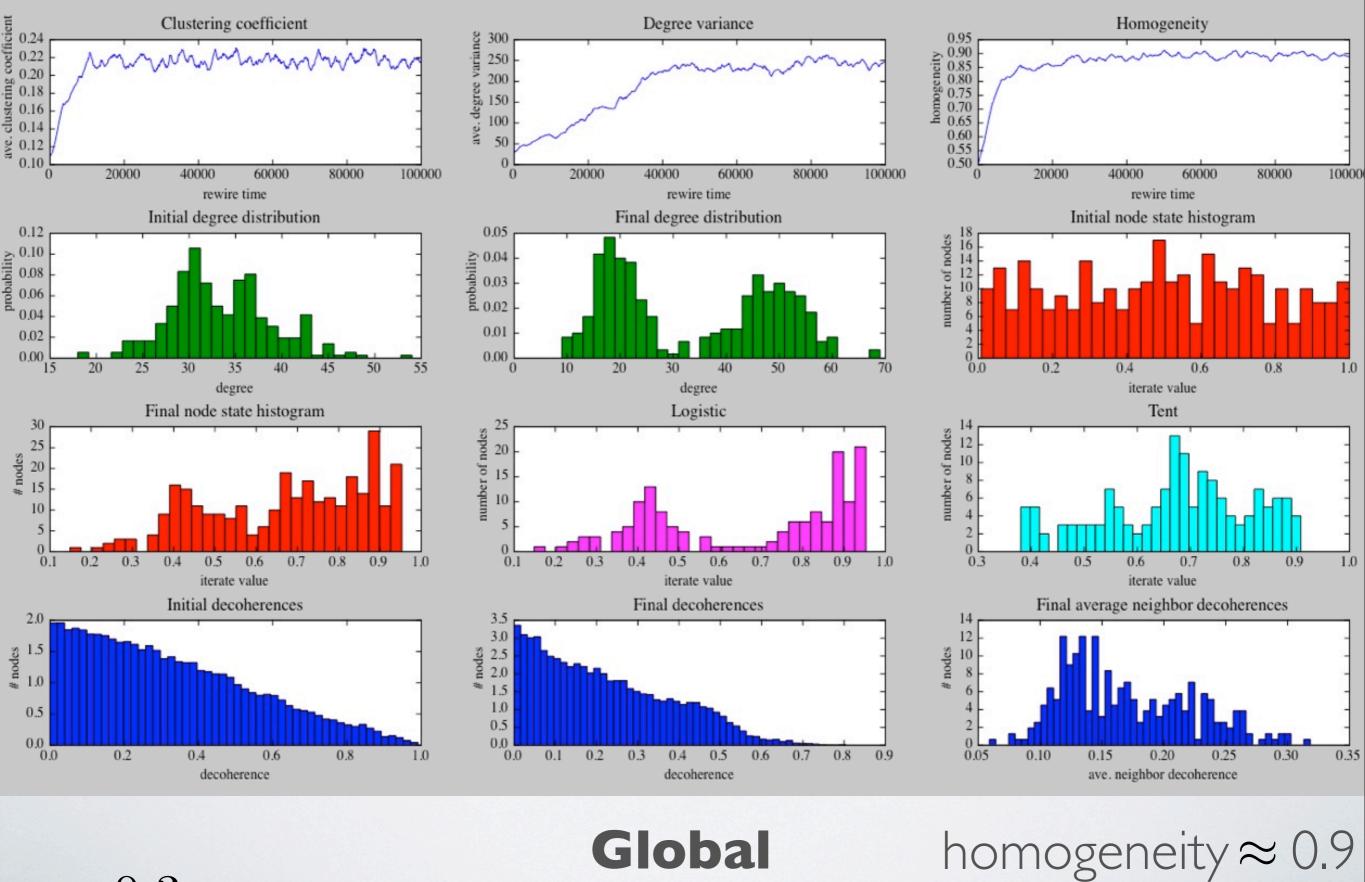


(i.e., nodes rewire more)

TWO MAPS ON A NETWORK

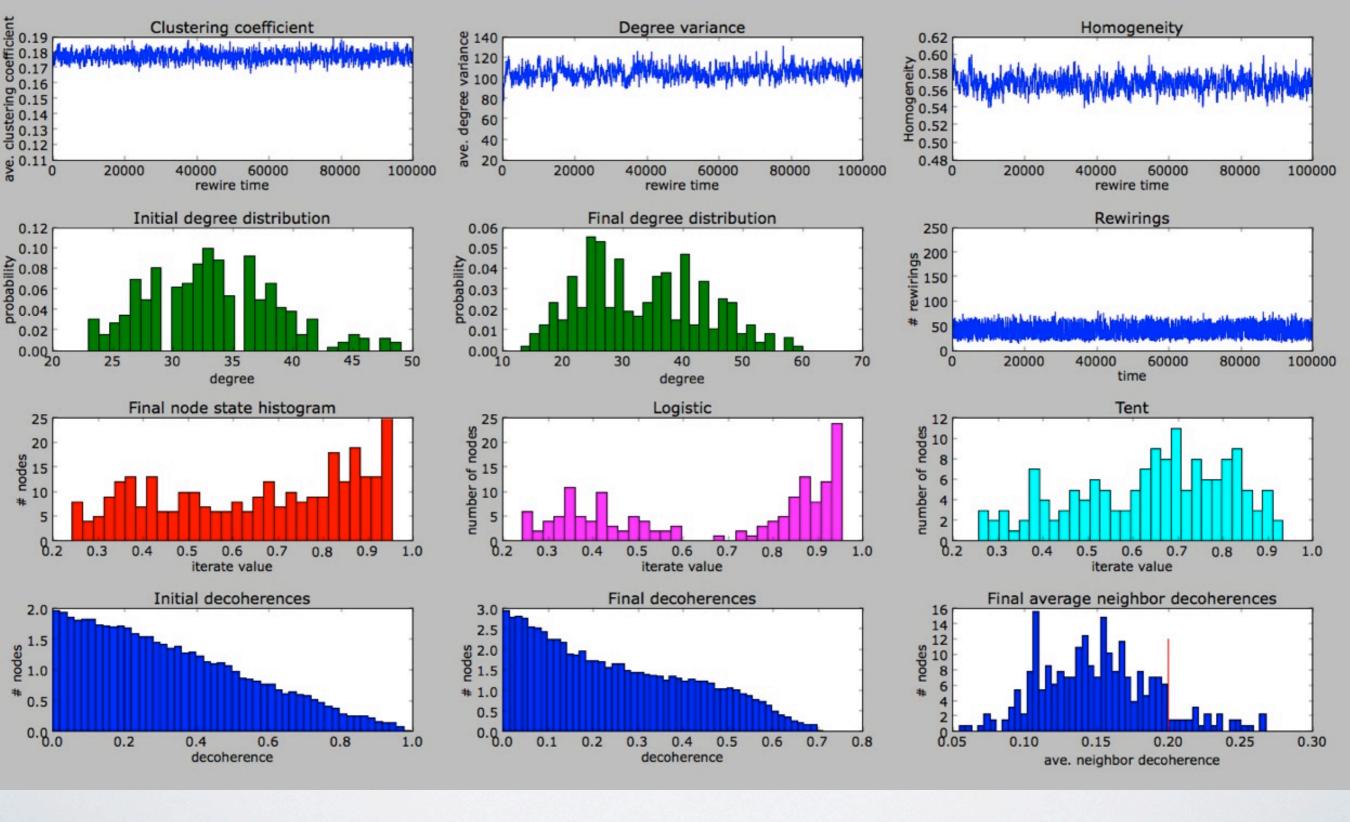
- Heterogeneous population
- Some nodes are logistic maps, others are tent maps
- Do they coalesce into homogeneous communities?
 - If so, how homogenous?
 - Could we distinguish the nodes from their iterates?
- <u>Heterogeneity</u> := fraction of edges that connect same nodes

Global rewiring, 500 transients, 100000 time steps, epsilon = 0.3



Global

 $\epsilon = 0.3$



Local

homogeneity ≈ 0.6

 $\begin{aligned} \epsilon &= 0.3 \\ \tau &= 0.2, \sigma = 3 \end{aligned}$

REWIRING CONCLUSIONS

- Each node is inherently chaotic
- Nodes try to "reign in their chaos" by associating with others who are similar
- New local rewiring algorithm:
 - Avoids unrealistic way of choosing who rewires and to whom
 - Achieves similar results: e.g., skewed degree distribution, high clustering ~0.2, interesting temporal dynamics
 - Depends heavily on threshold τ , not so much on max hops σ
- Two maps on the network coalesce into homogeneous communities (more so for global rewiring because nodes can search further)
- Local Rewiring => more rewirings => knock out of "ground state" (homogeneous connections)

PART II COMPUTATIONAL MECHANICS OF A NETWORK OF MAPS

Can we infer the topology?

0.792 0.026 0.075 0.045... 0.004 0.38 0.183 0.755... 0.568 0.975 0.623 0.413... 0.022 0.893 0.103 0.646... 0.684 0.344 0.321 0.774... 0.902 0.793 0.782 0.854... 0.11 0.767 0.707 0.81... 0.107 0.387 0.524 0.055... B A A A... A A A B... B B B A... A B A B... B A A B... B B B B... A B B B... A B B B... A A B A...

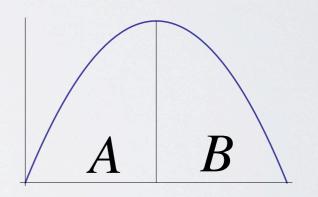
time series of iterates

symbols

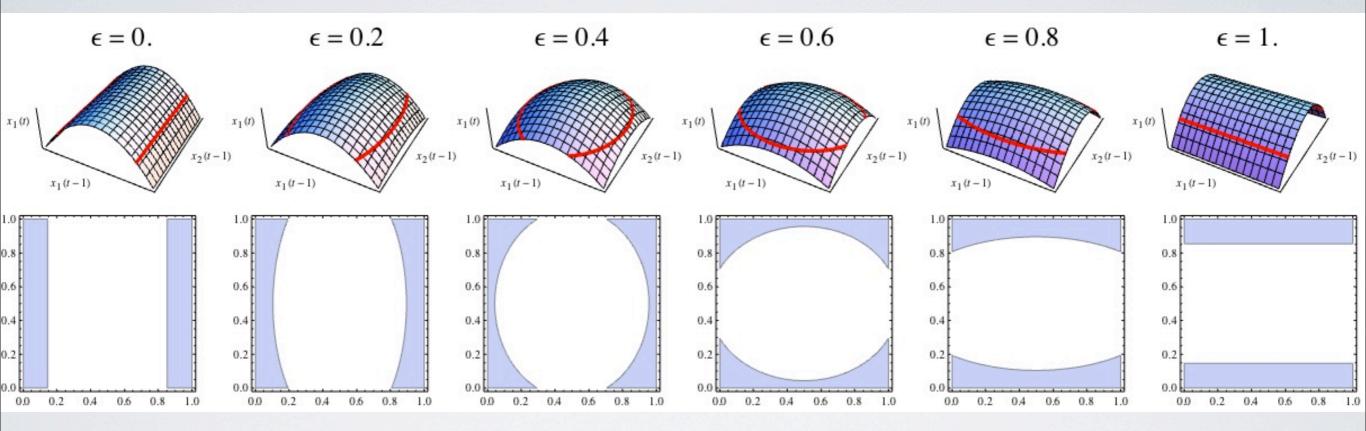
 $x_1(t+1) = (1-\epsilon)f(x_1(t)) + \epsilon f(x_2(t))$

Generating partition: decision point 1/2

 $x_1(t) = 0.38297512 \rightsquigarrow \sigma_1(t) = A$



• Analytical expression for $I(\sigma_1(t); \sigma_2(t))$?



 Need to determine the area of the unit square that gets mapped above 1/2

* weighted by the asymptotic distribution over the unit square *

• If the two logistic maps sampled the unit interval uniformly, this would be feasible:

Area
$$(\epsilon) = \frac{\left(4\sqrt{1-\epsilon} - \sqrt{2-4\epsilon}\right)\sqrt{\epsilon} - \sin^{-1}\left(\sqrt{2}\sqrt{\epsilon}\right)}{4\sqrt{(1-\epsilon)\epsilon}}$$

- But the two maps asymptotically sample the unit square in a complicated way
- Analytical expression: hard

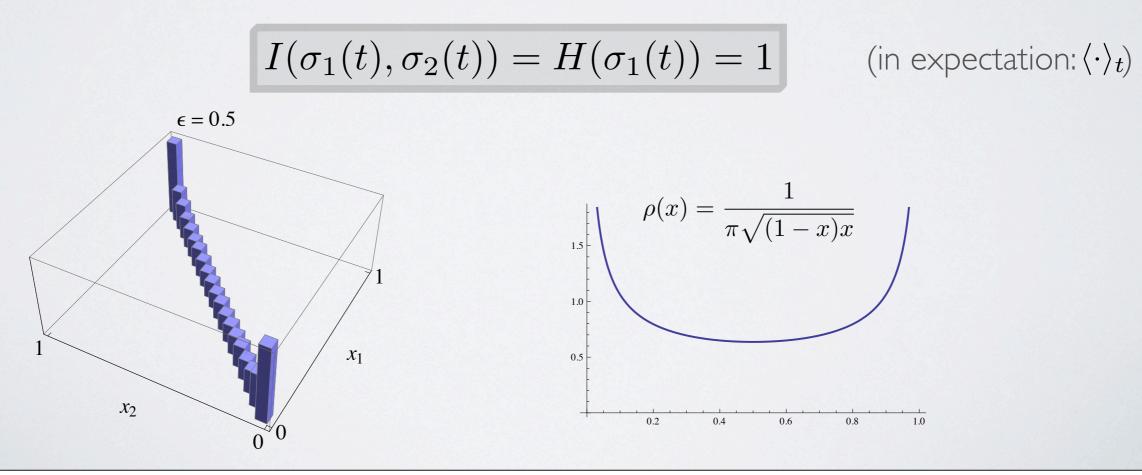
histogram of 20,000 iterates

X2

 $\epsilon = 0.1$

 x_1

- Trivial case: $\epsilon = \frac{1}{2}$ $x_1(t+1) = \frac{f(x_1(t)) + f(x_2(t))}{2} = x_2(t+1)$
- After one time step, they synchronize: $x_1(1) = x_2(1)$



TRANSFER ENTROPY

Node |
$$\sigma_1(t-5)\sigma_1(t-4)\sigma_1(t-3)\sigma_1(t-2)\sigma_1(t-1)\sigma_1(t)$$

Node 2 $\sigma_2(t-5)\sigma_2(t-4)\sigma_2(t-3)\sigma_2(t-2)\sigma_2(t-1)$

X	X'
Y	

$$T_{2\to 1} := I[X'; Y|X]$$

Info. theoretic measure of coherence of systems evolving in time

TIME-DELAYED MUTUAL INFO.

		$\sigma_1(t)$
C	$\sigma_2(t- au)$	

 $M_{1,2}(\tau) := I[\sigma_1(t); \sigma_2(t-\tau)]$

- Transfer entropy is supposedly better because it distinguishes exchanged information from shared info. due to common history (Schreiber, Phys. Rev. Letters, 2000)
- I find mixed results...

TWO NODES

• 1,000 transients

• 1,000,000 iterates

•r=4.0

			time-delayed m	nutual information	transfer entropy
Netv	work	Coupling ϵ	$I[\sigma_1(t);\sigma_2(t)]$	$I[\sigma_1(t);\sigma_2(t-1)]$	$I[\sigma_1(t); \sigma_2(t-1) \sigma_1(t-1)]$
		0.5	1.0	0.0000004	0
		0	0.00000000	0.0000001	0.0000001
		0.1	0.005	0.005	0.05
		0.2	0.38	0.04	0.10

THREE NODES

• 1,000 transients

• 100,000 iterates

•r=4.0

		time-delayed m	nutual information	transfer entropy
Network	Coupling ϵ	$I[\sigma_1(t);\sigma_2(t)]$	$I[\sigma_1(t);\sigma_2(t-1$	$\Big)\Big]I[\sigma_1(t);\sigma_2(t-1) \sigma_1(t-1)]$
	0.5	I.O Sync	0.000001	0.00001
	0.5	1.0	0.000001	0.00001
	0.1	0.00 I	0.007	0.05 t good
	0.1	0.01	0.006	0.002

Tuesday, June 1, 2010

THREE NODES

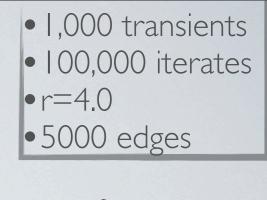
• 1,000 transients

• 1,000,000 iterates

•r=4.0

		time-delayed m	utual information	transfer entropy
Network	Coupling ϵ	$I[\sigma_1(t);\sigma_2(t)]$	$I[\sigma_1(t);\sigma_2(t-1)]$	$I[\sigma_1(t); \sigma_2(t-1) \sigma_1(t-1)]$
	0.3	0.30	0.04	0.10 1 bad
	0.3	\$ good 0.07	0.02	Dad 0.11
	0.6	I.O Sync	0.000006	
	0.6	I.O	0.0000006	t bad 0

300 NODES



		time-delayed m	utual information	transfer entropy
Network	Coupling ϵ	$I[\sigma_1(t);\sigma_2(t)]$	$I[\sigma_1(t);\sigma_2(t-1)$	$]I[\sigma_1(t); \sigma_2(t-1) \sigma_1(t-1)]$
	0.5	0.46	0.082	0.438
	0.5	Close 0.44	0.083	¢ close 0.430
	0.2	0.19	0.25	0.07
	0.2	1 bad 0.41	0.42	\$ good 0.007
Tuesday June 1 2010				

COMMENTS

- Mutual information (no time delay) and transfer entropy can detect who's connected to whom, but not always
- Transfer entropy eq, eq mutual information
- Future: try conditioning on more past symbols $I(\sigma_1(t); \sigma_2(t-1), ..., \sigma_2(t-k) | \sigma_1(t-1), ..., \sigma_1(t-k)$
- Infer paths in the network? Utilize paths in the network?

CAUSAL STATE FILTERING

Easier to infer the topology?

0.792 0.026 0.075 0.045... 0.004 0.38 0.183 0.755... 0.568 0.975 0.623 0.413... 0.022 0.893 0.103 0.646... 0.684 0.344 0.321 0.774... 0.902 0.793 0.782 0.854... 0.11 0.767 0.707 0.81... 0.107 0.387 0.524 0.055... BAAA... AAAB... BBBA... ABAB... BAAB... BBBB... ABBB... ABB... AABA...

symbols

G F C D... H F G C... F C D C... C B E E... F G D E... F C F G... E E F G... F C D G...

iterates

E-machine states

CAUSAL STATE FILTERING 4 steps:

I. Infer E-machines from nodes' symbolic output

 Feed symbolic time series into ε-machine, synchronize to a state, then output the ensuing ε-machine states

 $ABBAABAABA... \rightsquigarrow DFEGCDFDCE...$

synchronizing word

 $\epsilon\text{-}machine$ states

Compute mutual information & transfer entropy on
 E-machine states time series

4. Infer the network topology

CAUSAL STATE FILTERING

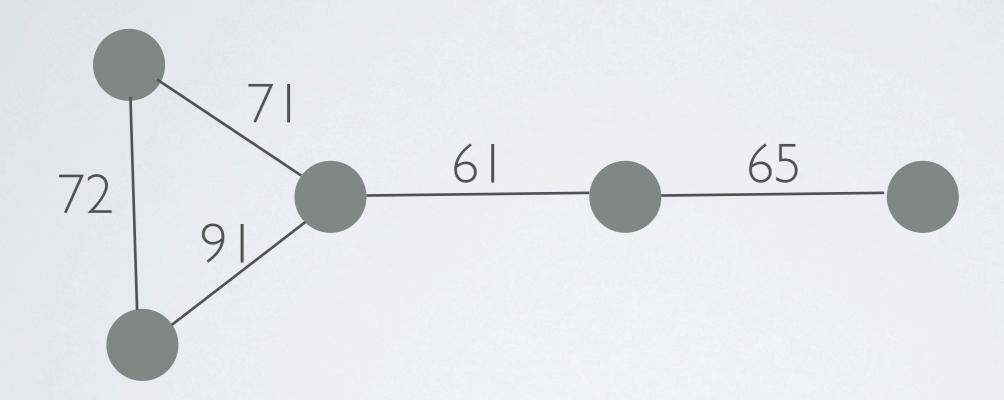
- Inferring the *E*-machine is hard
- When converting symbols to *ɛ*-machine states, I feed forbidden words into the *ɛ*-machine



$\mathbf{\Theta} \mathbf{\Theta} \mathbf{\Theta}$	Terminal — Python — 118×41
In [32]: ru r	n SymbolicDynamicsNet.py
InvalidDist	ribution Traceback (most recent call last)
/Users/char	liebrummitt/Documents/NLP/NLPnet/SymbolicDynamicsNet.py in ⊲module>()
127	
128	
	tes0 = state_sequence(m0, symbols[0])
	tes1 = state_sequence(m1, symbols[1])
131 stat	tes2 = state_sequence(m2, symbols[2])
/Users/char	liebrummitt/Documents/NLP/NLPnet/SymbolicDynamicsNet.py in state_sequence(machine, data)
25	seq = []
26	machine.set_current_distribution(machine.stationary_distribution())
> 27	for distribution in machine.distributions_iter(data):
28	events = distribution.events()
29	if len(events) == 1:
/Users/char	liebrummitt/.local/lib/python2.6/site-packages/cmpy/machines/mealyhmm.pyc in distributions_iter(s
ist)	
493	d = Distribution(dict(zip(nodes, dist)), joint=False)
494	
> 495	d.normalize()
496	d.trim()
497	<pre>selfcurrent_distribution = d</pre>
/Users/char	liebrummitt/.local/lib/python2.6/site-packages/cmpy/infotheory/distributions.pyc in normalize(sel
1233	<pre>total = logaddexp2.reduce(vals, dtype=float)</pre>
1234	if isinf(total):
-> 1235	raise InvalidDistribution(total)
1236	vals -= total
1237	<pre>selfdist = dict(zip(events, vals.tolist()))</pre>

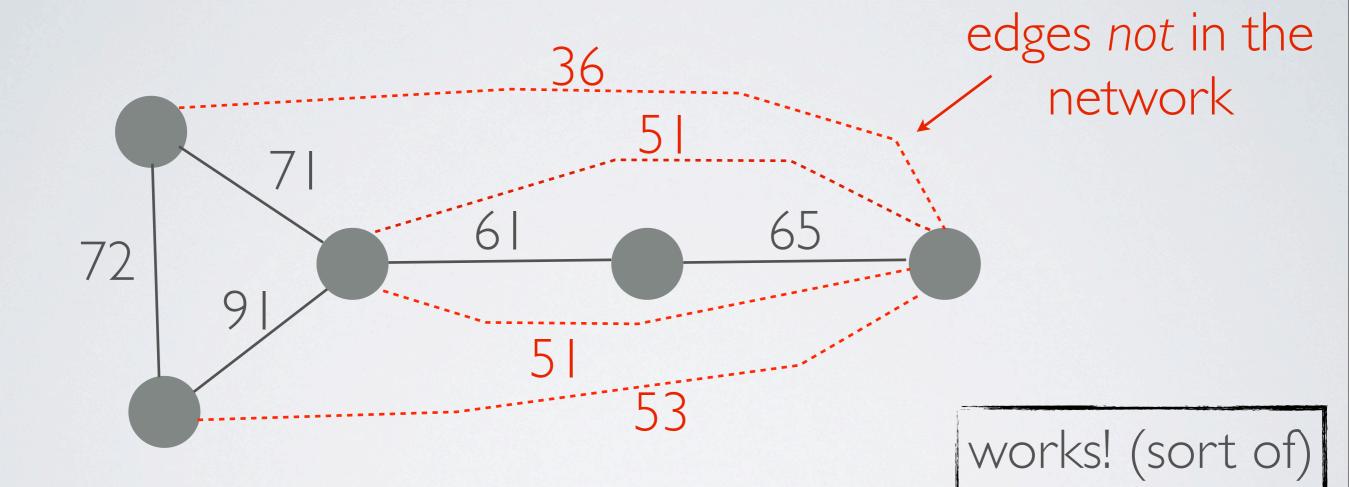
• Reset to asymptotic distribution. But: comparing two time series difficult

INFER NETWORK TOPOLOGY



edge labels: mutual info $\times 10^{-3}$ 100,000 iterates of data, ϵ =0.2

INFER NETWORK TOPOLOGY



edge labels: mutual info $\times 10^{-3}$ 100,000 iterates of data, ϵ =0.2

PART II: CONCLUSIONS

- Inferring topology from information measures is hard but has hope
- Mutual information (no time delay) seems to work better than transfer entropy
- Future:
 - Large networks of maps, other maps (tent, cusp, ...), other topologies (grids, grids with rewires, ...)
 - Information measures tailored toward graphs? e.g., use degree? paths?
 - Use time delay and more history to determine paths?
 - Network of chaotic ODEs: more tractable & coherent than logistic maps?