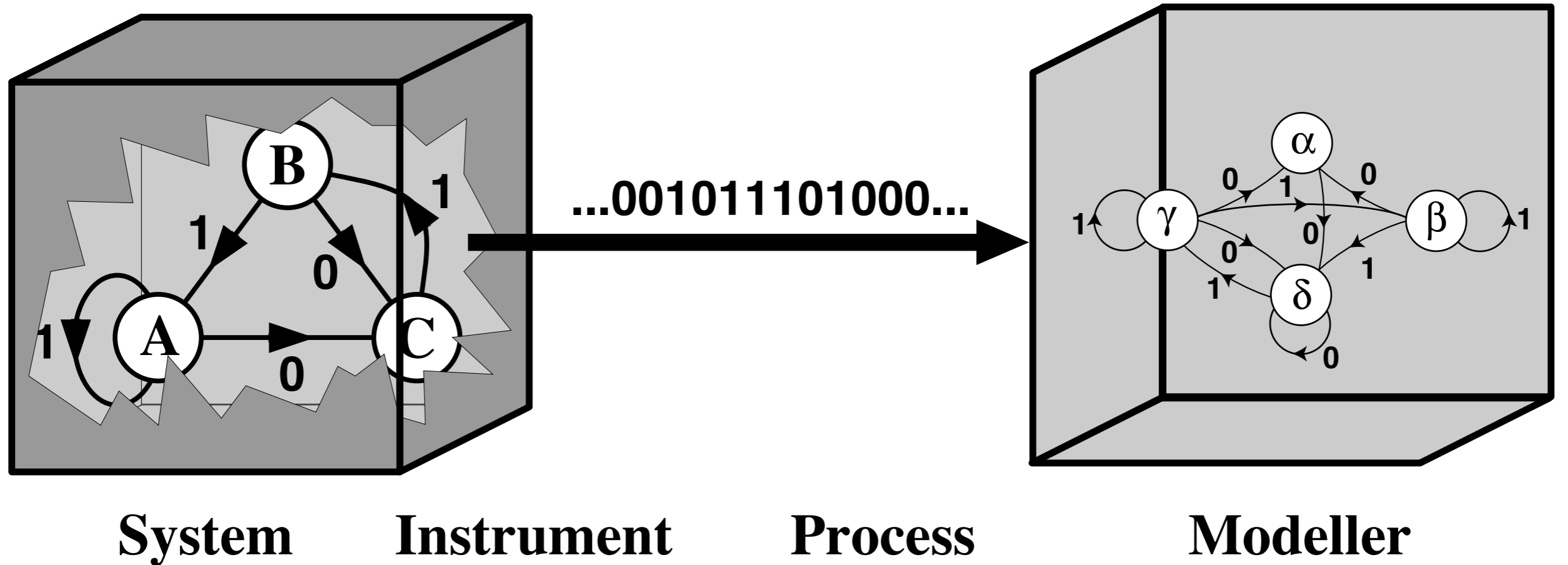


The ϵ -Machine

Reading for this lecture:

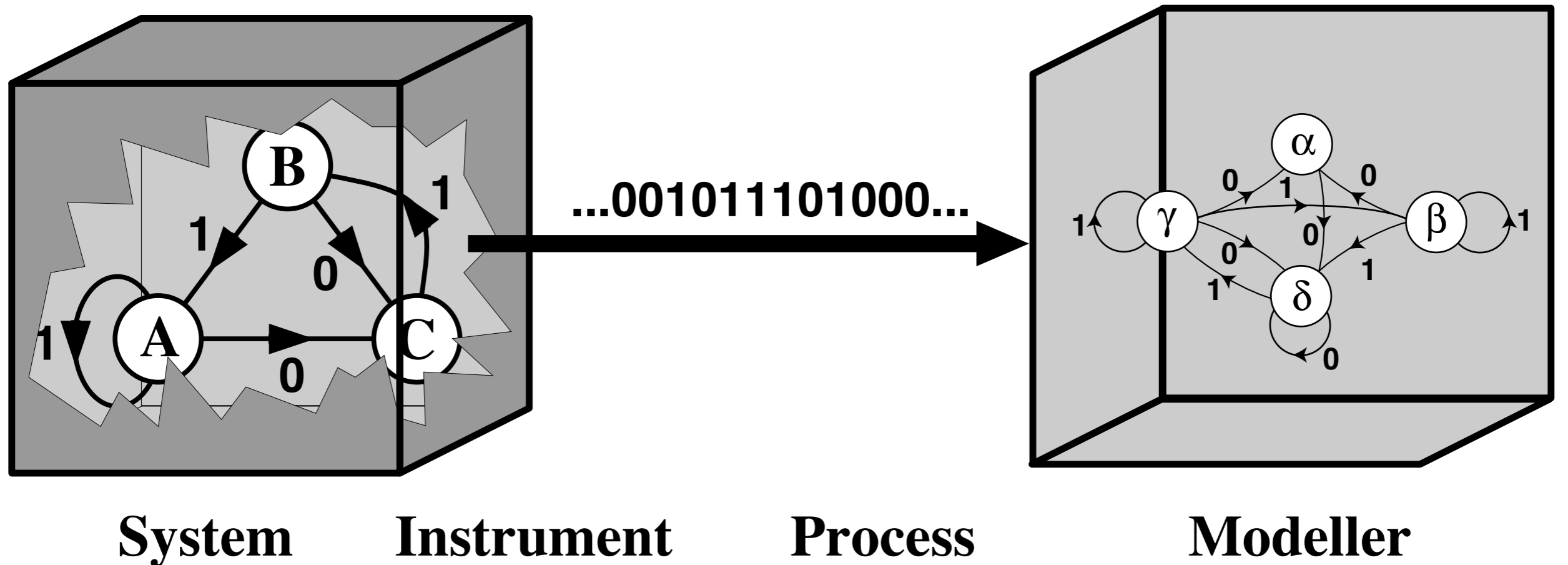
CMR article *CMPPSS* and *Lecture Notes*.

The Learning Channel:



Central questions:
What are the states?
What is the dynamic?

The Learning Channel:



Central questions:

What are the states? Causal States

What is the dynamic? The ϵ -Machine

The ϵ -Machine ...

$$\mathcal{M} = \left\{ \mathcal{S}, \{T^{(s)}, s \in \mathcal{A}\} \right\}$$

Causal State:

$$\overleftarrow{s}' \sim \overleftarrow{s}'' \iff \Pr(\overrightarrow{\mathcal{S}} \mid \overleftarrow{\mathcal{S}} = \overleftarrow{s}') = \Pr(\overrightarrow{\mathcal{S}} \mid \overleftarrow{\mathcal{S}} = \overleftarrow{s}'')$$

$$\overleftarrow{s}', \overleftarrow{s}'' \in \overleftarrow{\mathcal{S}}$$

Causal state set:

$$\mathcal{S} = \overleftarrow{\mathcal{S}} / \sim = \{\mathcal{S}_0, \mathcal{S}_1, \mathcal{S}_2, \dots\}$$

Conditional transition probability:

$$\begin{aligned} T_{ij}^{(s)} &= \Pr(\mathcal{S}_j, s \mid \mathcal{S}_i) \\ &= \Pr\left(\mathcal{S} = \epsilon(\overleftarrow{s} s) \mid \mathcal{S} = \epsilon(\overleftarrow{s})\right) \end{aligned}$$

The ϵ -Machine ...

Process \Rightarrow Predictive equivalence \Rightarrow ϵ -Machine

$$\text{Pr}(\overleftrightarrow{\mathcal{S}}) \Rightarrow \overleftarrow{\mathcal{S}} / \sim \Rightarrow \mathcal{M} = \left\{ \mathcal{S}, \{T^{(s)}, s \in \mathcal{A}\} \right\}$$

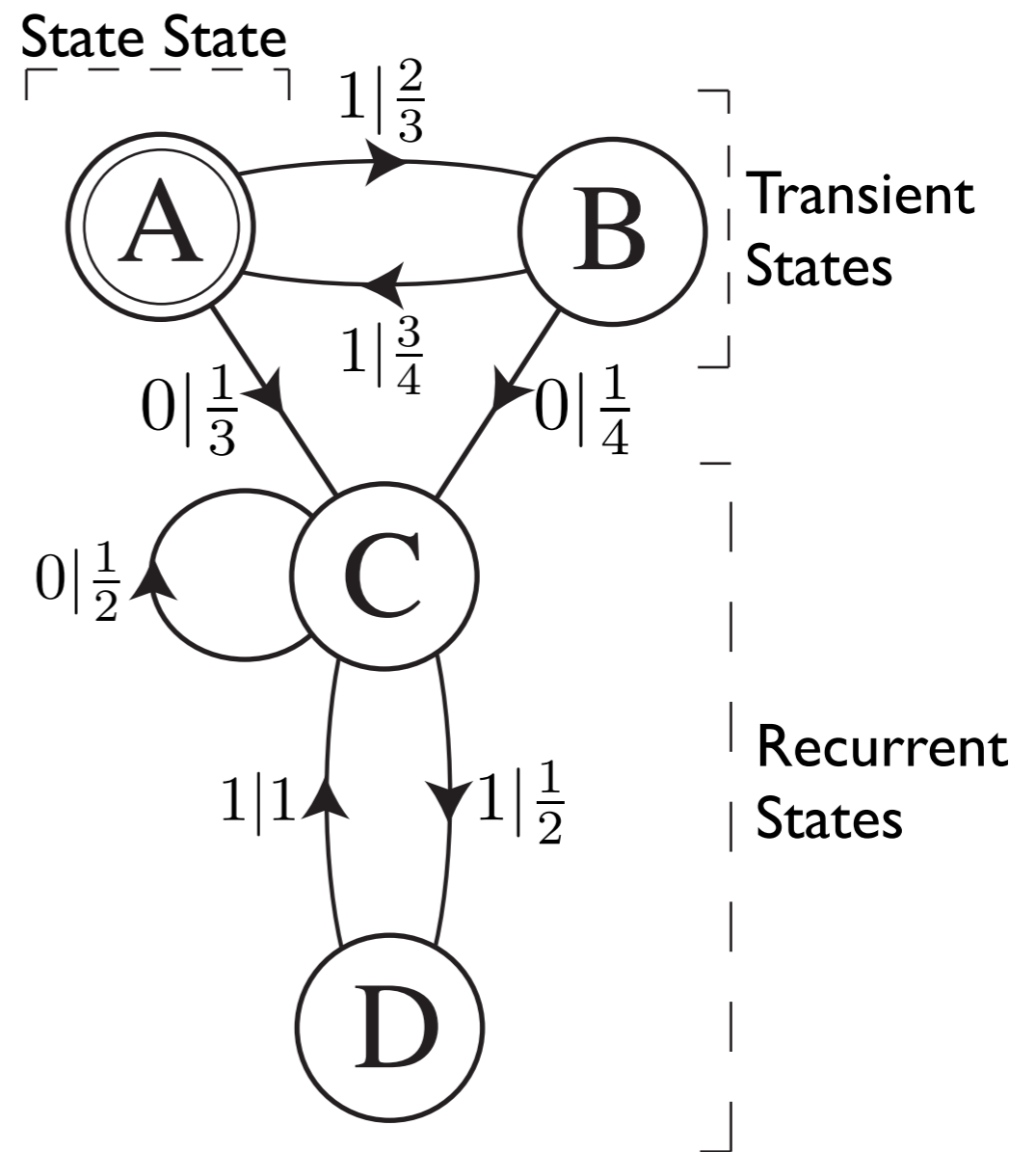
Unique Start State:

$$\mathcal{S}_0 = [\lambda]$$

$$\text{Pr}(\mathcal{S}_0, \mathcal{S}_1, \mathcal{S}_2, \dots) = (1, 0, 0, \dots)$$

Transient States

Recurrent States



The ϵ -Machine ...

Process \Rightarrow Predictive equivalence \Rightarrow ϵ -Machine

$$\text{Pr}(\overleftrightarrow{S}) \Rightarrow \overleftarrow{S} / \sim \Rightarrow \mathcal{M} = \left\{ \mathcal{S}, \{T^{(s)}, s \in \mathcal{A}\} \right\}$$

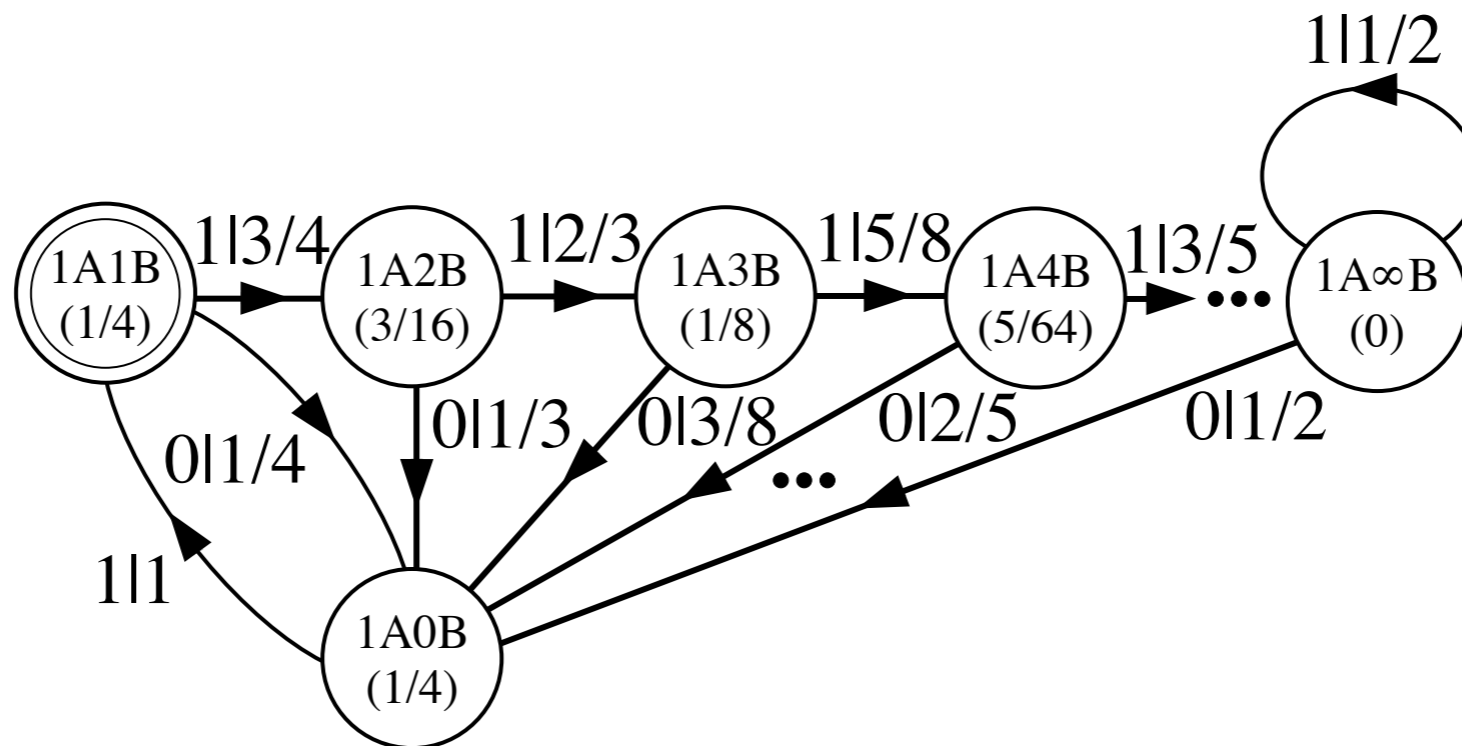
Not always finite state!

The ϵ -Machine ...

Process \Rightarrow Predictive equivalence \Rightarrow ϵ -Machine

$$\text{Pr}(\overleftrightarrow{S}) \Rightarrow \overleftarrow{S} / \sim \Rightarrow \mathcal{M} = \left\{ \mathcal{S}, \{T^{(s)}, s \in \mathcal{A}\} \right\}$$

Not always finite state!



The ϵ -Machine ...

Process \Rightarrow Predictive equivalence \Rightarrow ϵ -Machine

$$\text{Pr}(\overleftrightarrow{S}) \Rightarrow \overleftarrow{S} / \sim \Rightarrow \mathcal{M} = \left\{ \mathcal{S}, \{T^{(s)}, s \in \mathcal{A}\} \right\}$$

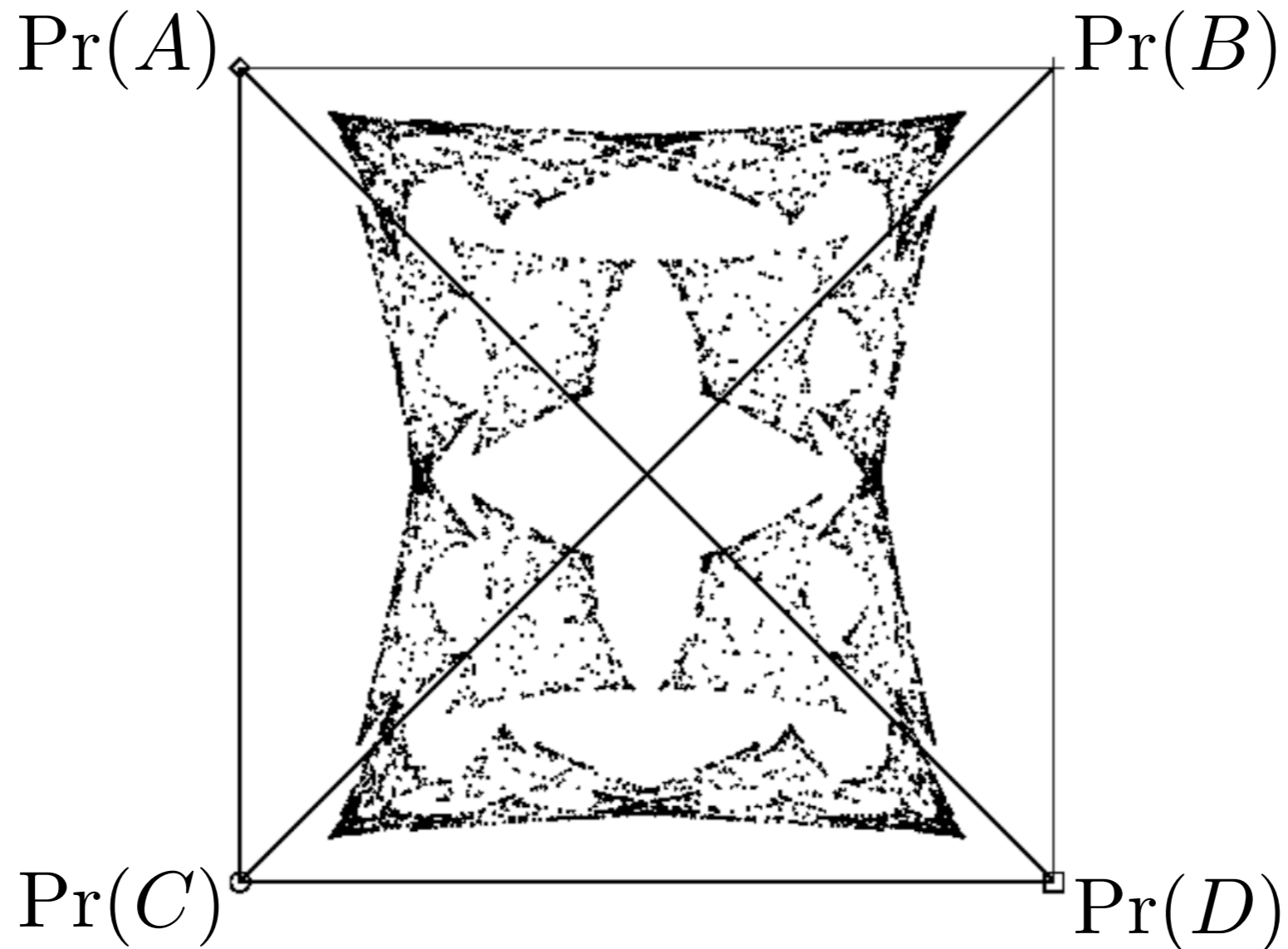
Not always finite state!

The ϵ -Machine ...

Process \Rightarrow Predictive equivalence \Rightarrow ϵ -Machine

$$\text{Pr}(\overleftrightarrow{S}) \Rightarrow \overleftarrow{S} / \sim \Rightarrow \mathcal{M} = \left\{ \mathcal{S}, \{T^{(s)}, s \in \mathcal{A}\} \right\}$$

Not always finite state!



The ϵ -Machine ...

Process \Rightarrow Predictive equivalence \Rightarrow ϵ -Machine

$$\text{Pr}(\overleftrightarrow{S}) \Rightarrow \overleftarrow{S} / \sim \Rightarrow \mathcal{M} = \left\{ \mathcal{S}, \{T^{(s)}, s \in \mathcal{A}\} \right\}$$

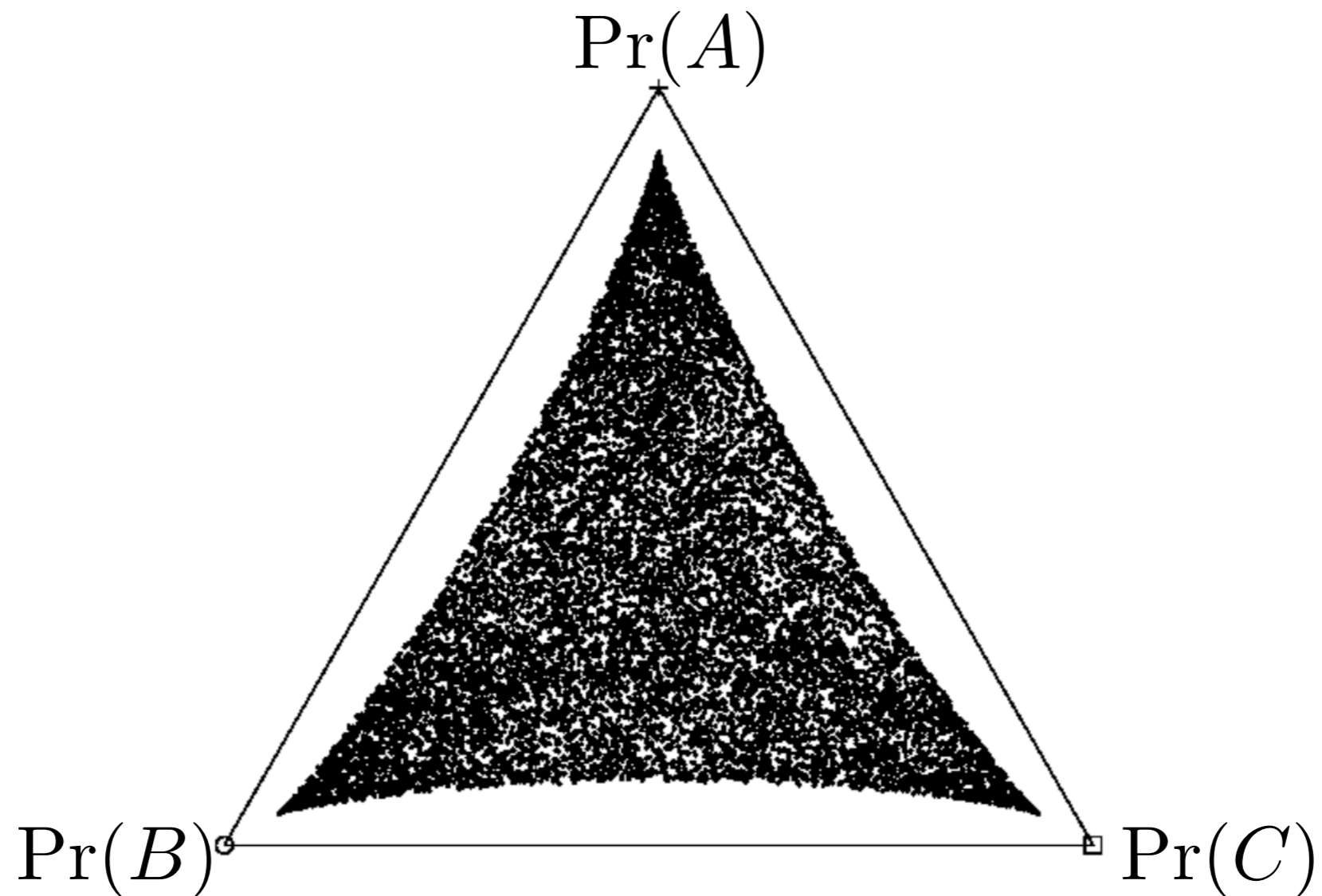
Not always finite state!

The ϵ -Machine ...

Process \Rightarrow Predictive equivalence \Rightarrow ϵ -Machine

$$\text{Pr}(\overleftrightarrow{\mathcal{S}}) \Rightarrow \overleftarrow{\mathbf{S}} / \sim \Rightarrow \mathcal{M} = \left\{ \mathcal{S}, \{T^{(s)}, s \in \mathcal{A}\} \right\}$$

Not always finite state!



The ϵ -Machine ...

A **Model** of a Process $\Pr(\overleftrightarrow{S})$:

ϵ -Machine reproduces the process's word distribution:

$$\Pr(s^1), \Pr(s^2), \Pr(s^3), \dots$$

$$s^L = s_1 s_2 \dots s_L \quad \mathcal{S}(t=0) = \mathcal{S}_0$$

$$\begin{aligned} \Pr(s^L) = & \Pr(\mathcal{S}_0) \Pr(\mathcal{S}_0 \xrightarrow{s=s_1} \mathcal{S}(1)) \Pr(\mathcal{S}(1) \xrightarrow{s=s_2} \mathcal{S}(2)) \\ & \dots \Pr(\mathcal{S}(L-1) \xrightarrow{s=s_L} \mathcal{S}(L)) \end{aligned}$$

Initially, $\Pr(\mathcal{S}_0) = 1$.

$$\Pr(s^L) = \prod_{l=1}^L T_{i=\epsilon(s^{l-1}), j=\epsilon(s^l)}^{(s^l)}$$

The ϵ -Machine ...

A Model of a Process $\text{Pr}(\vec{S})$...

Calculate word distribution from *recurrent states*: $\mathcal{S}_i \in \mathcal{S}_{\text{recurrent}}$

$$\text{Pr}(s^1), \text{Pr}(s^2), \text{Pr}(s^3), \dots$$

Get $\langle \pi | = (p_{\mathcal{S}_1}, p_{\mathcal{S}_2}, \dots)$ from $T = \sum_{s \in \mathcal{A}} T^{(s)}$

Then

$$\text{Pr}(s) = \langle \pi | T^{(s)} | 1 \rangle$$

$$| 1 \rangle = \begin{pmatrix} 1 \\ 1 \\ \vdots \end{pmatrix}$$

$$\text{Pr}(s_0 s_1) = \langle \pi | T^{(s_0)} T^{(s_1)} | 1 \rangle$$

...

$$\text{Pr}(s^L) = \langle \pi | T^{(s^L)} | 1 \rangle$$

$$T^{(s^L)} = T^{(s_0)} T^{(s_1)} \dots T^{(s_{L-1})}$$

The ϵ -Machine ...

Properties:

Shielding: Conditional independence of future & past

Unifilar

Markovian

Optimal predictor

Minimal size

Unique

The ϵ -Machine ...

Causal shielding:

Past and future are independent given causal state: $\overleftarrow{S} \perp_{\mathcal{S}} \overrightarrow{S}$

$$\text{Process: } \Pr(\overleftrightarrow{S}) = \Pr(\overleftarrow{S} \overrightarrow{S})$$

$$\Pr(\overleftrightarrow{S} \mid \mathcal{S}) = \Pr(\overleftarrow{S} \mid \mathcal{S}) \Pr(\overrightarrow{S} \mid \mathcal{S})$$

Causal states shield past & future from each other.

Similar to states of a Markov chain, but for hidden processes.

In fact, there is a Markov chain (in info-theoretic sense):

$$\overleftarrow{X} \Rightarrow \mathcal{S} \Rightarrow \overrightarrow{X}$$

The ϵ -Machine ...

Proof sketch:

$$\begin{aligned}\Pr(\overleftrightarrow{\mathcal{S}} \mid \mathcal{S}) &= \Pr(\overleftarrow{\mathcal{S}} \overrightarrow{\mathcal{S}} \mid \mathcal{S}) \\ &= \Pr(\overrightarrow{\mathcal{S}} \mid \overleftarrow{\mathcal{S}}, \mathcal{S}) \Pr(\overleftarrow{\mathcal{S}} \mid \mathcal{S})\end{aligned}$$

Will show: $\Pr(\overrightarrow{\mathcal{S}} \mid \overleftarrow{\mathcal{S}}, \mathcal{S}) = \Pr(\overrightarrow{\mathcal{S}} \mid \mathcal{S})$

$$\mathcal{S} = \epsilon(\overleftarrow{s}) \Rightarrow$$

$$\Pr\left(\overrightarrow{\mathcal{S}} \mid \overleftarrow{\mathcal{S}} = \overleftarrow{s}', \mathcal{S} = \epsilon(\overleftarrow{s})\right) = \Pr\left(\overrightarrow{\mathcal{S}} \mid \overleftarrow{\mathcal{S}} = \overleftarrow{s}\right) \quad (\overleftarrow{s}' \in [\overleftarrow{s}])$$

But, also, $\Pr\left(\overrightarrow{\mathcal{S}} \mid \overleftarrow{\mathcal{S}} = \overleftarrow{s}\right) = \Pr\left(\overrightarrow{\mathcal{S}} \mid \mathcal{S} = \epsilon(\overleftarrow{s})\right)$ (Causal equiv. rel'n)

So, $\Pr\left(\overrightarrow{\mathcal{S}} \mid \overleftarrow{\mathcal{S}} = \overleftarrow{s}, \mathcal{S} = \sigma\right) = \Pr\left(\overrightarrow{\mathcal{S}} \mid \mathcal{S} = \sigma\right)$ □

The ϵ -Machine ...

ϵ Ms are **Unifilar**: $(\mathcal{S}_t, s) \rightarrow$ unique \mathcal{S}_{t+1}

(in automata theory, “deterministic”)

That is:

(1) $\mathcal{S}_i \in \mathcal{S}$, $s \in \mathcal{A}$, at most one $\mathcal{S}_j \in \mathcal{S}$:

$$\overleftarrow{s} \in \mathcal{S}_i \Rightarrow \overleftarrow{s} s \in \mathcal{S}_j$$

(2) If there is a next causal state j :

$$\mathcal{S}_{k \neq j} \in \mathcal{S} \Rightarrow T_{ik}^{(s)} = 0$$

(3) If there is not:

$$T_{ij}^{(s)} = 0$$

The ϵ -Machine ...

Unifilarity ...

Proof sketch:

Must show $\overleftarrow{s} \sim \overleftarrow{s'} \Rightarrow \overleftarrow{s}s \sim \overleftarrow{s'}s$

Futures with symbol prefixed: sF $F \subseteq \mathcal{A}^{\mathbb{Z}^+}$

$$\overleftarrow{s} \sim \overleftarrow{s'} \Rightarrow \Pr(\overrightarrow{S} \in sF \mid \overleftarrow{S} = \overleftarrow{s}) = \Pr(\overrightarrow{S} \in sF \mid \overleftarrow{S} = \overleftarrow{s'})$$

$$\Pr(\overrightarrow{S}^1 = s, \overrightarrow{S}_1 \in F \mid \overleftarrow{S} = \overleftarrow{s}) = \Pr(\overrightarrow{S}^1 = s, \overrightarrow{S}_1 \in F \mid \overleftarrow{S} = \overleftarrow{s'}) \quad \Pr(X, Y|Z) = \Pr(Y|Z)\Pr(X|Y, Z)$$

$$\Pr(\overrightarrow{S}_1 \in F \mid \overrightarrow{S}^1 = s, \overleftarrow{S} = \overleftarrow{s}) \Pr(\overrightarrow{S}^1 = s \mid \overleftarrow{S} = \overleftarrow{s}) = \Pr(\overrightarrow{S}_1 \in F \mid \overrightarrow{S}^1 = s, \overleftarrow{S} = \overleftarrow{s'}) \Pr(\overrightarrow{S}^1 = s \mid \overleftarrow{S} = \overleftarrow{s'})$$

$$\Pr(\overrightarrow{S}_1 \in F \mid \overleftarrow{S} = \overleftarrow{s}s) = \Pr(\overrightarrow{S}_1 \in F \mid \overleftarrow{S} = \overleftarrow{s'}s)$$

$$\Rightarrow \overleftarrow{s}s \sim \overleftarrow{s'}s \quad \square$$

(Stationarity and
by assumption

$$\Pr(\overrightarrow{S}^1 = s \mid \overleftarrow{s}) = 1$$
$$\Pr(\overrightarrow{S}^1 = s \mid \overleftarrow{s'}) = 1)$$

The ϵ -Machine ...

Unifilarity ...

Consequence:

Unifilarity: 1-1 map between state-sequences & symbol-sequences.

Entropy rate expression requires this 1-1 mapping.

Can (must) use ϵM to calculate entropy rate h_μ .

The ϵ -Machine ...

ϵ Ms are **first-order Markov** in state sequences:

$$\Pr(\mathcal{S}_t | \dots \mathcal{S}_{t-2} \mathcal{S}_{t-1}) = \Pr(\mathcal{S}_t | \mathcal{S}_{t-1})$$

Proof sketch:

Show

$$\Pr(\mathcal{S}_t | \mathcal{S}_{t-2} \mathcal{S}_{t-1}) = \Pr(\mathcal{S}_t | \mathcal{S}_{t-1})$$

(Additional conditioning removed by induction.)

$$\begin{aligned} \Pr(\mathcal{S}_t \in M \subset \mathcal{S} | \mathcal{S}_{t-2} \mathcal{S}_{t-1}) &= \Pr(\overset{\rightarrow 1}{S} \in A \subset \mathcal{A} | \mathcal{S}_{t-2} \mathcal{S}_{t-1}) \\ &= \Pr(\overset{\rightarrow 1}{S} \in A | \mathcal{S}_{t-1}) \quad (\text{Causal shielding}) \\ &= \Pr(\mathcal{S}_t \in M | \mathcal{S}_{t-1}) \quad \square \end{aligned}$$

The ϵ -Machine ...

ϵ Ms are **Optimal Predictors**:

Compared to any rival effective states R :

$$H \left[\begin{array}{c|c} \overrightarrow{S}^L & R \end{array} \right] \geq H \left[\begin{array}{c|c} \overrightarrow{S}^L & S \end{array} \right]$$

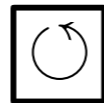
Proof sketch: $H \left[\begin{array}{c|c} \overrightarrow{S}^L & S \end{array} \right] = H \left[\begin{array}{c|c} \overrightarrow{S}^L & \overleftarrow{s} \in S \end{array} \right]$ (Causal equiv. rel'n)

$$= H \left[\begin{array}{c|c} \overrightarrow{S}^L & \overleftarrow{s} \end{array} \right]$$

$$\leq H \left[\begin{array}{c|c} \overrightarrow{S}^L & R \end{array} \right]$$

$$R = \eta(\overleftarrow{s})$$

(Data processing inequality)



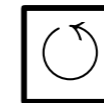
The ϵ -Machine ...

ϵ Ms are Optimal Predictors ...

Lemma:

$$h_\mu(\mathcal{S}) = h_\mu$$

$$\begin{aligned} \text{Proof: } h_\mu(\mathcal{S}) &= \lim_{L \rightarrow \infty} \frac{1}{L} H \left[\overrightarrow{S}^L | \mathcal{S} \right] && \text{(Block entropy)} \\ &= \lim_{L \rightarrow \infty} \frac{1}{L} H \left[\overrightarrow{S}^L | \overleftarrow{S} \right] && \text{(Causal equiv. rel'n)} \\ &= \lim_{L \rightarrow \infty} \frac{1}{L} L H \left[S | \overleftarrow{S} \right] && \text{(Stationarity)} \\ &= H \left[S | \overleftarrow{S} \right] \\ &= h_\mu \end{aligned}$$



Corollary: $h_\mu(R) \geq h_\mu$

The ϵ -Machine ...

ϵ Ms are Optimal Predictors ...

Corollary (**Maximal Prescience**): $\Pi(R) \leq \Pi(\mathcal{S})$

Rival model: $\Pi(R) = \log_2 |\mathcal{A}| - h_\mu(R)$

But: $\Pi(\mathcal{S}) = \log_2 |\mathcal{A}| - h_\mu = \mathbf{G}$

So: $\Pi(R) \leq \Pi(\mathcal{S})$

$$h_\mu(R) \geq h_\mu$$

The ϵ -Machine ...

ϵ Ms are Optimal Predictors ...

Remarks:

- (1) Causal states contain every difference (in past) that makes a difference (to future)
(Recall Bateson “information”)
- (2) Causal states are sufficient statistics for the future.
(See below.)

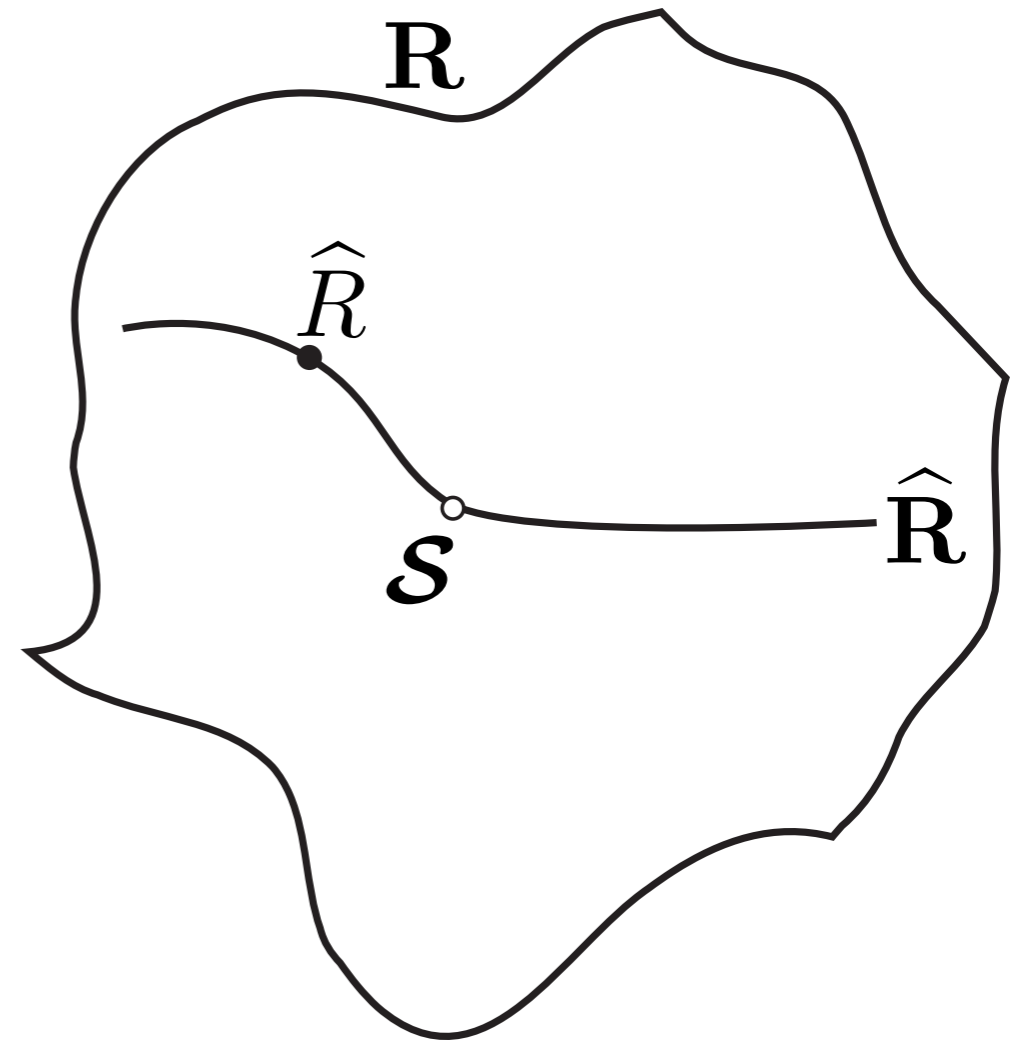
The ϵ -Machine ...

Prescient Rivals $\hat{\mathbf{R}}$:

Alternative models that are optimal predictors

$$\hat{R} \in \hat{\mathbf{R}}$$

$$H[\vec{S}^L | \hat{R}] = H[\vec{S}^L | \mathcal{S}]$$



(Prescient rivals are sufficient statistics for process's future.)

The ϵ -Machine ...

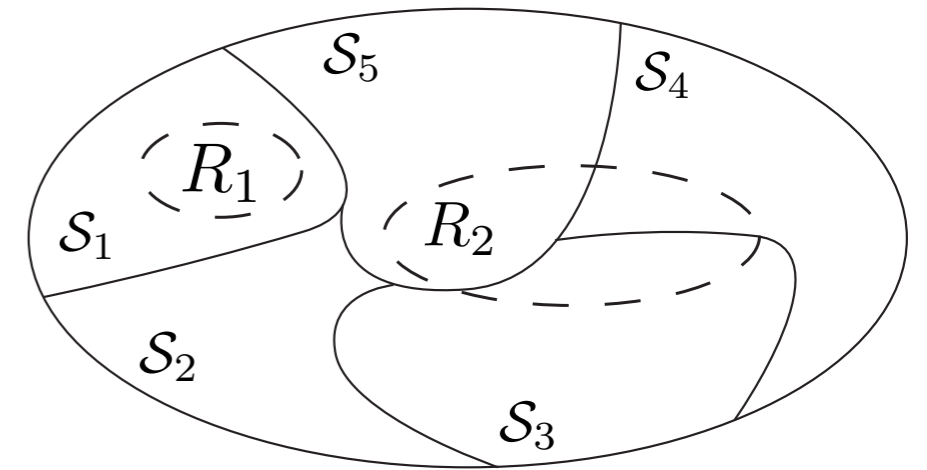
Prescient rivals are refinements of causal states:

Proof sketch:

(1) Either $R_k \subseteq \mathcal{S}_i$:

Then make same prediction,

$$\Pr(\vec{S} | R_k) = \Pr(\vec{S} | \mathcal{S}_i)$$



(2) Or R_k consists of pieces of various \mathcal{S}_i . (Not a refinement.)

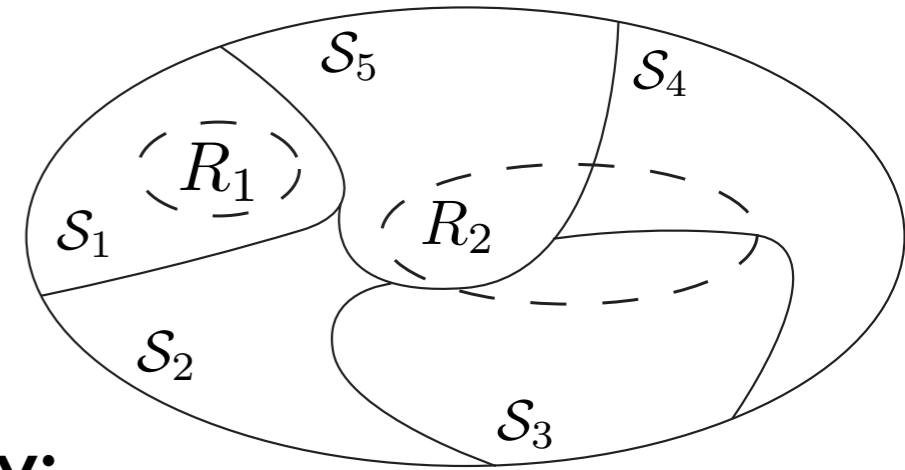
Then its morph is a statistical mixture of various \mathcal{S}_i morphs:

$$\Pr(\vec{S} | R_k) = \sum_i c_i \Pr(\vec{S} | \mathcal{S}_i)$$

The ϵ -Machine ...

Prescient rivals are refinements of causal states:

Proof sketch ...



But mixing distributions increases entropy:

$$H \left[\sum_i c_i P_i \right] \geq \sum_i H(P_i)$$

Thus, worse prediction with rival.

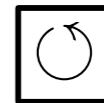
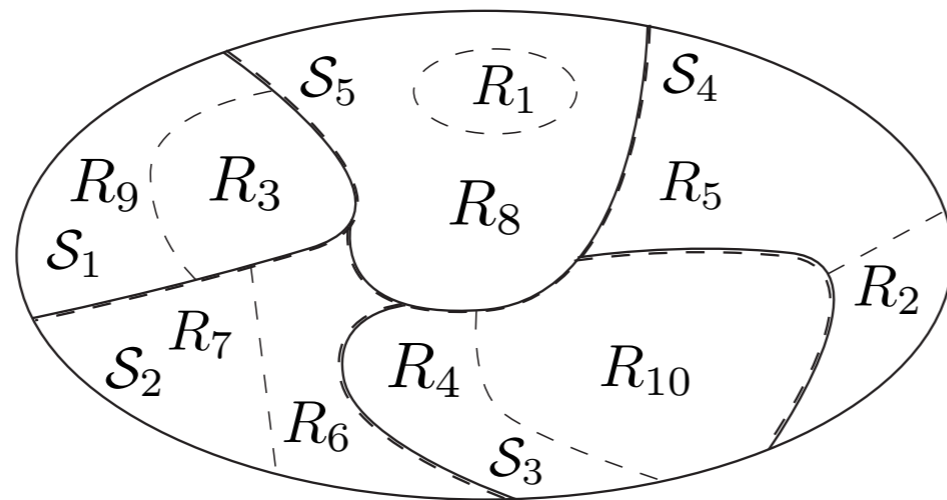
Contradiction!

The ϵ -Machine ...

Prescient rivals are refinements of causal states ...

Proof sketch ...

To be equally prescient, rival must be a refinement:



The ϵ -Machine ...

Minimal Statistical Complexity:

For all prescient rivals, ϵM is the smallest:

$$C_{\mu}(\hat{R}) \geq C_{\mu}(\mathcal{S})$$

Proof sketch:

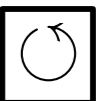
(1) Prescient rivals are refinements, so

$$\exists g : \mathcal{S} = g(\hat{R})$$

(2) But

$$H[f(X)] \leq H[X] \Rightarrow H[\mathcal{S}] = H[g(\hat{R})] \leq H[\hat{R}]$$

(3) So $C_{\mu} \leq H[\hat{R}]$



The ϵ -Machine ...

Minimal Statistical Complexity ...

Consequence:

- (1) C_μ measures historical information process stores.
- (2) This would not be true, if not minimal representation.

The ϵ -Machine ...

ϵ Ms are Unique:

Prescient rival of same size is, up to state relabeling, the ϵ M.

$$C_\mu(\hat{R}) = C_\mu(\mathcal{S}) \Rightarrow \hat{R} = \mathcal{S}$$

Proof Sketch:

(1) Refinement: $\mathcal{S} = g(\hat{R})$

(2) Other way? $f : \hat{R} = f(\mathcal{S})$

(3) Show $H[\hat{R}|\mathcal{S}] = 0$. Consider: $I[\mathcal{S}; \hat{\mathcal{R}}]$

$$H[\mathcal{S}] - H[\mathcal{S}|\hat{R}] = H[\hat{R}] - H[\hat{R}|\mathcal{S}]$$

$$H[\mathcal{S}] = H[\hat{R}] - H[\hat{R}|\mathcal{S}]$$

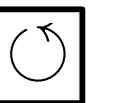
$$H[\mathcal{S}|\hat{R}] = 0$$

$$\text{But } H[\mathcal{S}] = H[\hat{R}]$$

$$\text{So } H[\hat{R}|\mathcal{S}] = 0$$

$$\Rightarrow \hat{R} = f(\mathcal{S})$$

$$\Rightarrow g = f^{-1}$$



The ϵ -Machine ...

ϵ Ms have Minimal State-Stochasticity:

$$H[\hat{\mathcal{R}}_t | \hat{\mathcal{R}}_{t-1}] \geq H[\mathcal{S}_t | \mathcal{S}_{t-1}]$$

Proof Sketch:

(1) Entropy Chain Rule:

$$H[X, Y | Z] = H[Y | Z] + H[X | Y, Z]$$

$$H[\mathcal{S}_t, \vec{S}^1 | \mathcal{S}_{t-1}] = H[\vec{S}^1 | \mathcal{S}_{t-1}] + H[\mathcal{S}_t | \vec{S}^1, \mathcal{S}_{t-1}]$$

(2) Unfilarity:

$$H[\mathcal{S}_t | \mathcal{S}_{t-1}, \vec{S}^1] = 0$$

(3) So:

$$H[\vec{S}^1 | \mathcal{S}_{t-1}] = H[\mathcal{S}_t, \vec{S}^1 | \mathcal{S}_{t-1}]$$

The ϵ -Machine ...

ϵ Ms have Minimal State-Stochasticity ...

(4) Again:

$$\begin{aligned} H \left[\hat{\mathcal{R}}_t, \vec{S}^1 \mid \hat{\mathcal{R}}_{t-1} \right] &= H \left[\vec{S}^1 \mid \hat{\mathcal{R}}_{t-1} \right] + H \left[\hat{\mathcal{R}}_t \mid \vec{S}^1, \hat{\mathcal{R}}_{t-1} \right] \\ &\geq H \left[\vec{S}^1 \mid \hat{\mathcal{R}}_{t-1} \right] \\ &= H \left[\vec{S}^1 \mid \mathcal{S}_{t-1} \right] \quad \text{(Refinement)} \\ &= H \left[\mathcal{S}_t, \vec{S}^1 \mid \mathcal{S}_{t-1} \right] \end{aligned}$$

(5) Also, by chain rule:

$$H \left[\hat{\mathcal{R}}_t, \vec{S}^1 \mid \hat{\mathcal{R}}_{t-1} \right] = H \left[\hat{\mathcal{R}}_t \mid \hat{\mathcal{R}}_{t-1} \right] + H \left[\vec{S}^1 \mid \hat{\mathcal{R}}_t, \hat{\mathcal{R}}_{t-1} \right]$$

(6) Putting (4) and (5) together gives:

$$H \left[\hat{\mathcal{R}}_t \mid \hat{\mathcal{R}}_{t-1} \right] + H \left[\vec{S}^1 \mid \hat{\mathcal{R}}_t, \hat{\mathcal{R}}_{t-1} \right] \geq H \left[\mathcal{S}_t, \vec{S}^1 \mid \mathcal{S}_{t-1} \right]$$

The ϵ -Machine ...

ϵ Ms have Minimal State-Stochasticity ...

(7) Expand RHS of (6) and re-arrange:

$$H[\hat{\mathcal{R}}_t | \hat{\mathcal{R}}_{t-1}] - H[\mathcal{S}_t | \mathcal{S}_{t-1}] \geq H \left[\overset{\rightarrow 1}{S} | \mathcal{S}_t, \mathcal{S}_{t-1} \right] - H \left[\overset{\rightarrow 1}{S} | \hat{\mathcal{R}}_t, \hat{\mathcal{R}}_{t-1} \right]$$

(8) Note:

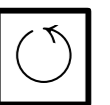
$$\mathcal{S}_t = g(\hat{\mathcal{R}}_t) \Rightarrow (\mathcal{S}_t, \mathcal{S}_{t-1}) = g'(\hat{\mathcal{R}}_t, \hat{\mathcal{R}}_{t-1})$$

(9) So,

$$H \left[\overset{\rightarrow 1}{S} | \hat{\mathcal{R}}_t, \hat{\mathcal{R}}_{t-1} \right] \leq H \left[\overset{\rightarrow 1}{S} | \mathcal{S}_t, \mathcal{S}_{t-1} \right] \quad H[X|Y] \leq H[X|g(Y)]$$

(10) And so RHS of (7) > 0 and we have:

$$H[\hat{\mathcal{R}}_t | \hat{\mathcal{R}}_{t-1}] \geq H[\mathcal{S}_t | \mathcal{S}_{t-1}]$$



The ϵ -Machine ...

Random variable $X \sim \text{Pr}_\theta(x)$

Sufficient statistic $T(X)$ for θ :

[EIT, Section 2.9]

Contains all info in X for θ .

That is, $I[\theta; X] = I[\theta; T(X)]$

Minimal sufficient statistic:

$T(X)$ is a function of every other sufficient statistic $U(X)$.

The ϵ -Machine ...

ϵ M is a **Minimal Sufficient Statistic** for a Process.

Proof Sketch:

(1) Maximal prescience gives sufficiency:

$$I[\vec{S}^L; \mathcal{S}] = I[\vec{S}^L; \overleftarrow{S}]$$

(2) In fact, every prescient rival $\hat{\mathcal{R}}$ is a sufficient statistic.

$$I[\vec{S}^L; \hat{\mathcal{R}}] = I[\vec{S}^L; \overleftarrow{S}]$$

(3) ϵ M is minimal sufficient statistic:

Rival states are refinements of causal states: $\mathcal{S} = g(\hat{\mathcal{R}})$. 

Lesson: You can calculate everything about process from its ϵ M.

The ϵ -Machine ...

Summary:

ϵM :

- (1) Optimal predictor: Lower prediction error than any rival.
- (2) Minimal size: Smallest of the prescient rivals.
- (3) Unique: Any smallest, optimal, unifilar predictor is equivalent.
- (4) Model of the process: Reproduces all of process's statistics.
- (5) Causal shielding: Renders process's future independent of past.

The ϵ -Machine ...

Dynamical system's **intrinsic computation**:

- (1) How much of past does process store?
- (2) In what architecture is that information stored?
- (3) How is stored information used to produce future behavior?

The ϵ -Machine ...

Reading for next lecture:

CMR articles *CMPPSS* & *RURO*.