

The Big, Big Picture

Reading for this lecture:

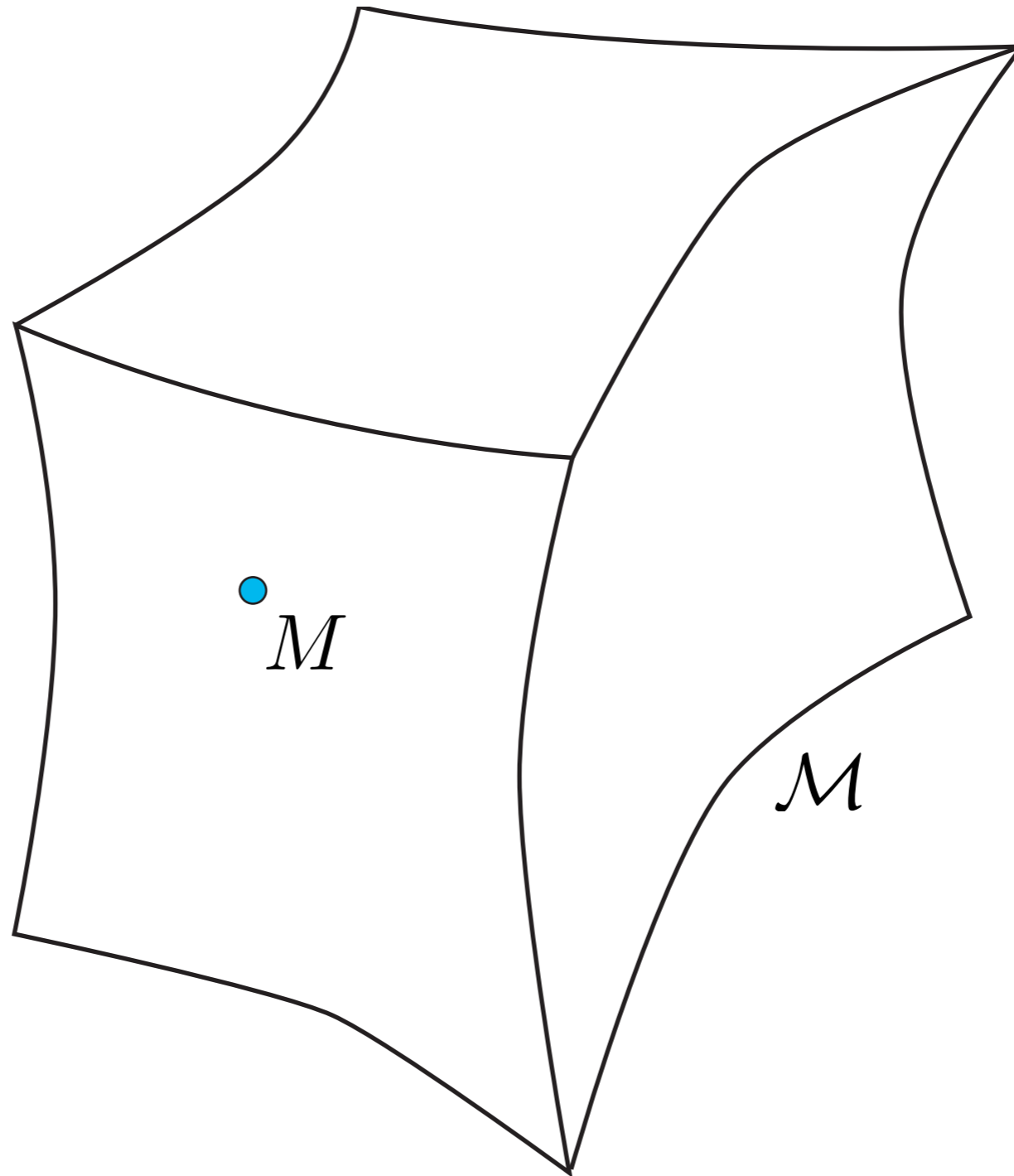
NDAC, Chapter 3

Projects!

The Big, Big Picture (Bifurcations I) ...

Space of all dynamical systems: \mathcal{M}

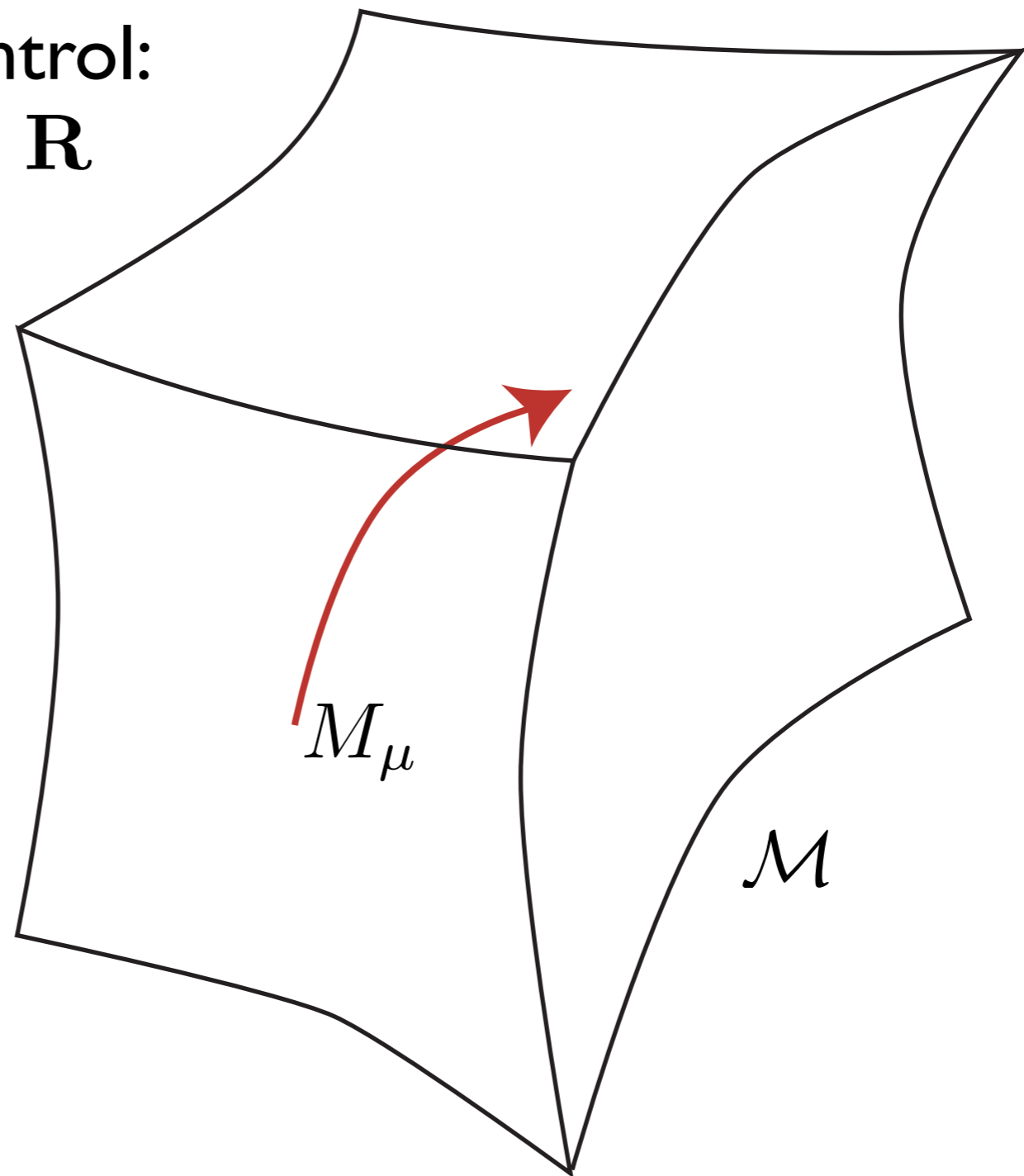
a particular dynamical system: $M \in \mathcal{M}$



The Big, Big Picture (Bifurcations I) ...

Model of experimental control:

an arc in \mathcal{M} : M_μ , $\mu \in \mathbf{R}$



What happens as μ is varied?

The arena of Bifurcation Theory

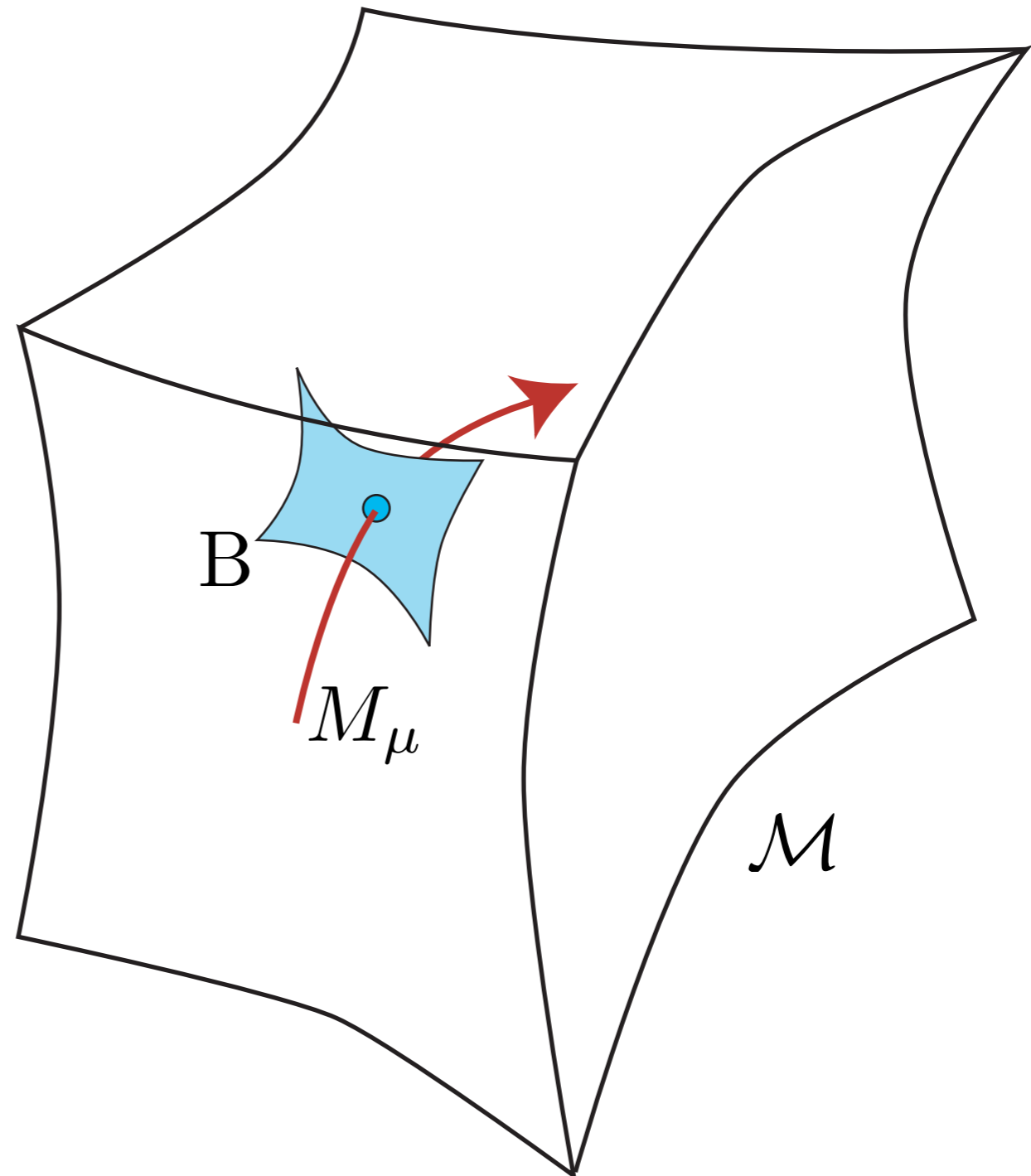
The Big, Big Picture (Bifurcations I) ...

Bifurcation Theory:

Bifurcation: Qualitative change in behavior
as parameter is (slowly) varied

Bifurcation surface: B

“Change”
= Topologically
distinct behaviors

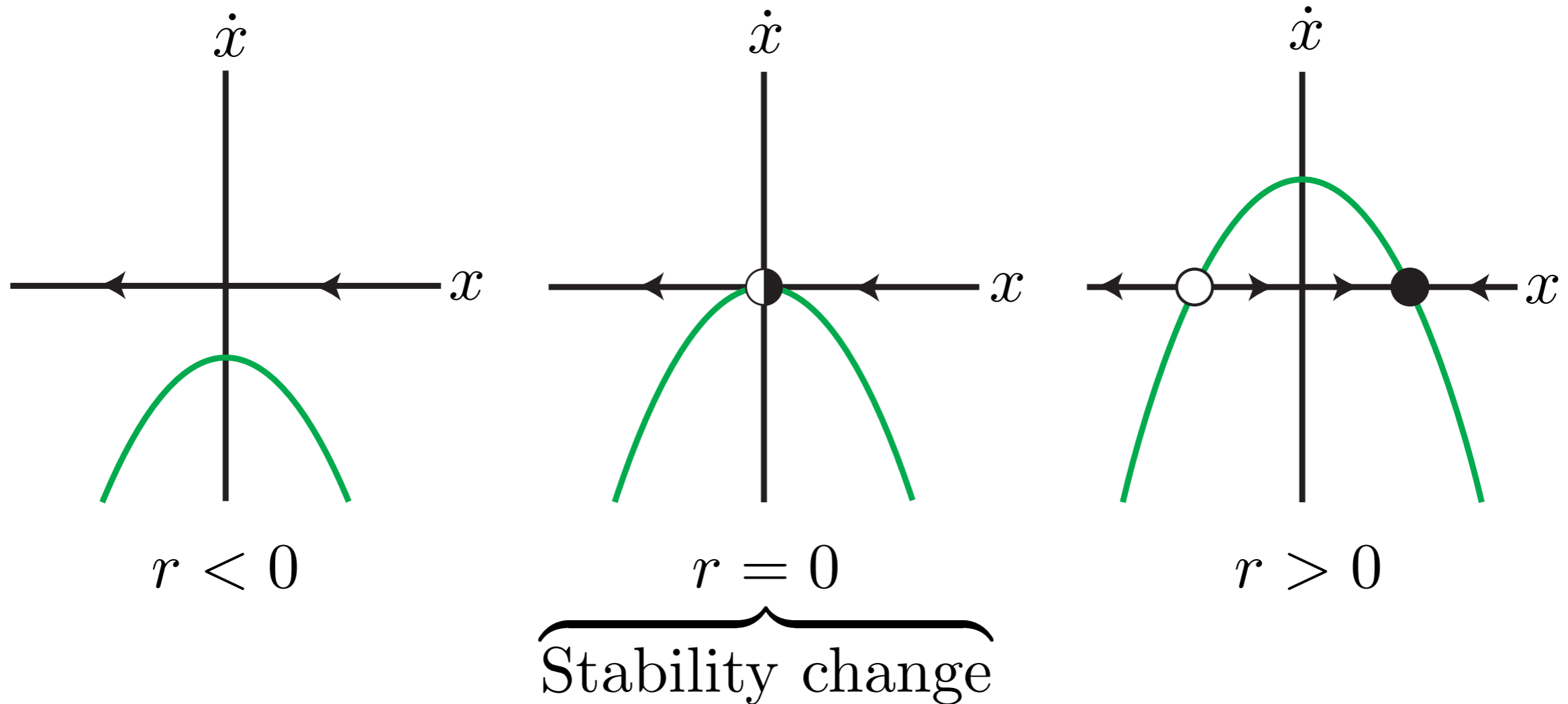


The Big, Big Picture (Bifurcations I) ...

Bifurcation Theory of 1D Flows:

Saddle node bifurcation: Blue-Sky Catastrophe

Normal Form: $\dot{x} = r - x^2$



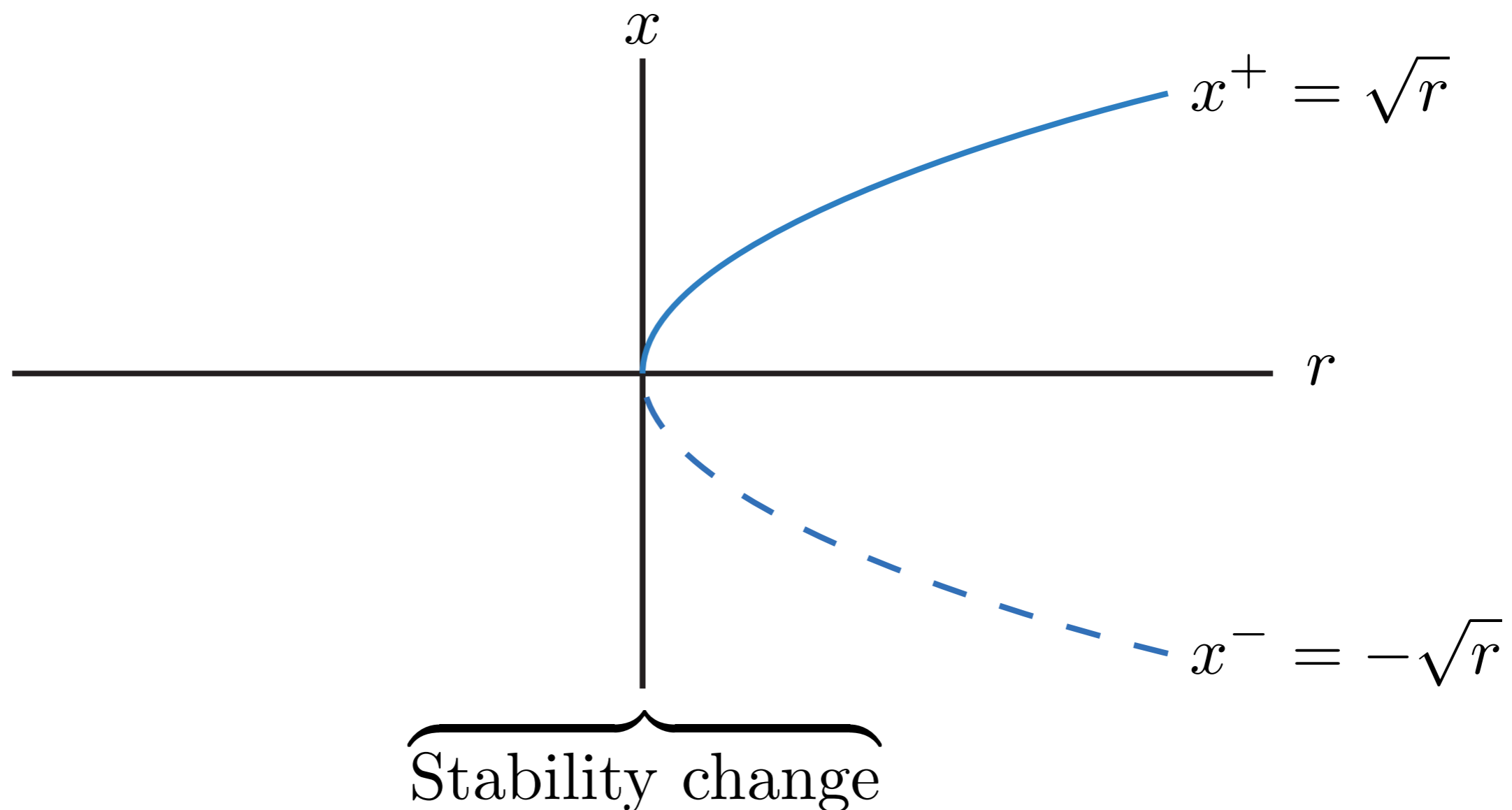
The Big, Big Picture (Bifurcations I) ...

Bifurcation Theory of 1D Flows ...

Bifurcation diagram: Attractor(s) versus parameter

Saddle node bifurcation diagram:

Fixed point(s) versus parameter

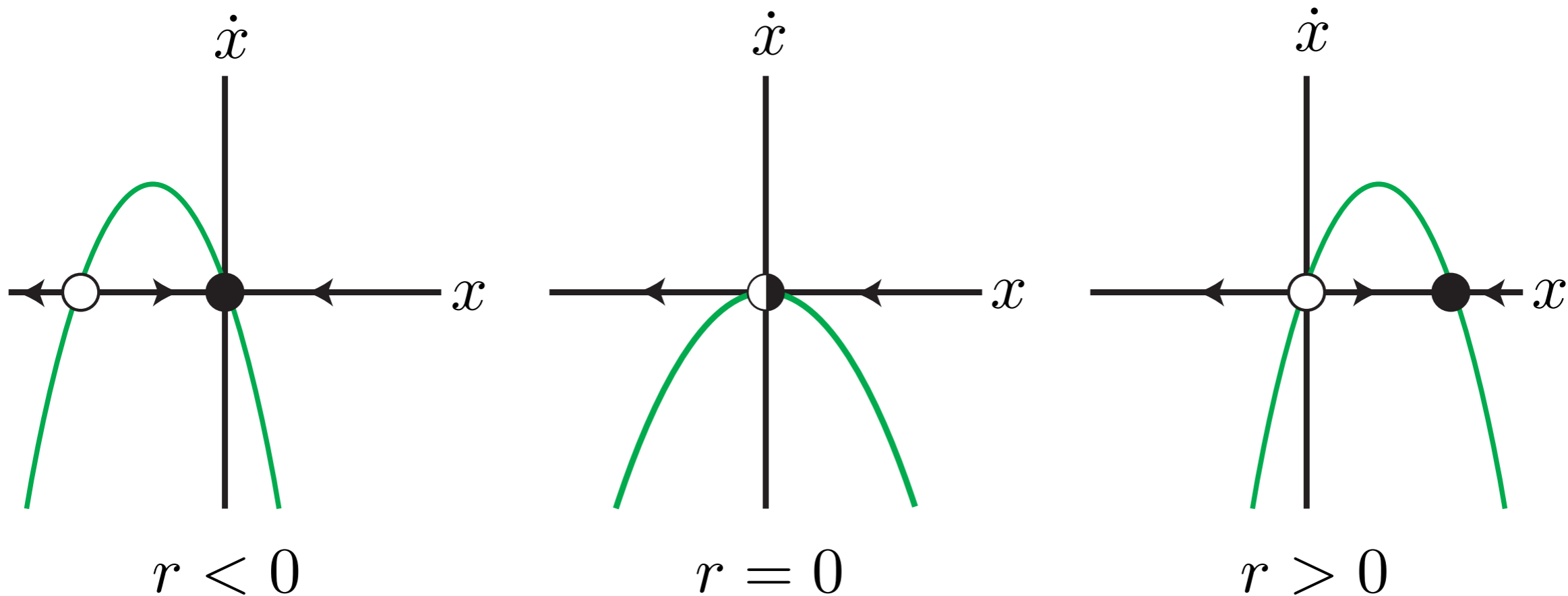


The Big, Big Picture (Bifurcations I) ...

Bifurcation Theory of 1D Flows ...

Transcritical bifurcation: exchange of stability

Normal form: $\dot{x} = rx - x^2$

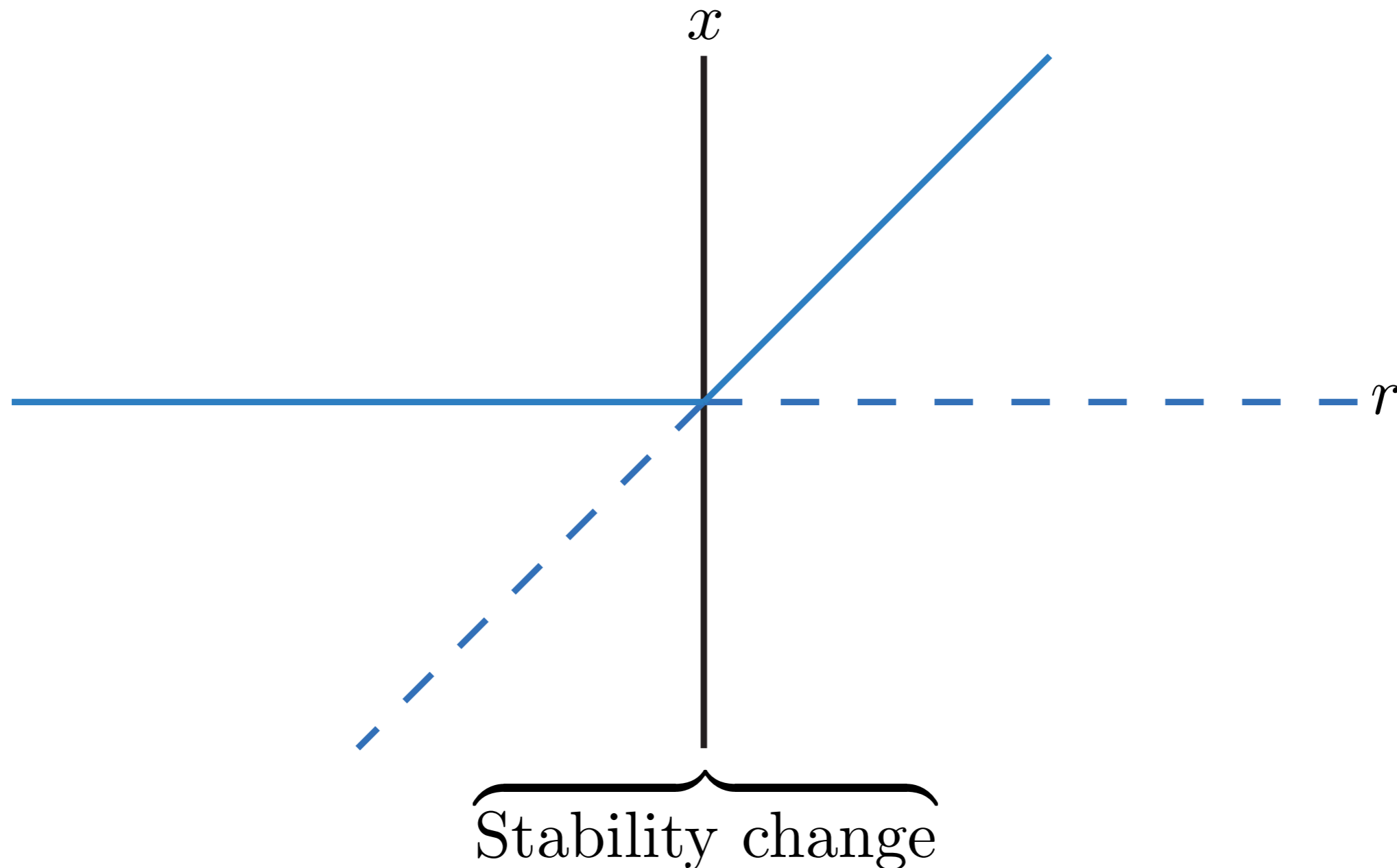


Stability change

The Big, Big Picture (Bifurcations I) ...

Bifurcation Theory of 1D Flows ...

Transcritical bifurcation diagram: Fixed points versus parameter

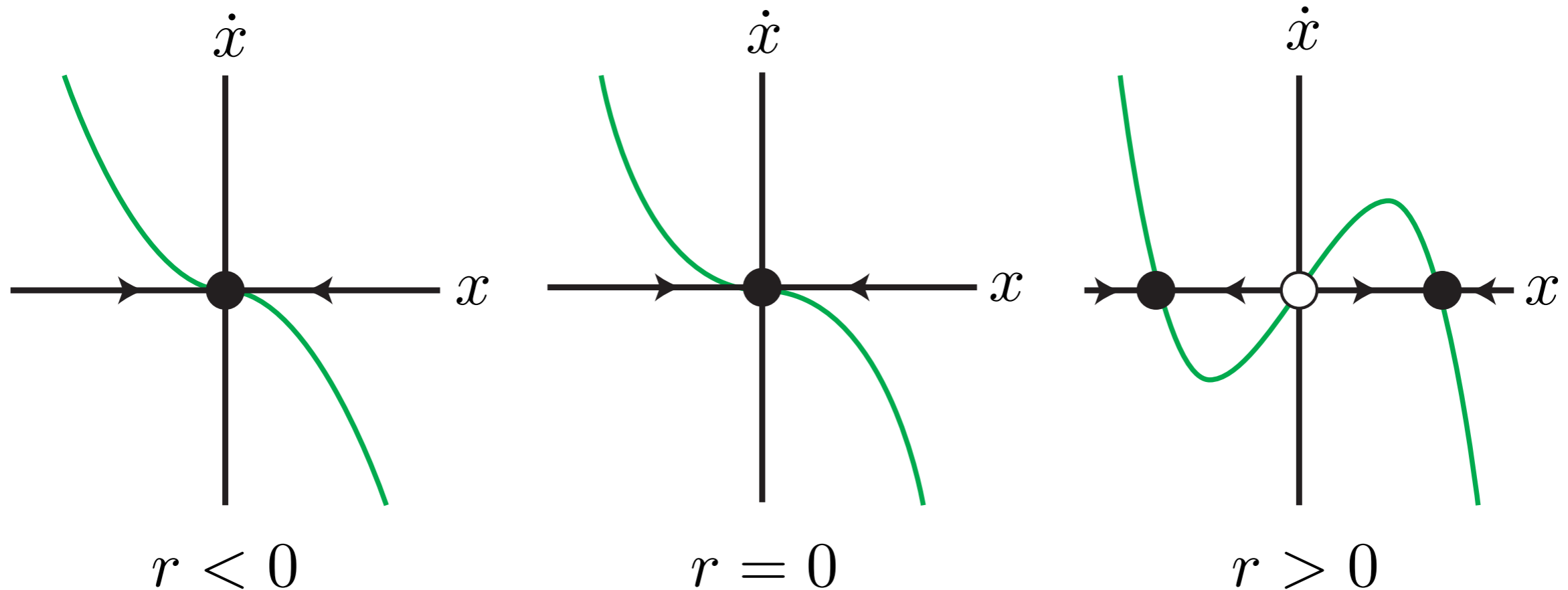


The Big, Big Picture (Bifurcations I) ...

Bifurcation Theory of 1D Flows ...

Pitchfork bifurcation:

Normal Form: $\dot{x} = rx - x^3$



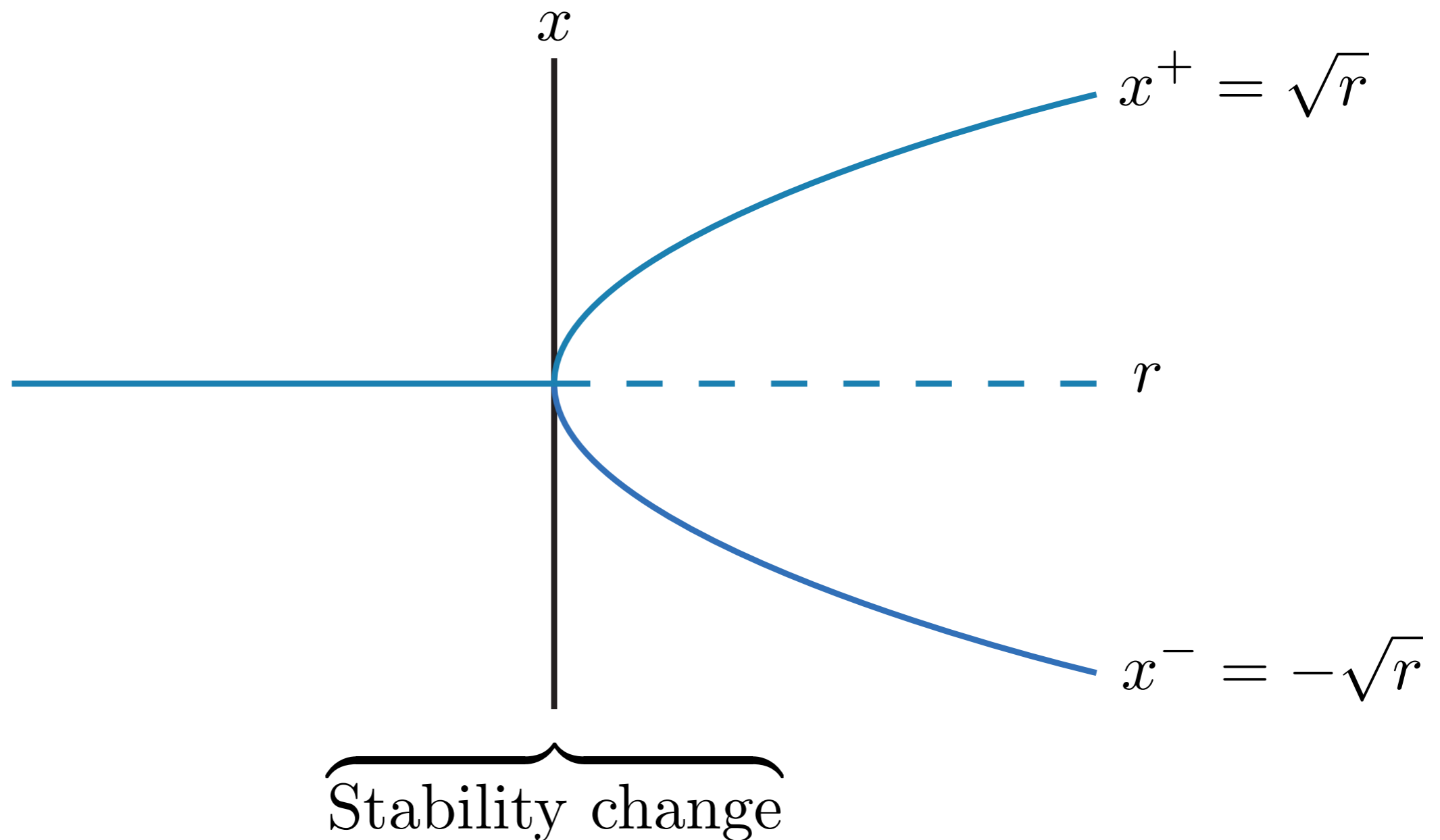
Stability change

The Big, Big Picture (Bifurcations I) ...

Bifurcation Theory of 1D Flows:

Pitchfork bifurcation diagram:

Fixed points versus parameter



The Big, Big Picture (Bifurcations I) ...

Bifurcation Theory of 1D Flows ...

Effective Potential: $V(x)$

Given: $\dot{x} = f(x)$

Can we find $\dot{x} = -\frac{\partial V(x)}{\partial x}$?

$$V(x) = -\int dx f(x)$$

Pitchfork bifurcation:

$$\dot{x} = rx - x^3$$

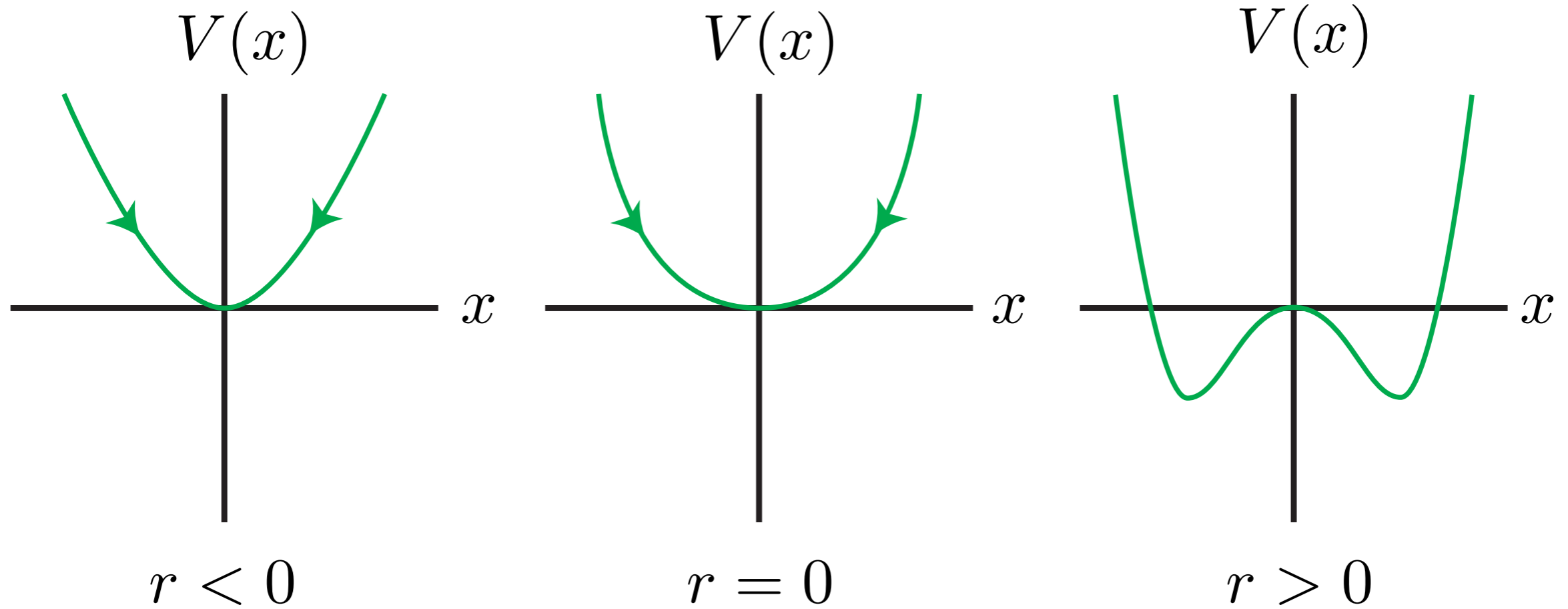
$$V(x) = -\frac{1}{2}rx^2 + \frac{1}{4}x^4$$

The Big, Big Picture (Bifurcations I) ...

Bifurcation Theory of 1D Flows ...

Pitchfork bifurcation:

Effective Potential: $V(x) = -\frac{1}{2}rx^2 + \frac{1}{4}x^4$



Stability change

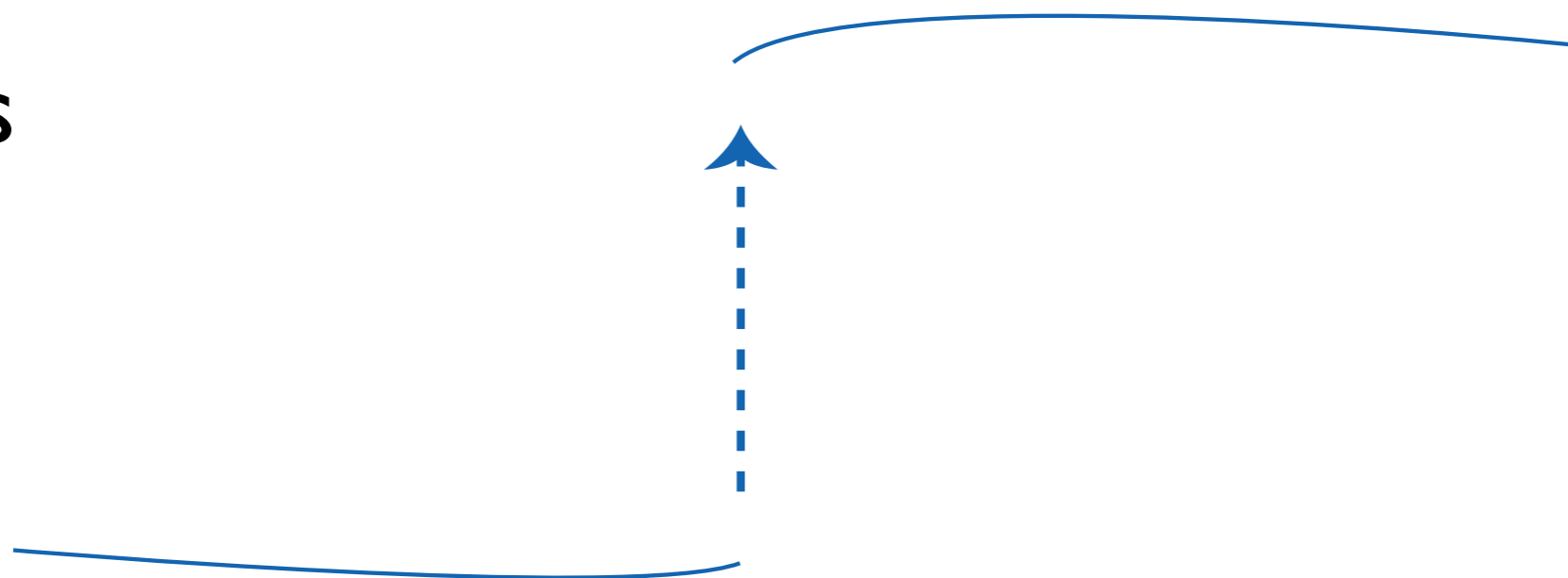
The Big, Big Picture (Bifurcations I) ...

Catastrophe Theory:

Bifurcations from a fixed point to a fixed point
beyond “gradual” changes in equilibria
a model of sudden, large change in **behavior**
... and a new classification scheme

Behaviors

x^*



$\mu \rightarrow$

Control parameters

The Big, Big Picture (Bifurcations I) ...

Catastrophe Theory ...

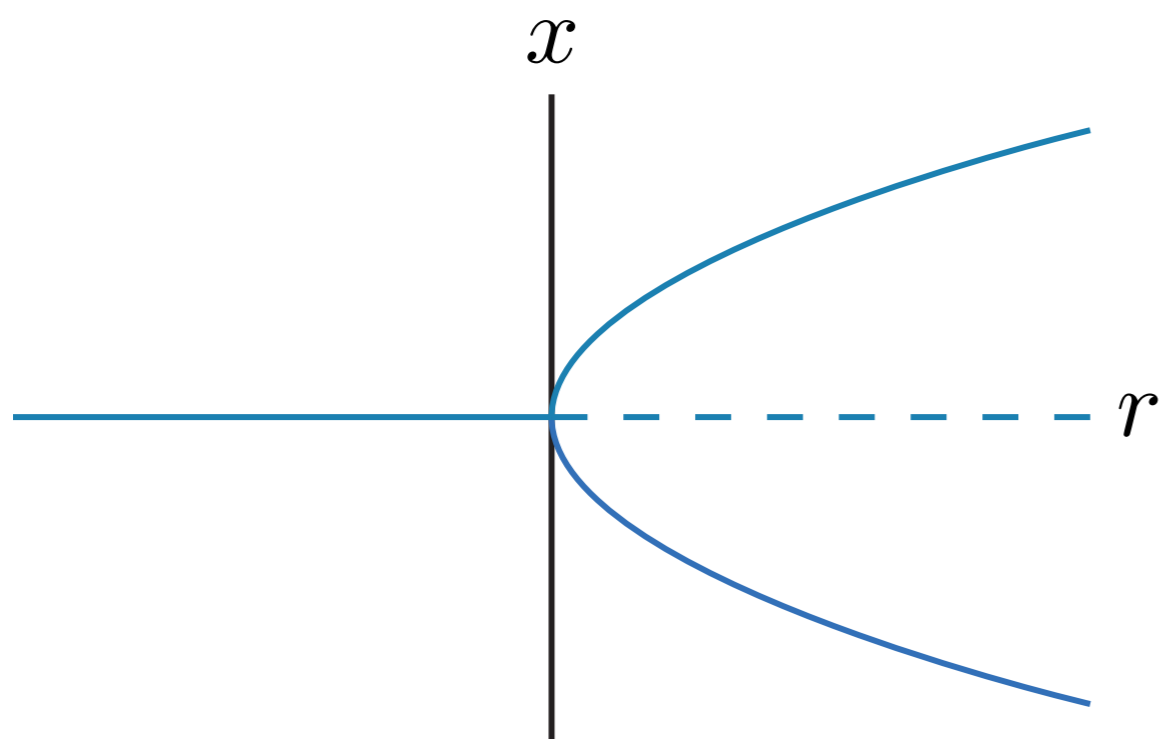
Cusp Catastrophe: two control parameters, one behavior

Normal form: $\dot{x} = h + rx - x^3$

Effective potential: $V(x) = \frac{1}{4}x^4 - \frac{1}{2}rx^2 - hx$

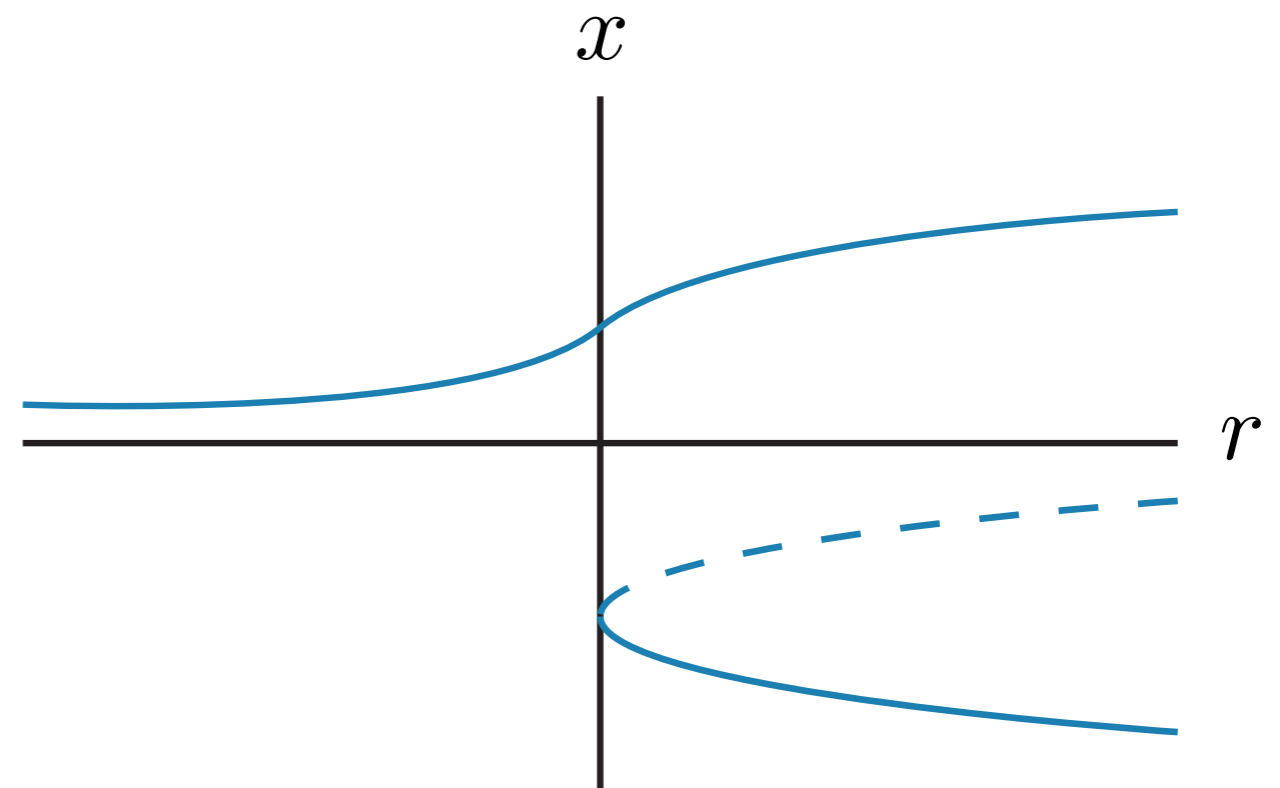
Pitchfork bifurcation:

$$h = 0$$



Broken symmetry:

$$h \neq 0$$



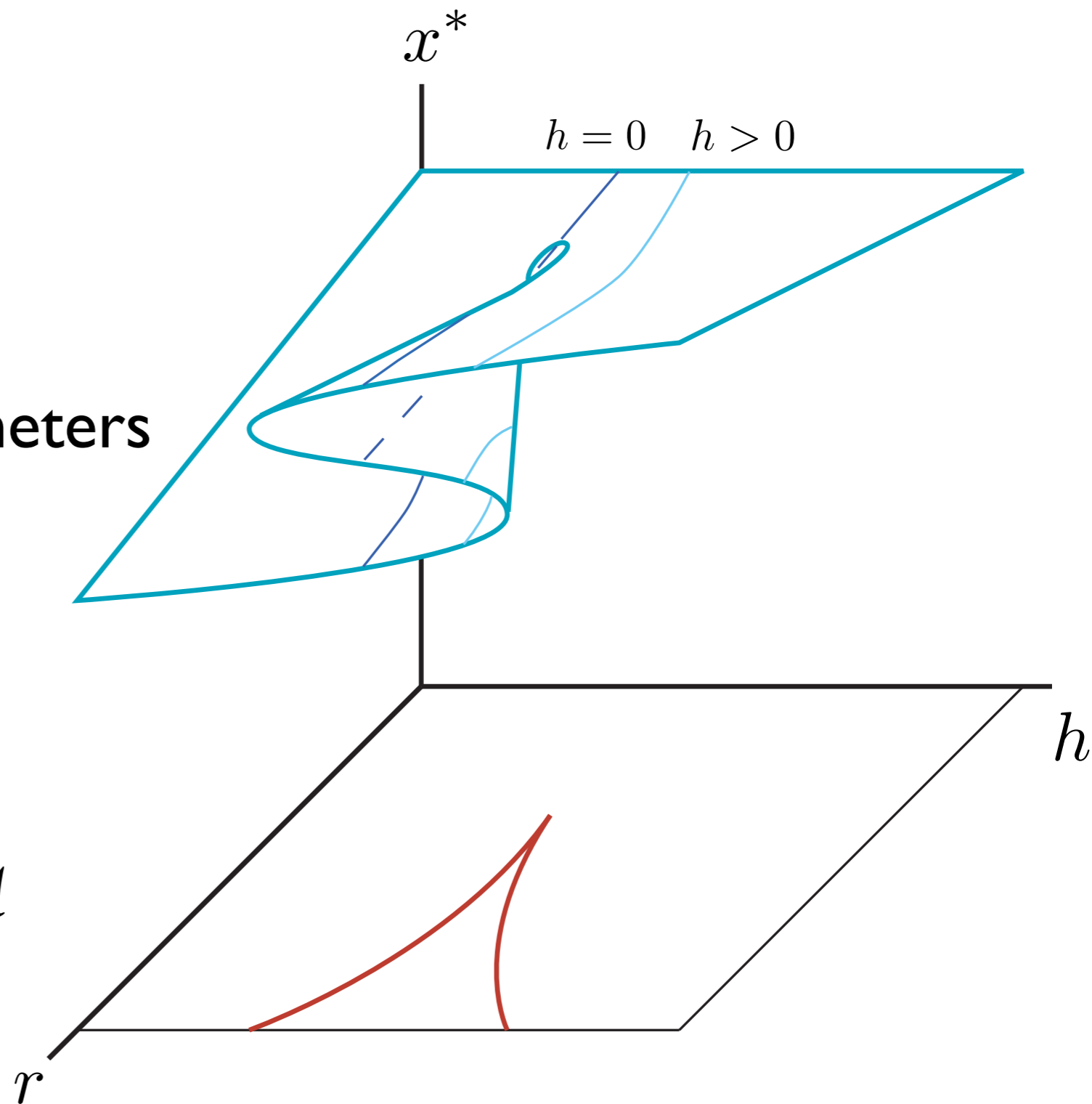
The Big, Big Picture (Bifurcations I) ...

Catastrophe Theory ...

Cusp Catastrophe ...

Behavior Surface:

fixed points $\{x^*\}$ v. parameters



Control Space: $(r, h) \in \mathcal{M}$

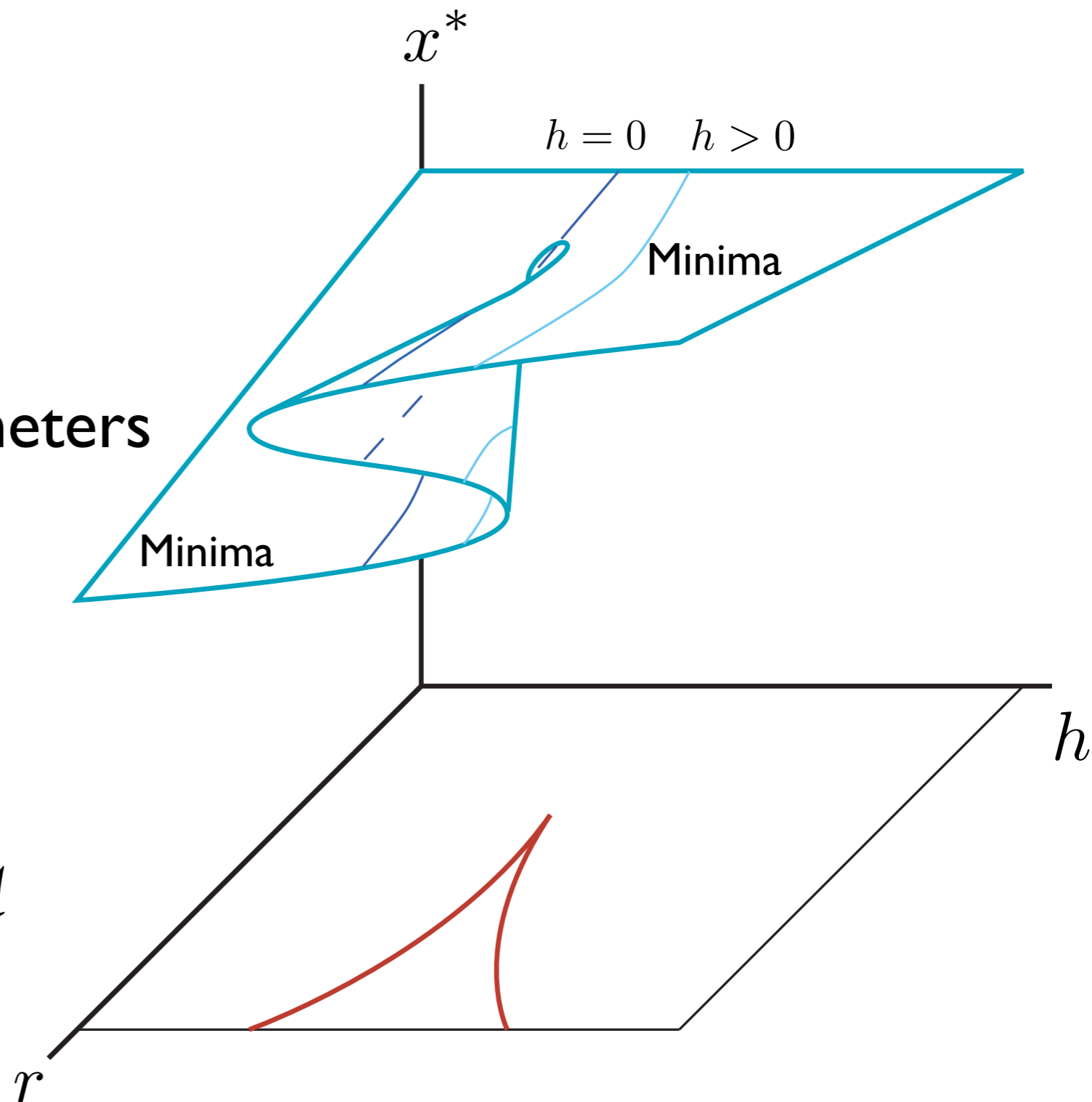
The Big, Big Picture (Bifurcations I) ...

Catastrophe Theory ...

Cusp Catastrophe ...

Behavior Surface:

fixed points $\{x^*\}$ v. parameters



Control Space: $(r, h) \in \mathcal{M}$

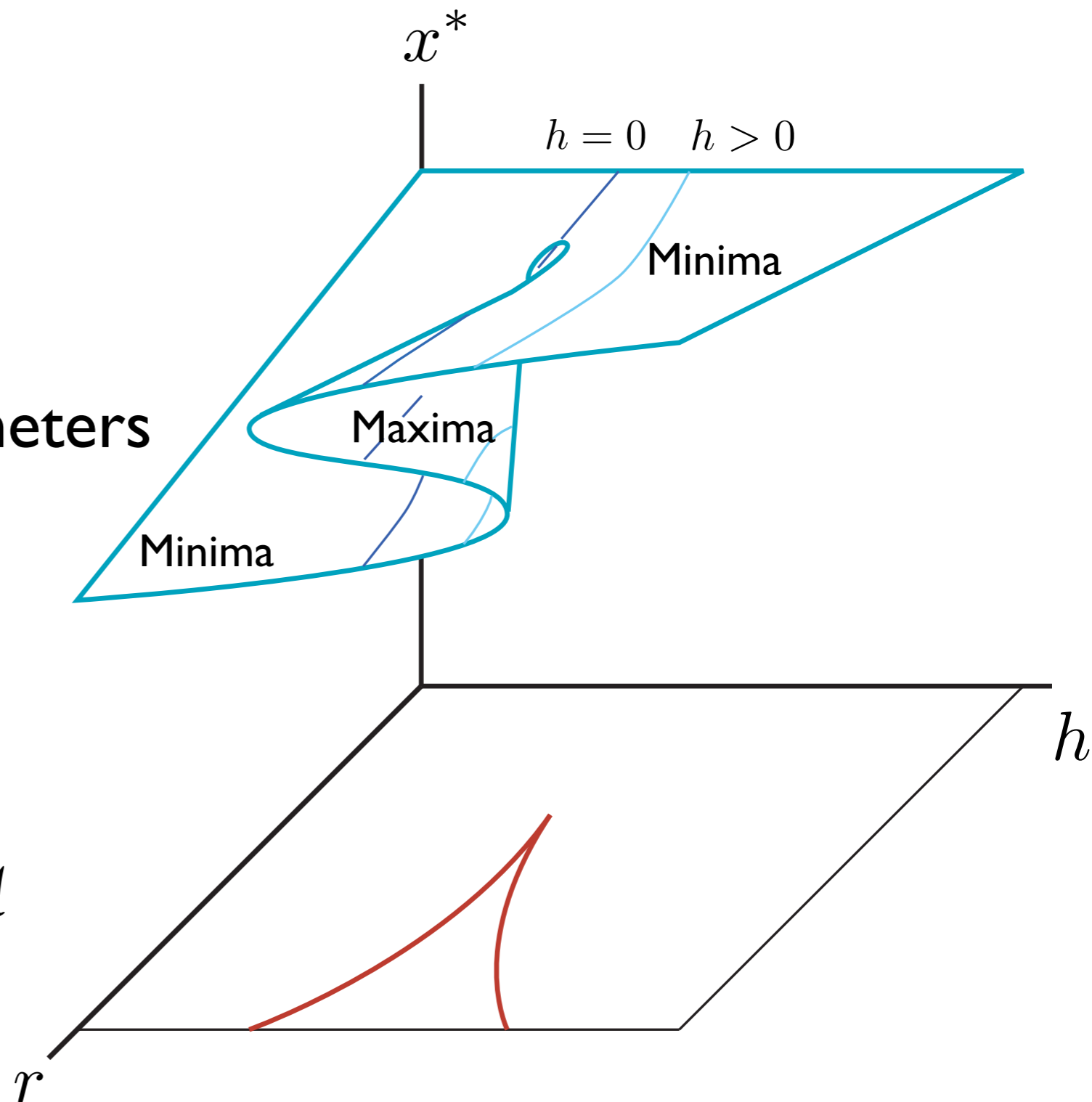
The Big, Big Picture (Bifurcations I) ...

Catastrophe Theory ...

Cusp Catastrophe ...

Behavior Surface:

fixed points $\{x^*\}$ v. parameters



Control Space: $(r, h) \in \mathcal{M}$

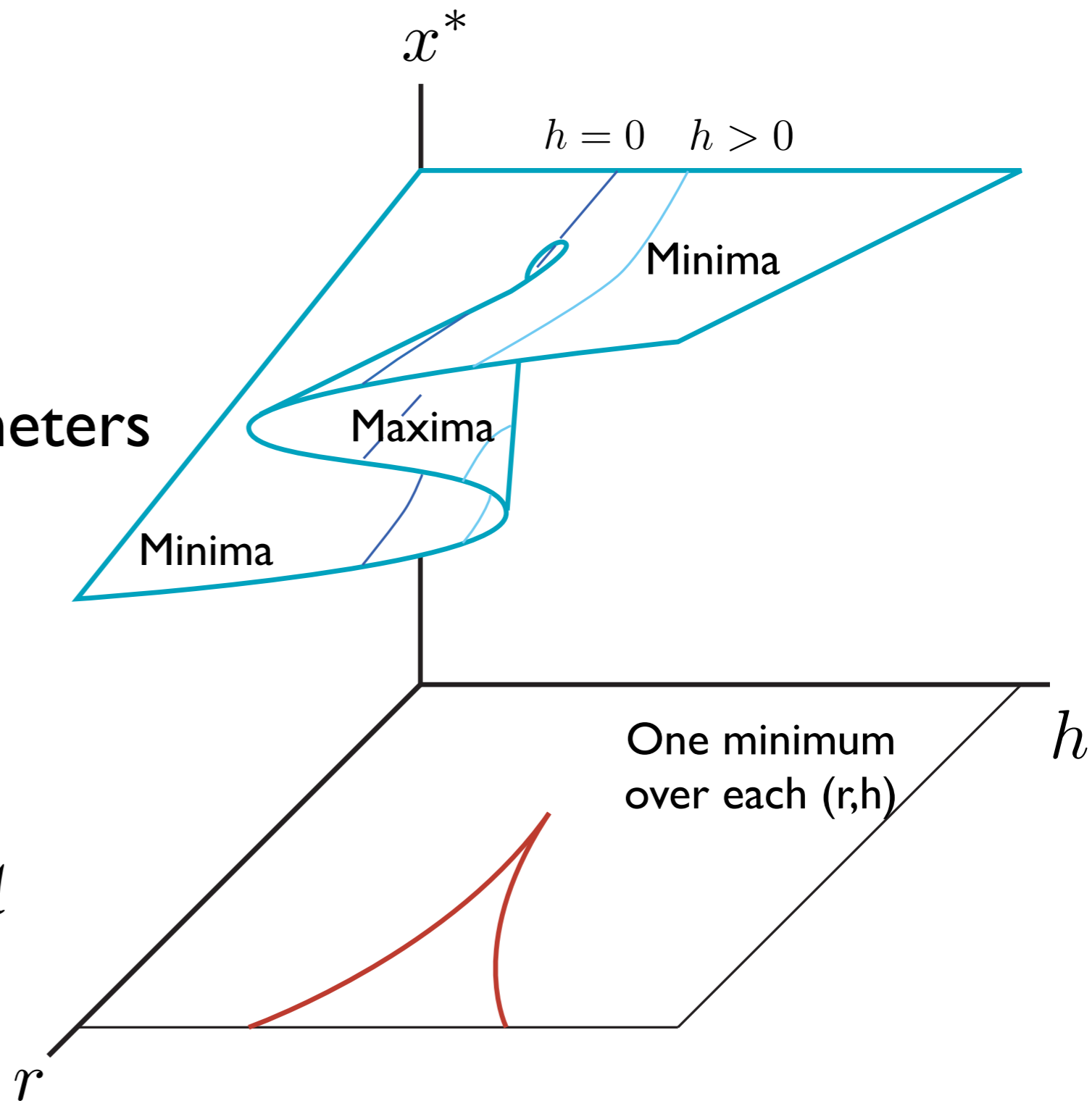
The Big, Big Picture (Bifurcations I) ...

Catastrophe Theory ...

Cusp Catastrophe ...

Behavior Surface:

fixed points $\{x^*\}$ v. parameters



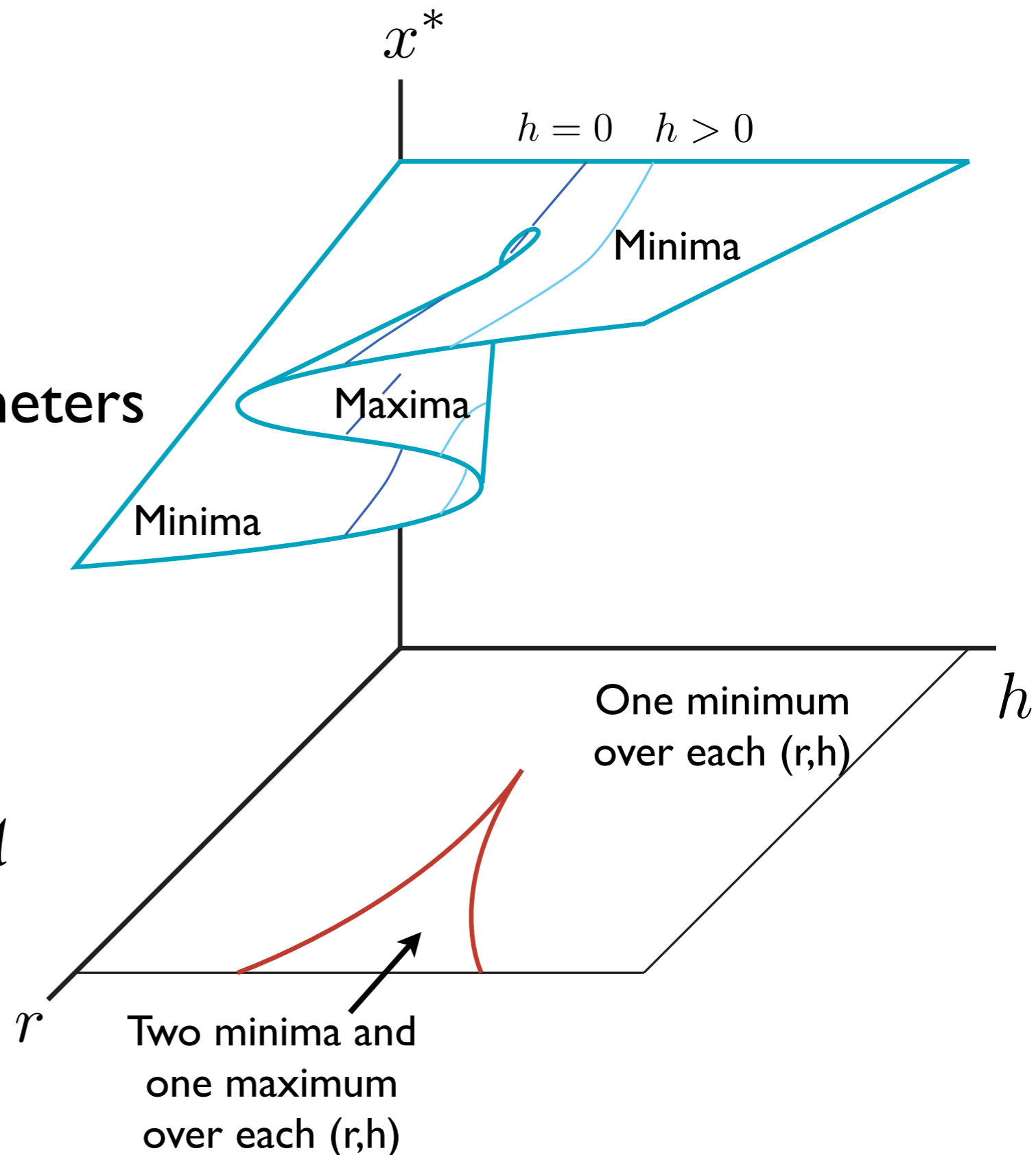
Control Space: $(r, h) \in \mathcal{M}$

The Big, Big Picture (Bifurcations I) ...

Catastrophe Theory ...
Cusp Catastrophe ...

Behavior Surface:

fixed points $\{x^*\}$ v. parameters



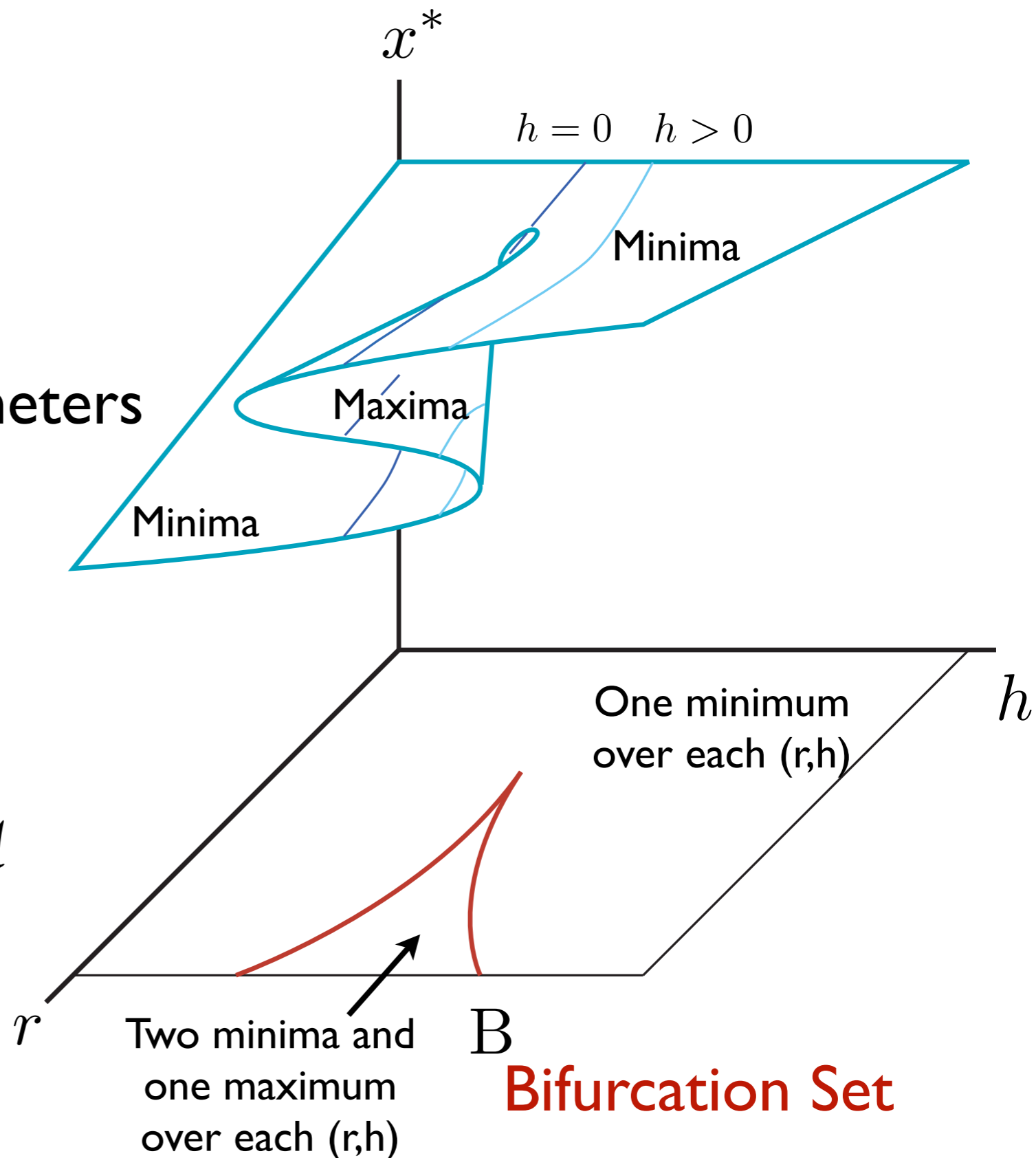
Control Space: $(r, h) \in \mathcal{M}$

The Big, Big Picture (Bifurcations I) ...

Catastrophe Theory ...
Cusp Catastrophe ...

Behavior Surface:

fixed points $\{x^*\}$ v. parameters

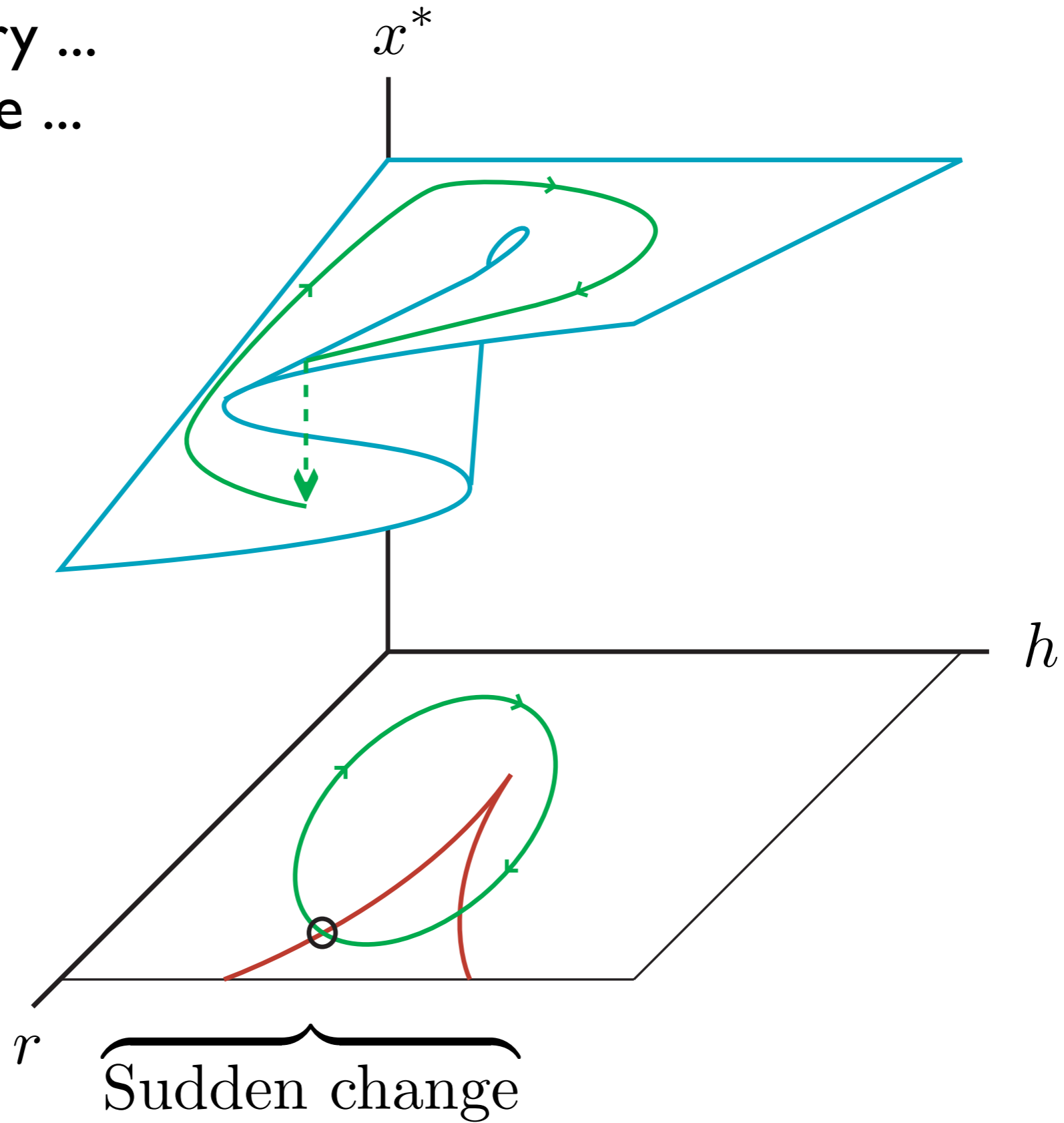


Control Space: $(r, h) \in \mathcal{M}$

The Big, Big Picture (Bifurcations I) ...

Catastrophe Theory ...

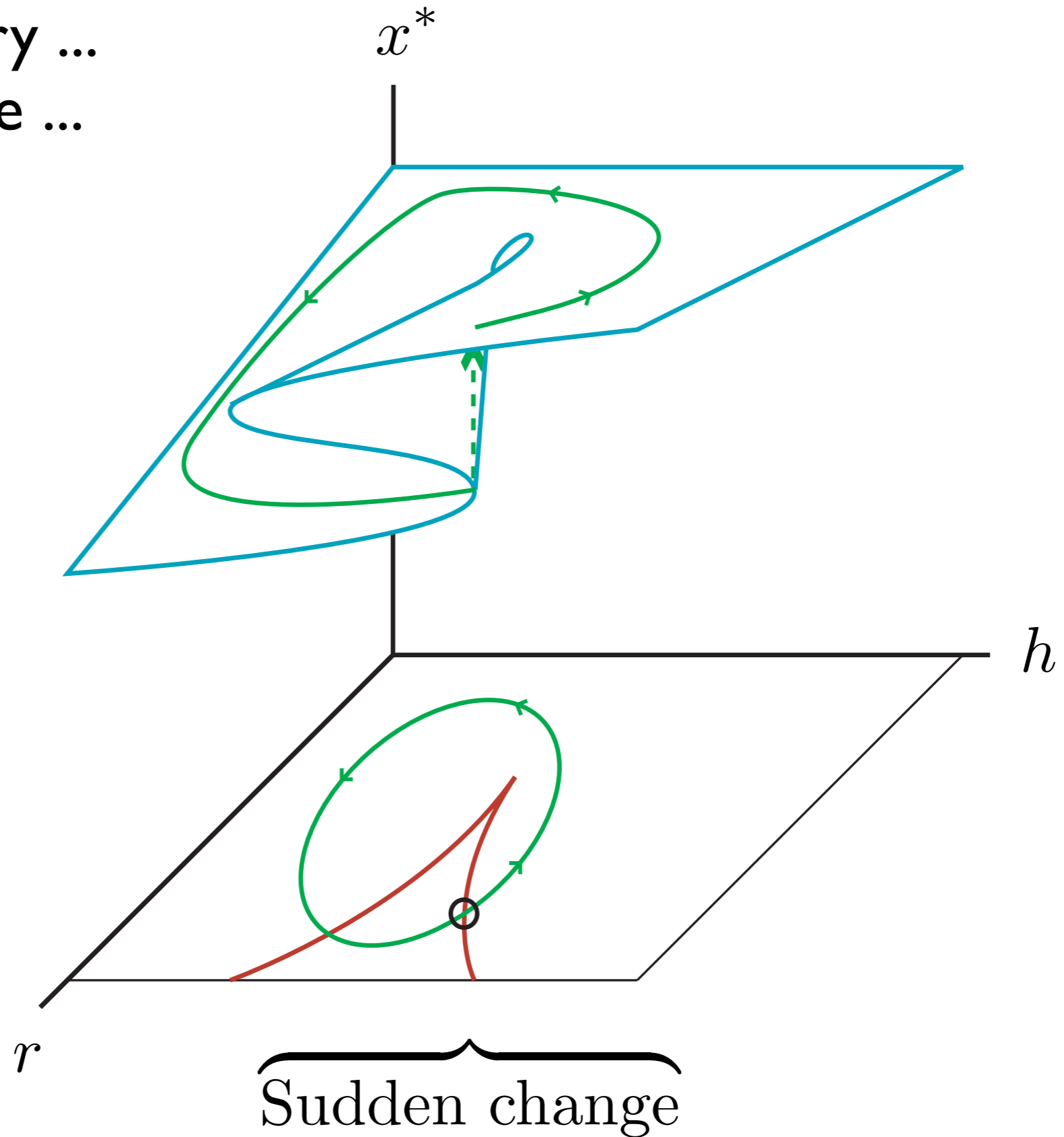
Cusp Catastrophe ...



The Big, Big Picture (Bifurcations I) ...

Catastrophe Theory ...

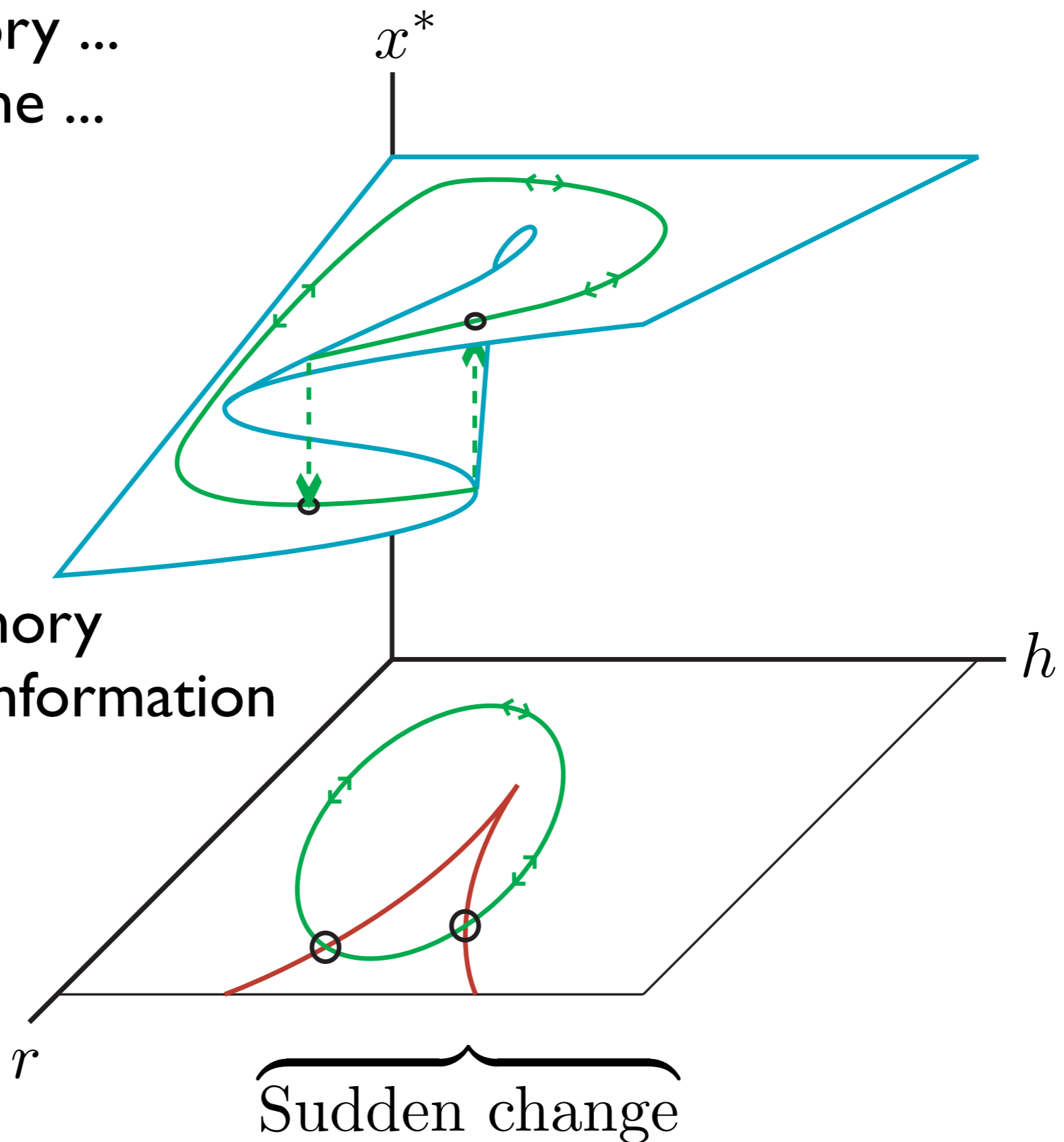
Cusp Catastrophe ...



The Big, Big Picture (Bifurcations I) ...

Catastrophe Theory ...
Cusp Catastrophe ...

Hysteresis:
system has memory
a way to store information



The Big, Big Picture (Bifurcations I) ...

Catastrophe Theory ...

Classification:

number of controls

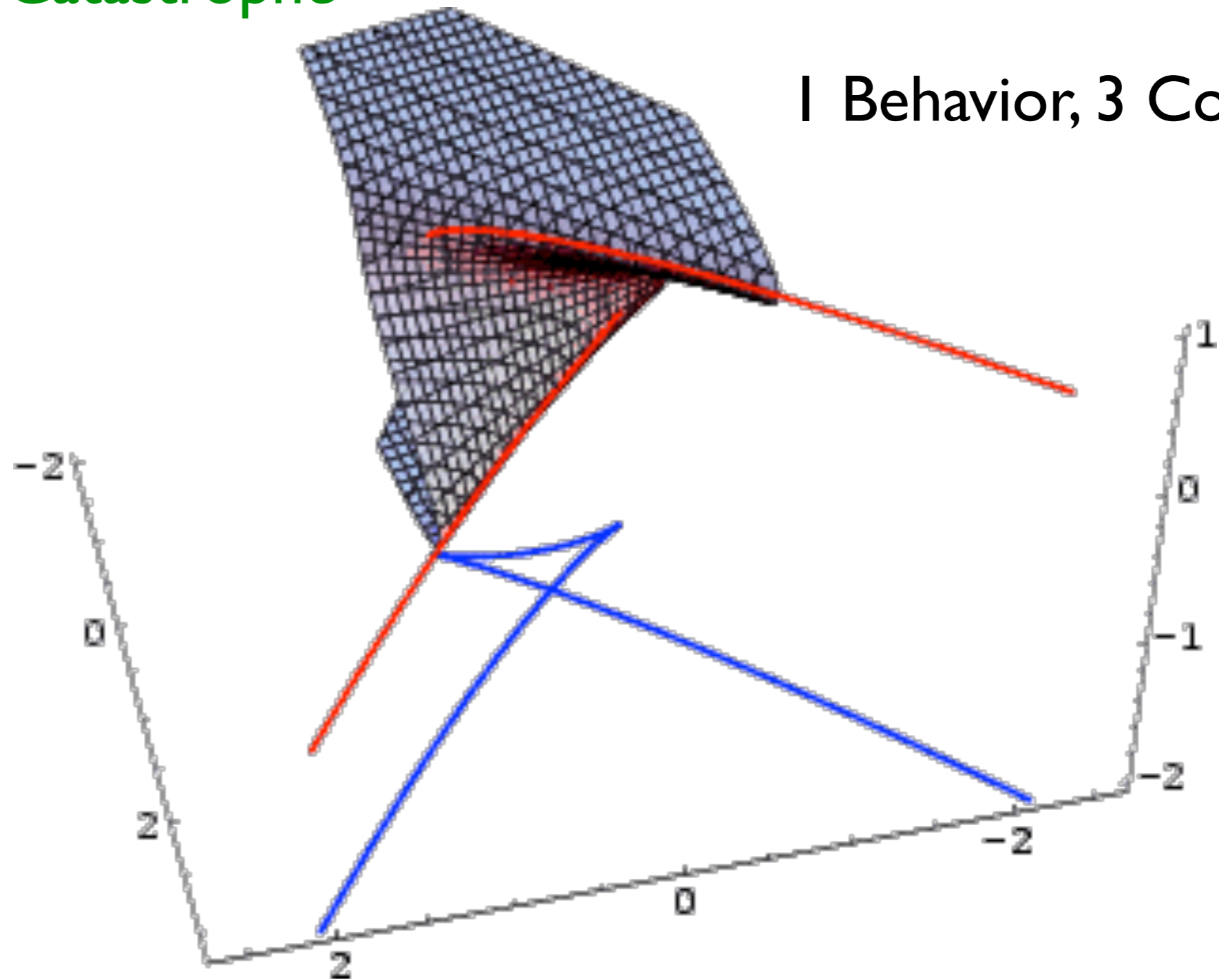
number of behavior variables

Controls	1 Behavior	2 Behaviors
1	Fold (Saddle Node)	
2	Cusp	
3	Swallowtail	Hyperbolic & Elliptic Umbilic
4	Butterfly	Parabolic Umbilic
5	?	?

The Big, Big Picture (Bifurcations I) ...

Catastrophe Theory ...

Swallowtail Catastrophe



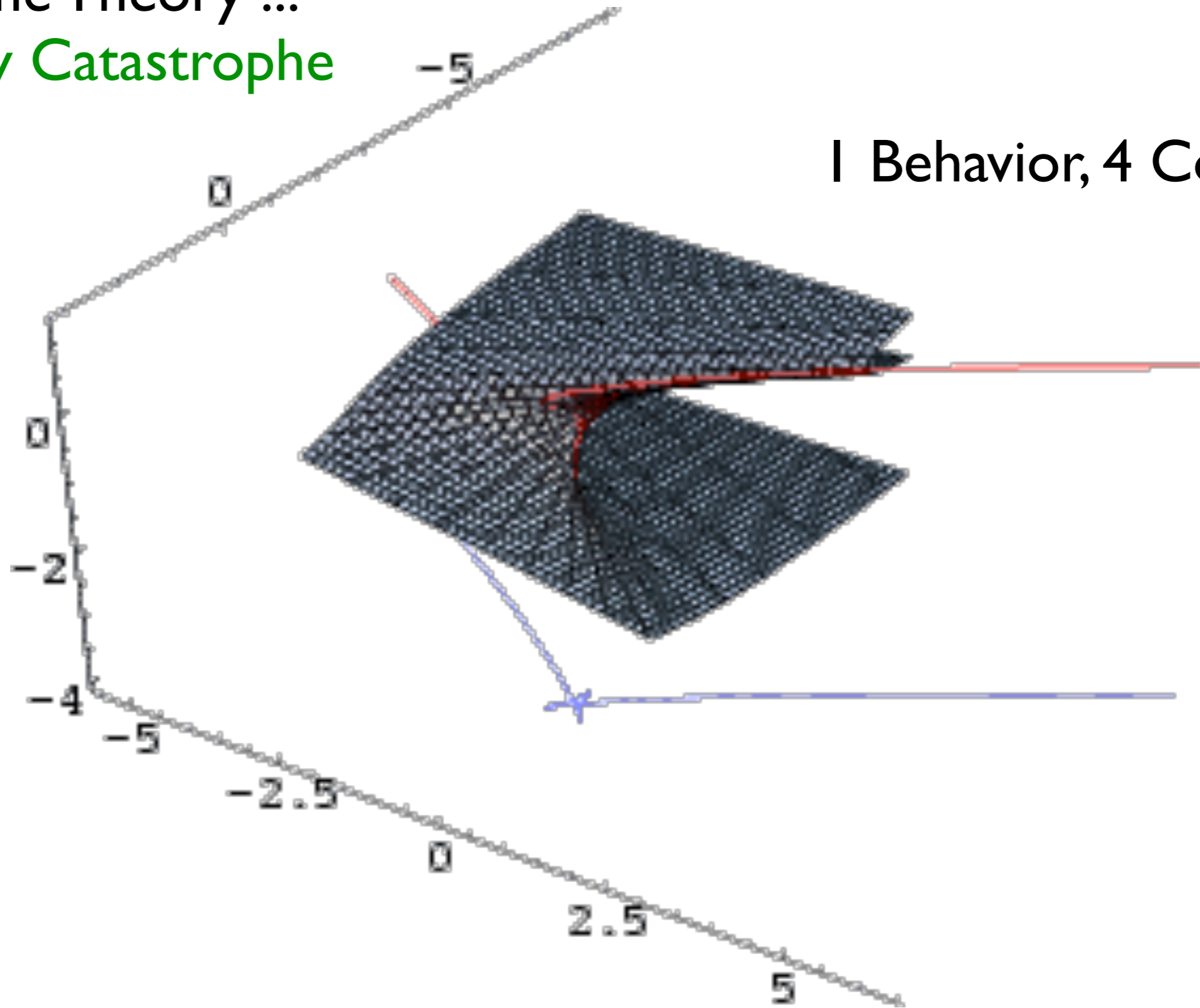
1 Behavior, 3 Controls

The Big, Big Picture (Bifurcations I) ...

Catastrophe Theory ...

Butterfly Catastrophe

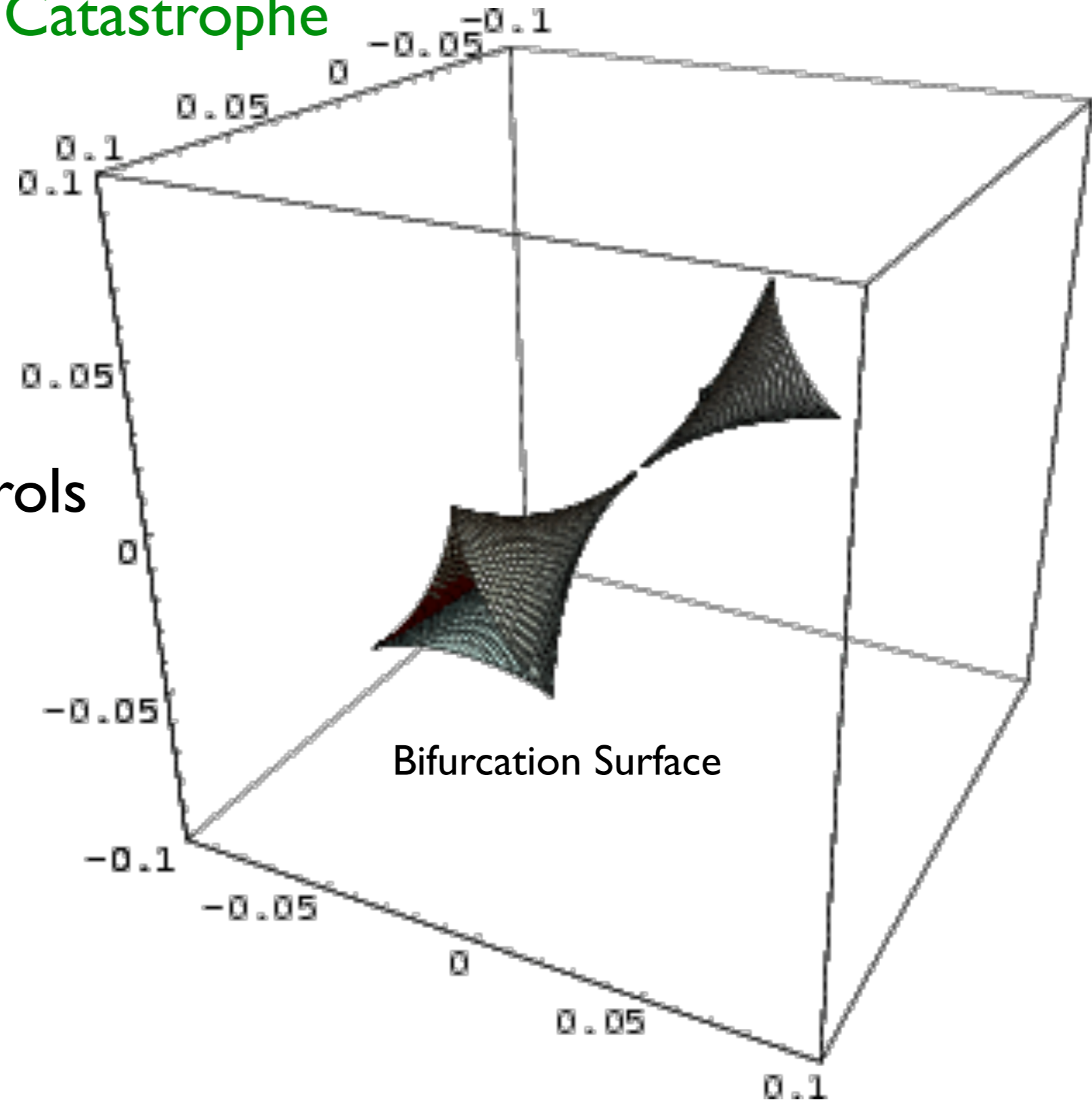
I Behavior, 4 Controls



The Big, Big Picture (Bifurcations I) ...

Catastrophe Theory ...

Elliptic Umbilic Catastrophe



2 Behavior, 3 Controls

The Big, Big Picture (Bifurcations I) ...

Reading for next lecture:

NDAC, Chapter 8 and Sec. 10.0-10.4.